








# Modular Procedural Automation

Yokogawa Users Group  
October 2012

## Modular Procedural Automation (MPA)

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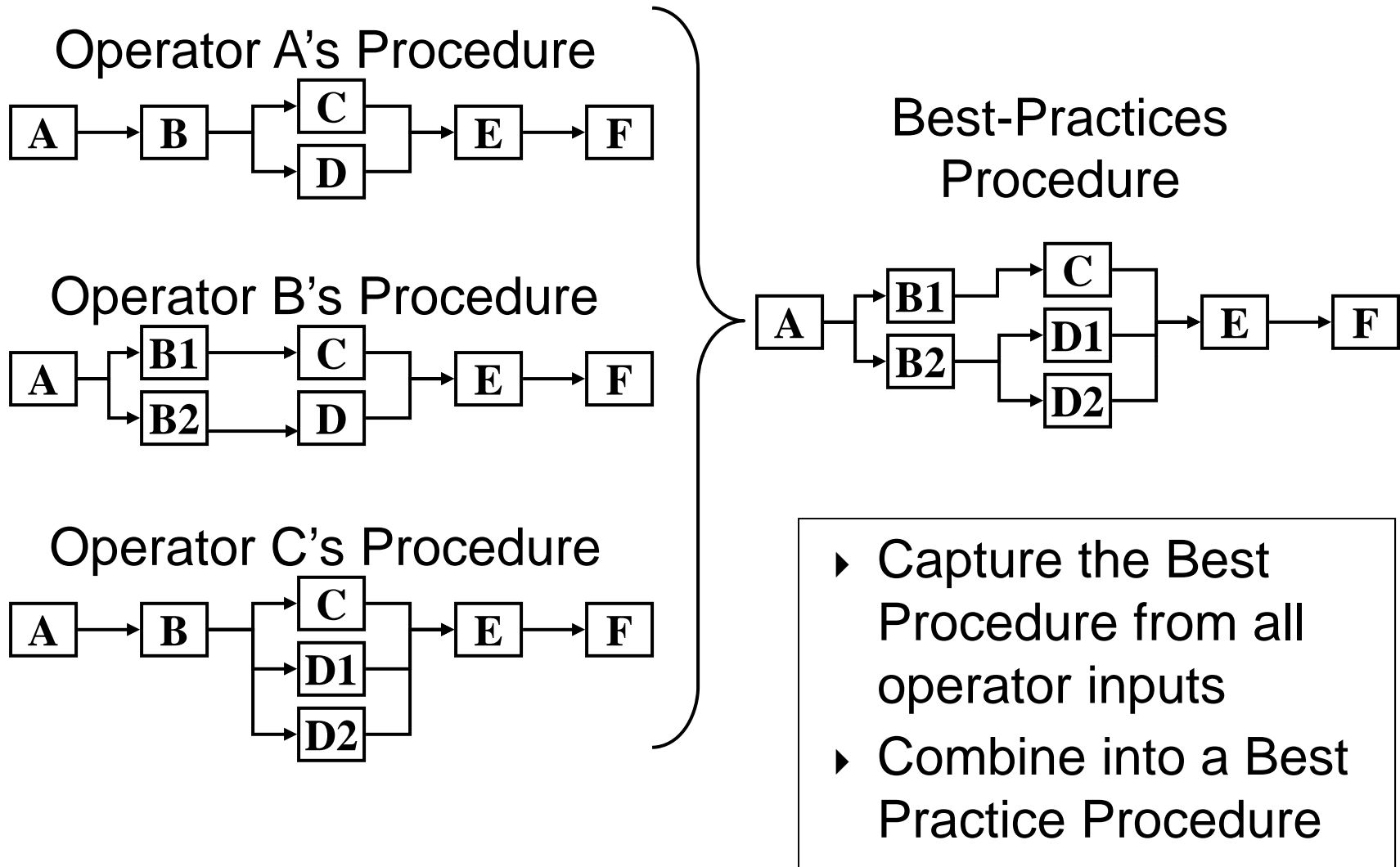
-  What is MPA?
-  Consulting Methodology
-  How to select the right tool for the job
-  ExaPilot examples
-  Centum VP examples

# What is MPA?

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- “Modular Procedural Automation” (MPA) - Yokogawa’s capability and expertise in providing automated procedures, in accordance with ISA106.
  - A consultative approach by process experts who understand process operations and provide recommendations to automate and improve procedures.
  - Proven methodology that captures, documents and implements procedural knowledge gathered from operational staff
  - It is modular- standardize implementation to increase flexibility, reduce implementation costs, and promote repeatability and reuse.
  - MPA integrates with any existing control system

# Capturing Procedural Best Practices

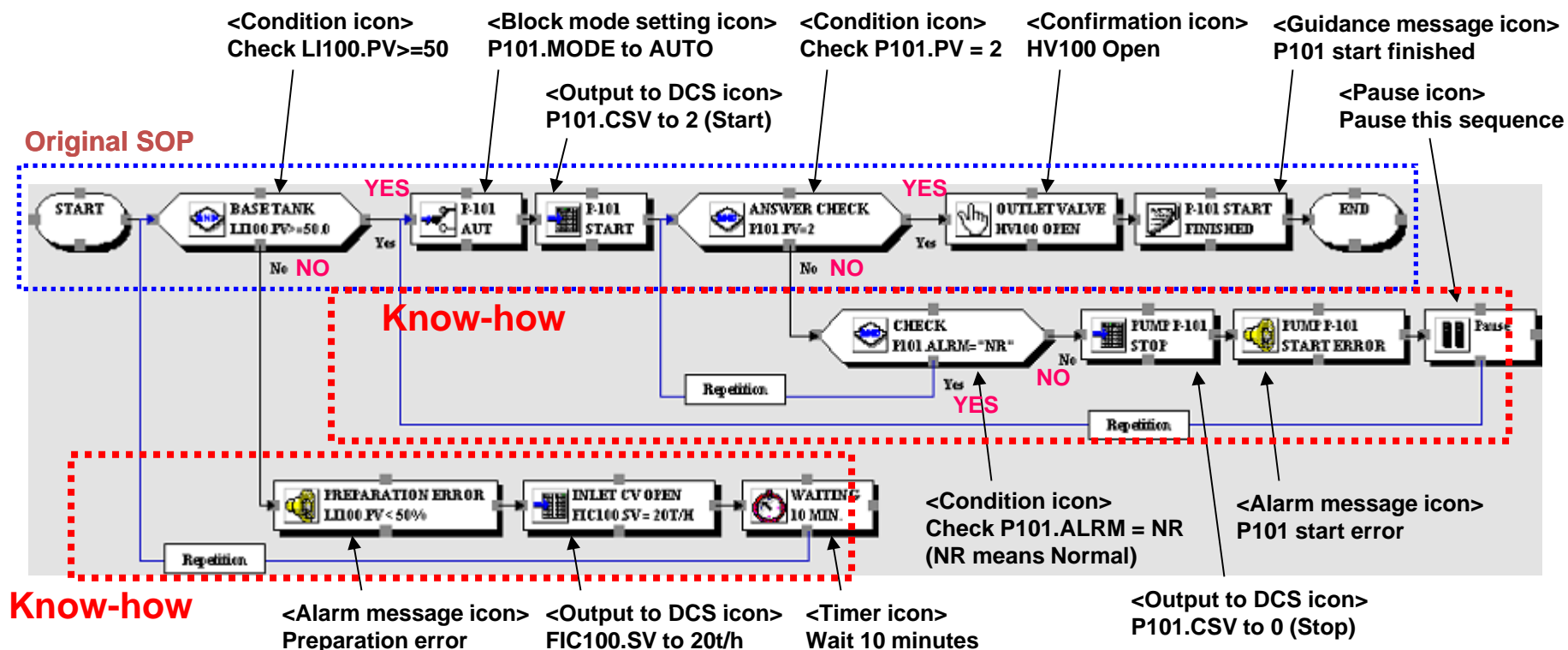


# Capturing Procedural Best Practices

## Original SOP (Standard Operating Procedure)

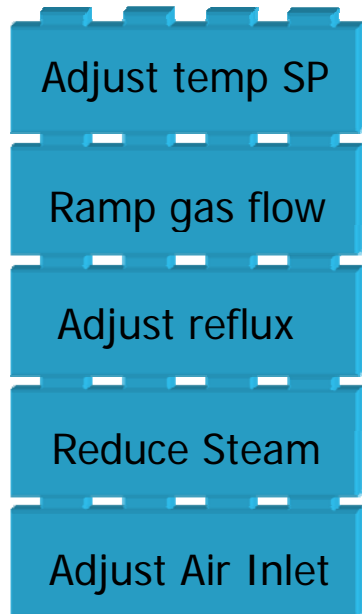
- (1) Check base tank level LI100.PV  $\geq 50\%$
- (2) Start pump P-101
- (3) Check pump status feedback
- (4) Confirm field operator to open hand valve HV100

**Capture Operator Knowledge!**

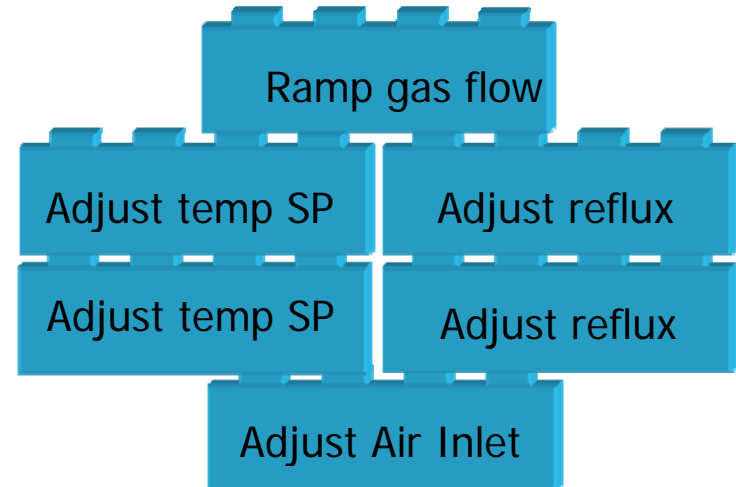


## Procedural control- Modularization of code

- Transition from Product mix A to Product mix B



- Transition from Product mix B to Product mix C



# Consulting Site Visit

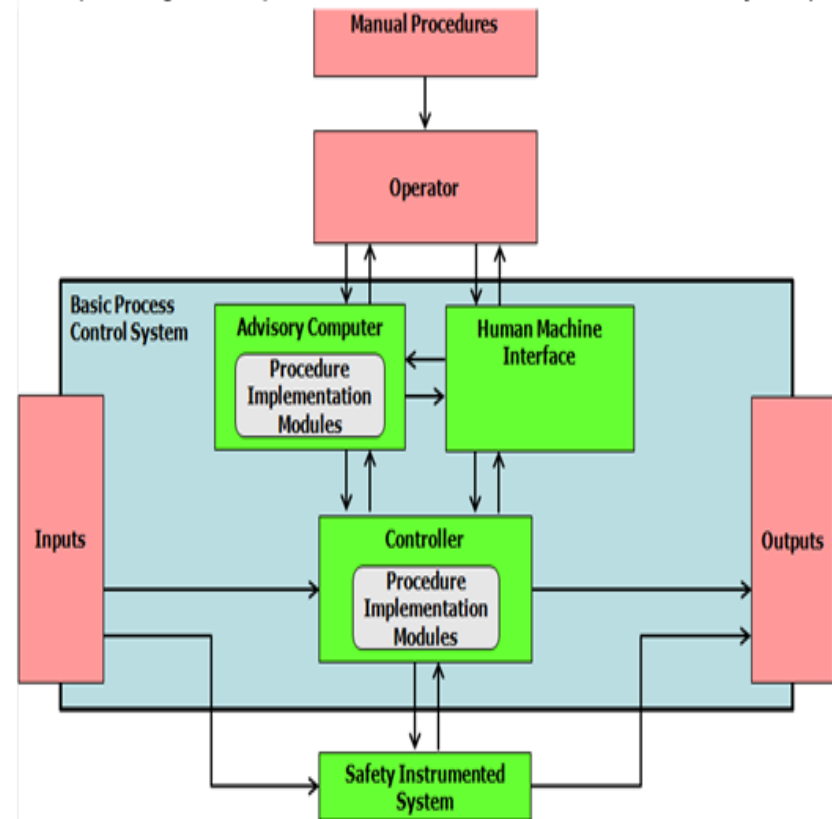
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- ⇒ Look for opportunities for improvement (major “pain” points)
- ⇒ Methodologies and templates for:
  - Site visit pre-work
  - Plant walkthrough
  - Interview checklists with
    - Management
    - Operations
    - Other functions
  - Initial review meeting/ on-site report
- ⇒ Assist in ROI calculations
- ⇒ Prioritize and recommend best solutions

# Tool Selection

- What determines if the MPA application should be implemented in the controller?
  - Fault tolerance (high reliability required?)
  - Safety/environmental risks
  - Execution speed requirements
  - Level of automation available
  - Procedure implementation and lifecycle cost
  - Operating philosophy
  - Incremental implementation/modification of procedures

Conceptual Diagram of Implementation Modules in a Basic Process Control System (BPCS)



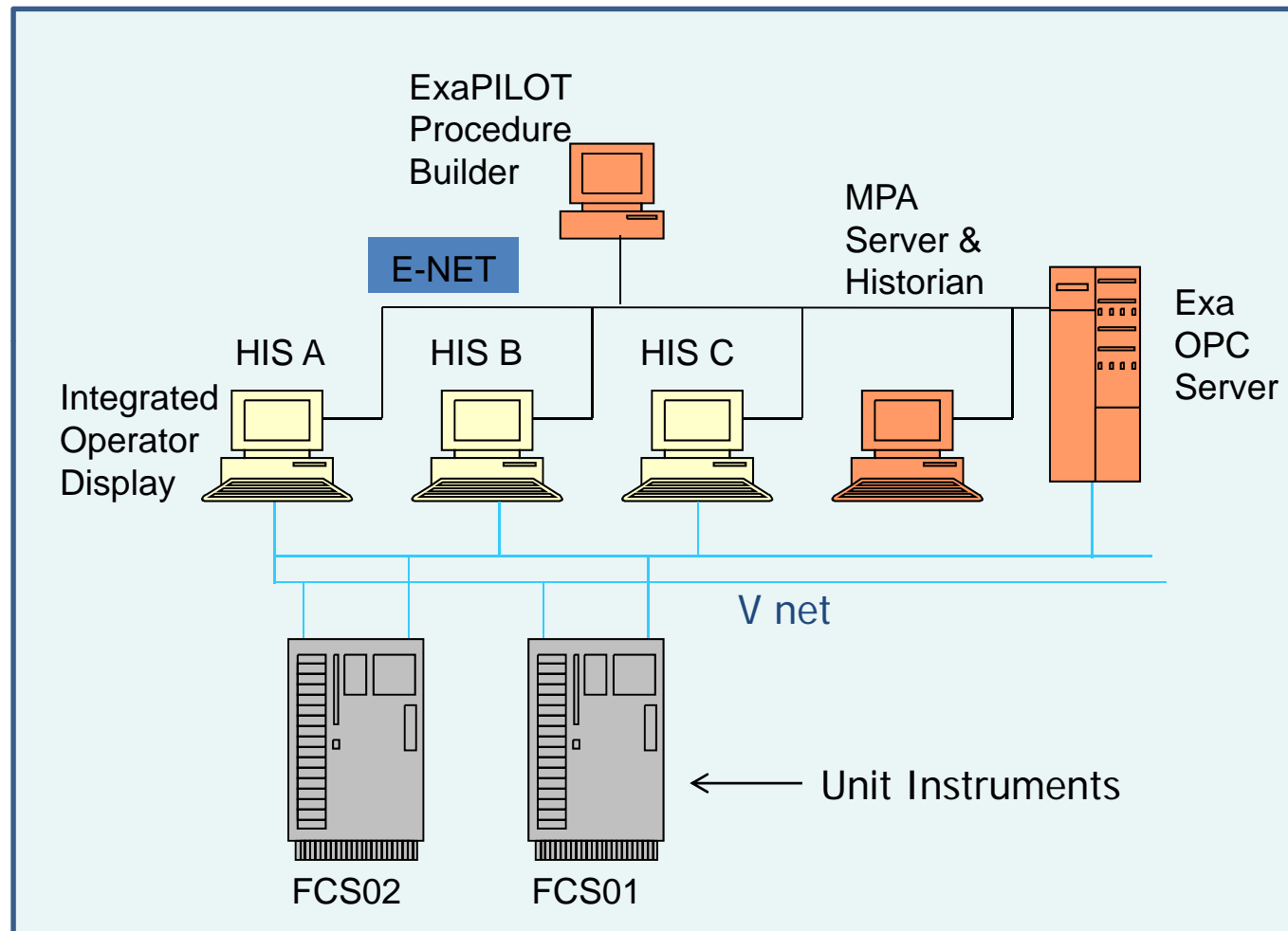


# Yokogawa MPA Tools

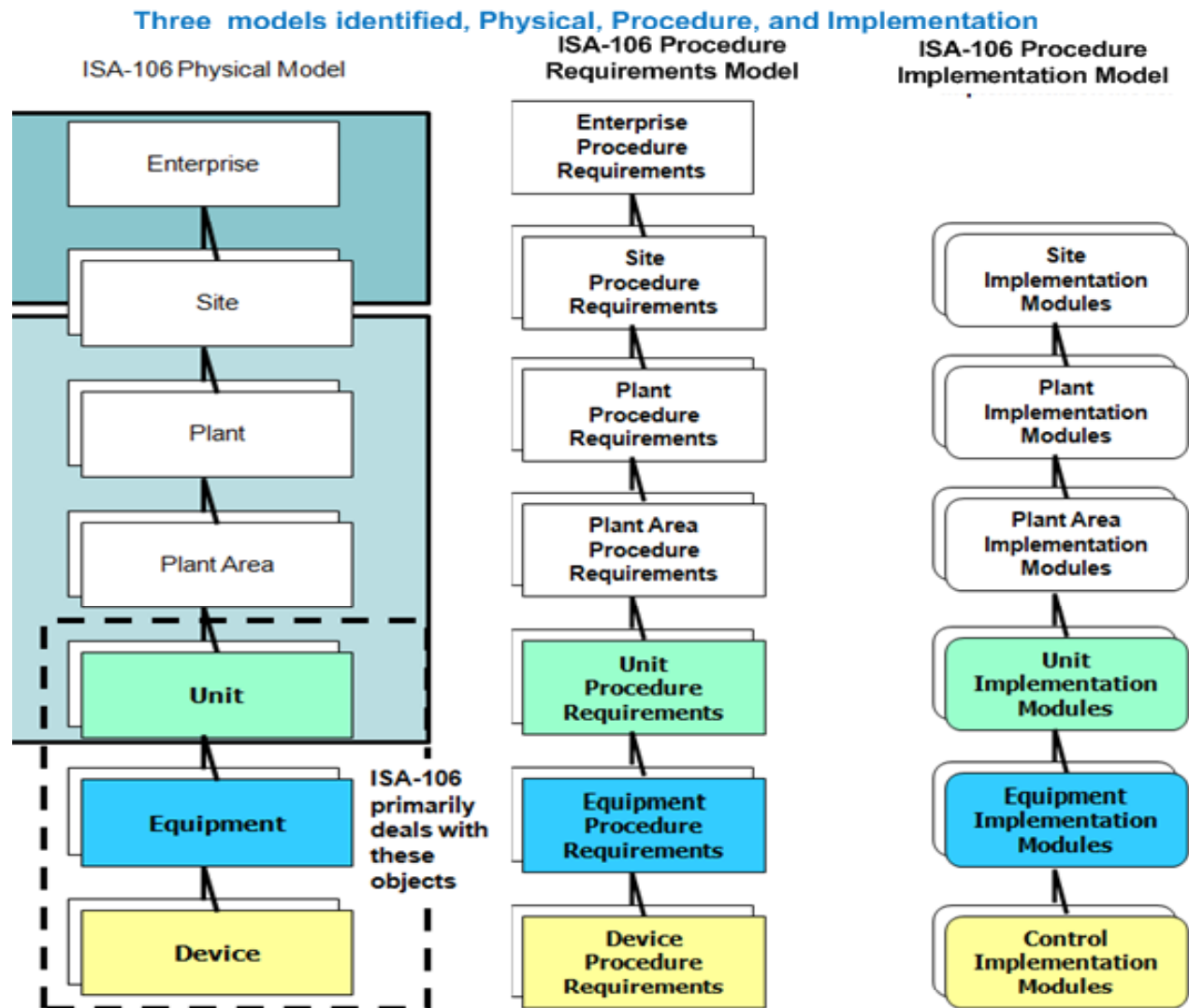
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- Unit Instrument Function Block
  - Within the redundant FCS Controller
  - Based on ISA88 structure (SFC)
  - Supports state-based control
  - Allows the use of modular generic sequences/tags/code
  - Generates operator messages/confirmations/data entry
- Exapilot
  - Within the Advisory Computer
  - User-friendly flowcharting
  - Allows for modular sub-procedures
  - Capable of manipulating instruments
  - Generates operator messages/confirmations/data entry
  - Works with any control system (OPC)

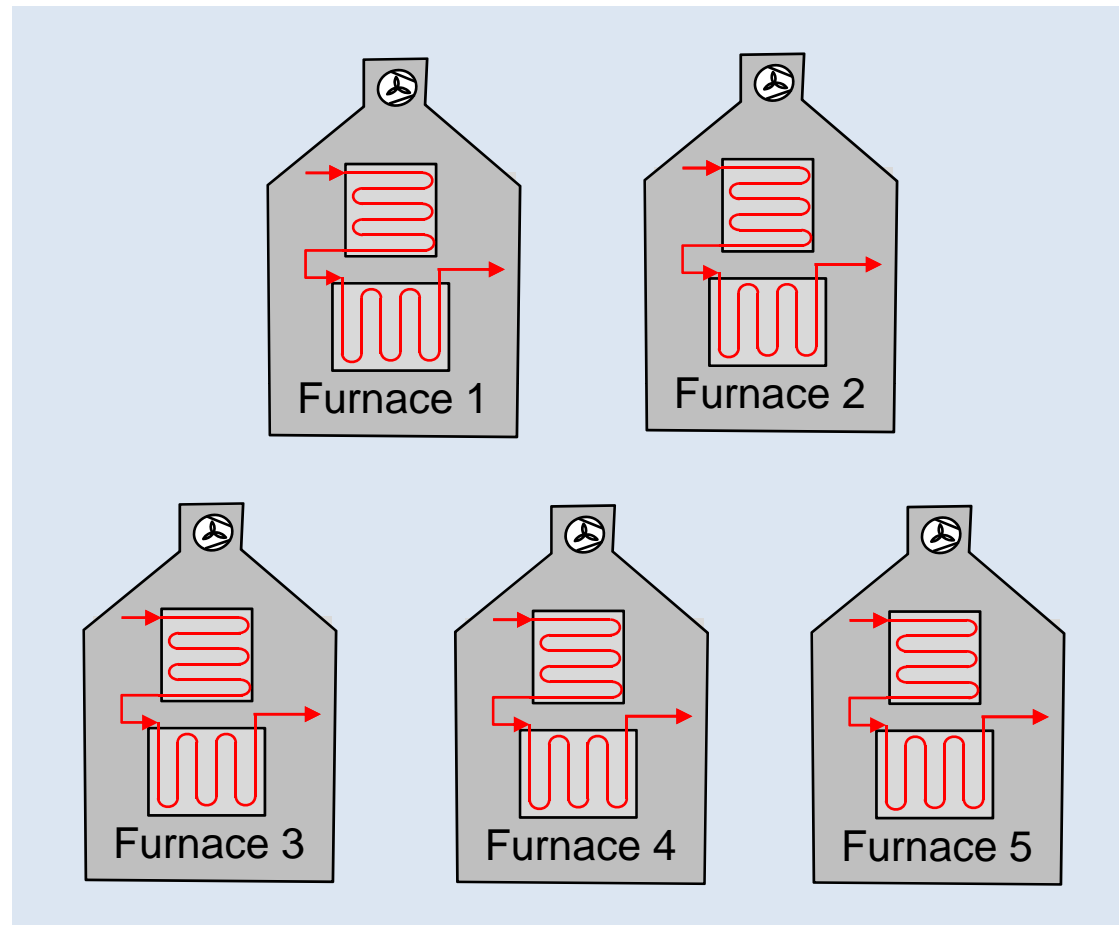
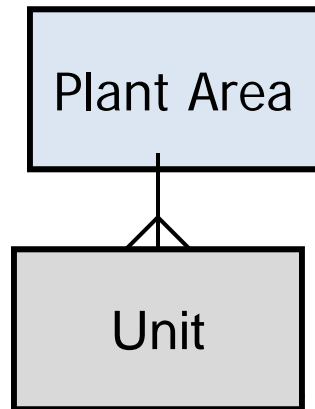
## Basic MPA Architecture



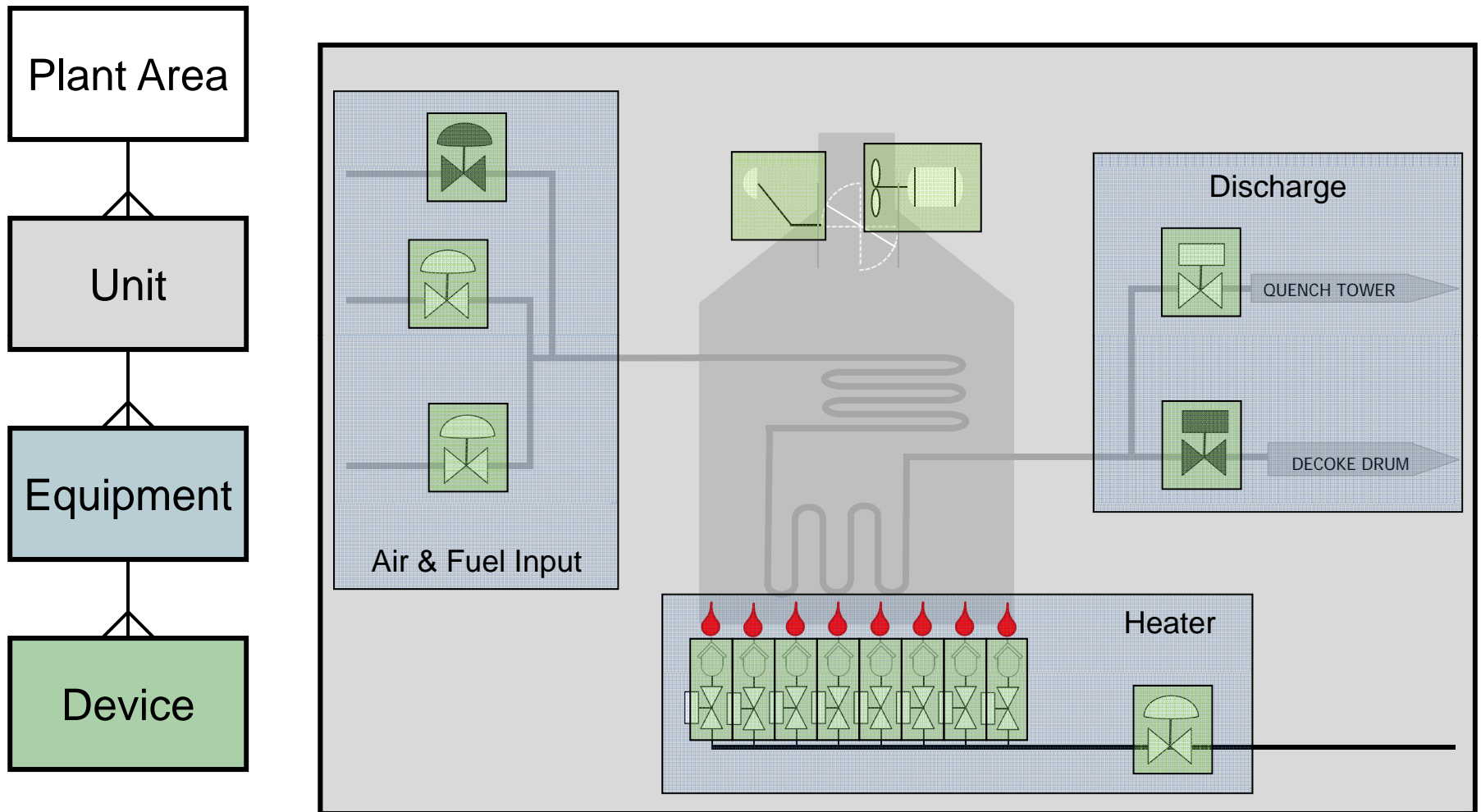
# Design Components



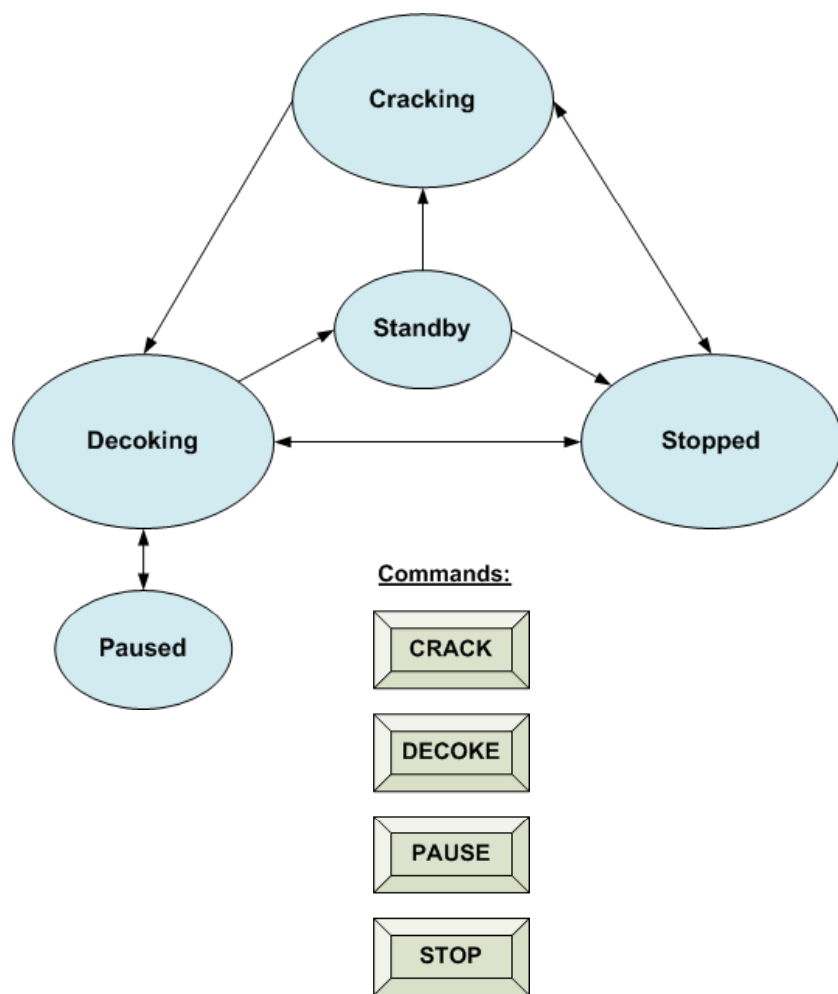
## ➤ Ethylene Furnace Example



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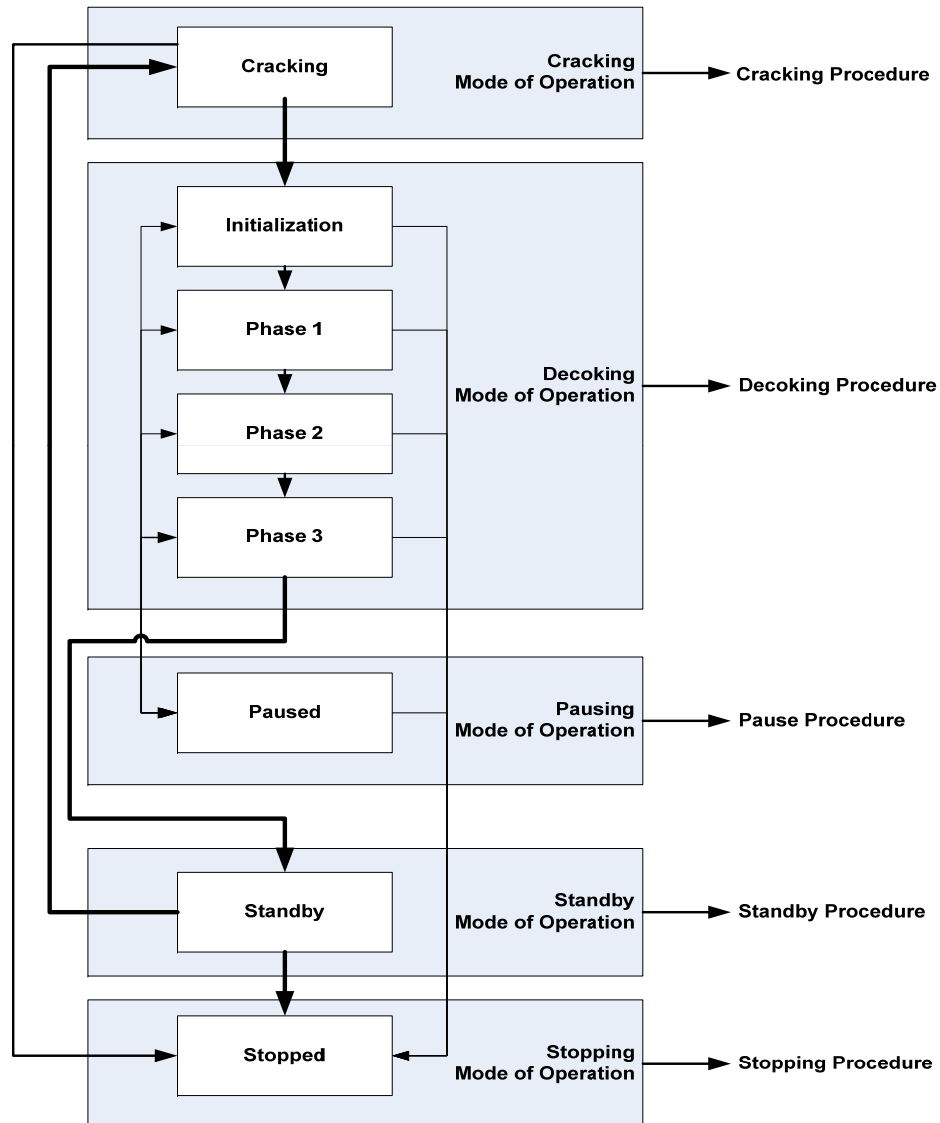


# → State Transition Diagram

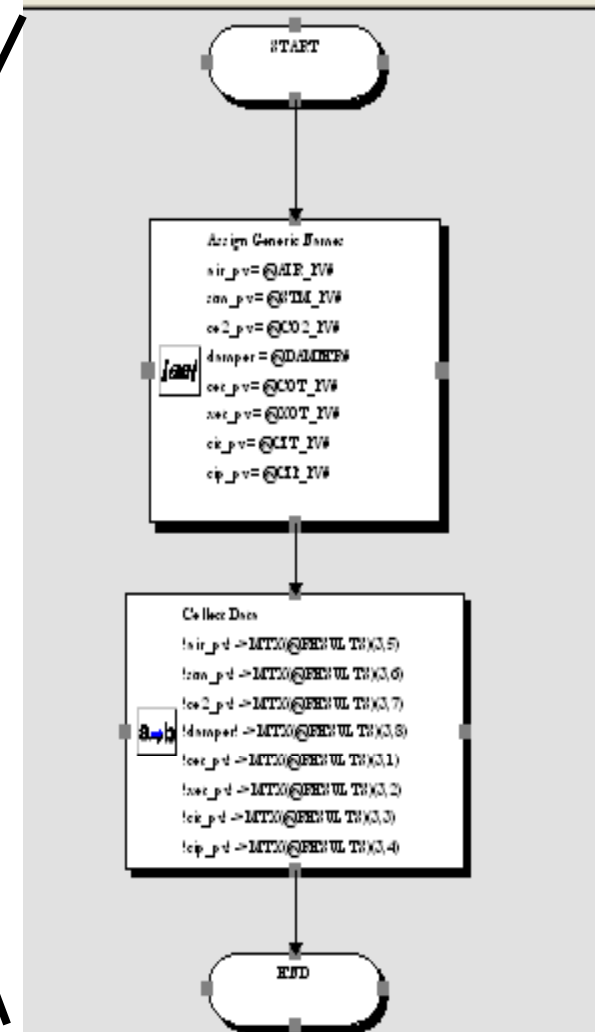
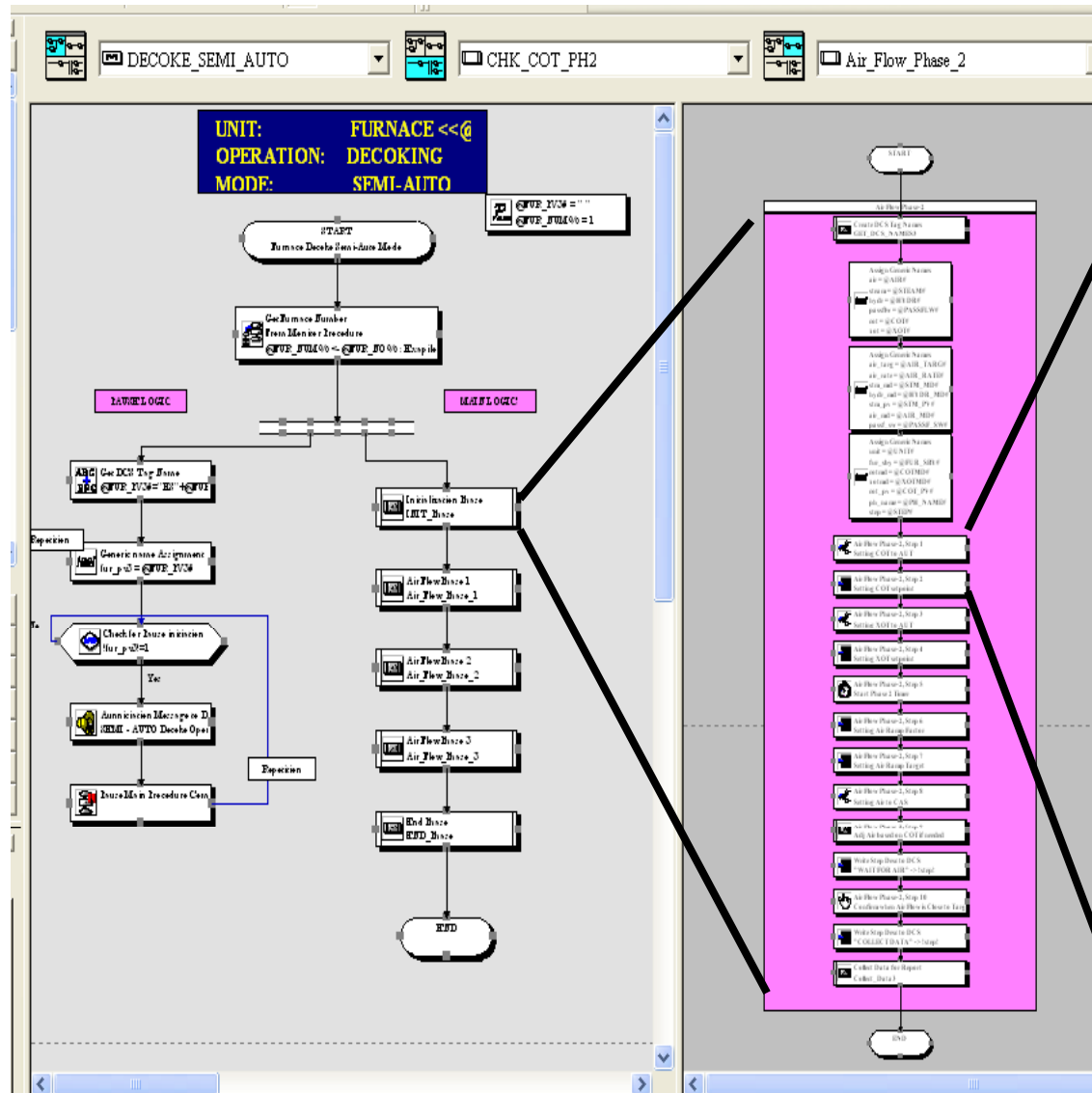


State	Available Commands	Operator-Initiated?	Description
Cracking	Decoke Stop	Yes Yes	The furnace is in full production. Coking deposits are being monitored.
Decoking	Standby Pause Stop	No No/Yes Yes	Coking deposits are being removed from the coils. At the end of process, the status is automatically changed to Standby. If an abnormal condition occurs, the status is automatically changed to Pause.
Stopped	Crack Decoke	Yes Yes	Furnace is taken out of service for maintenance. Cracking or Decoking can be selected by the operator.
Standby	Crack Stop	Yes Yes	Furnace is ready to be transitioned into Cracking from Decoking.
Paused	Decoke	Yes	Operator can pause the Decoking at any time and resume it.

# ➡ Map Procedures to States

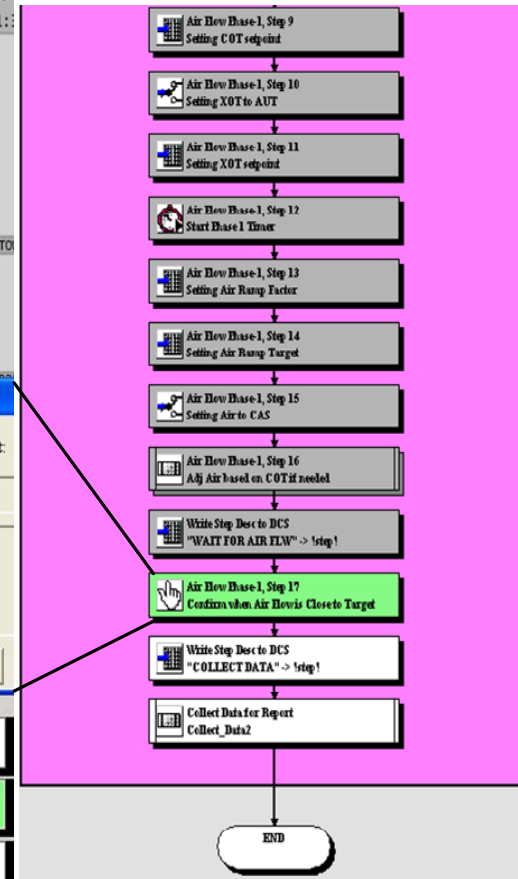
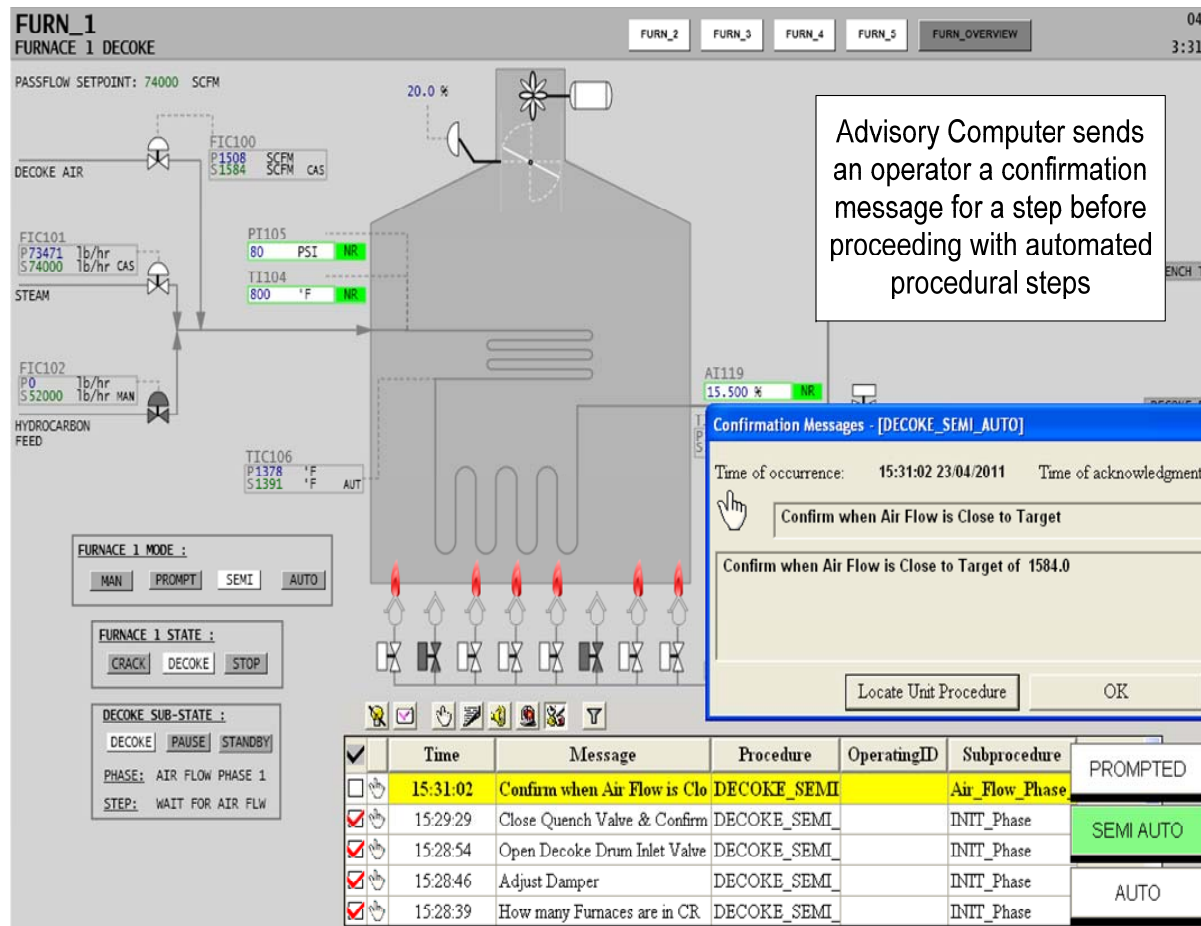


# Exapilot MPA Example

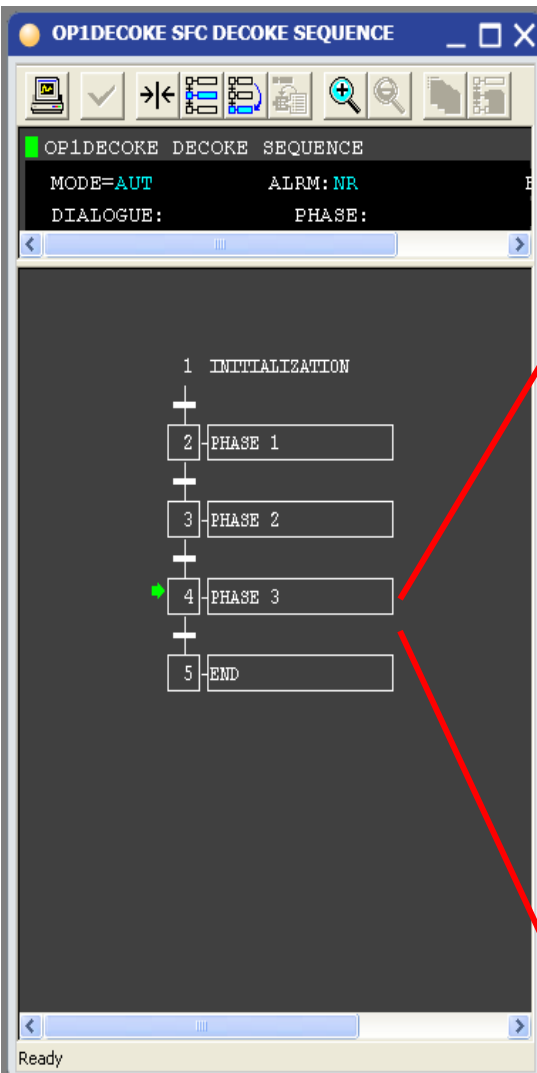




# Exapilot – Interface with Graphics

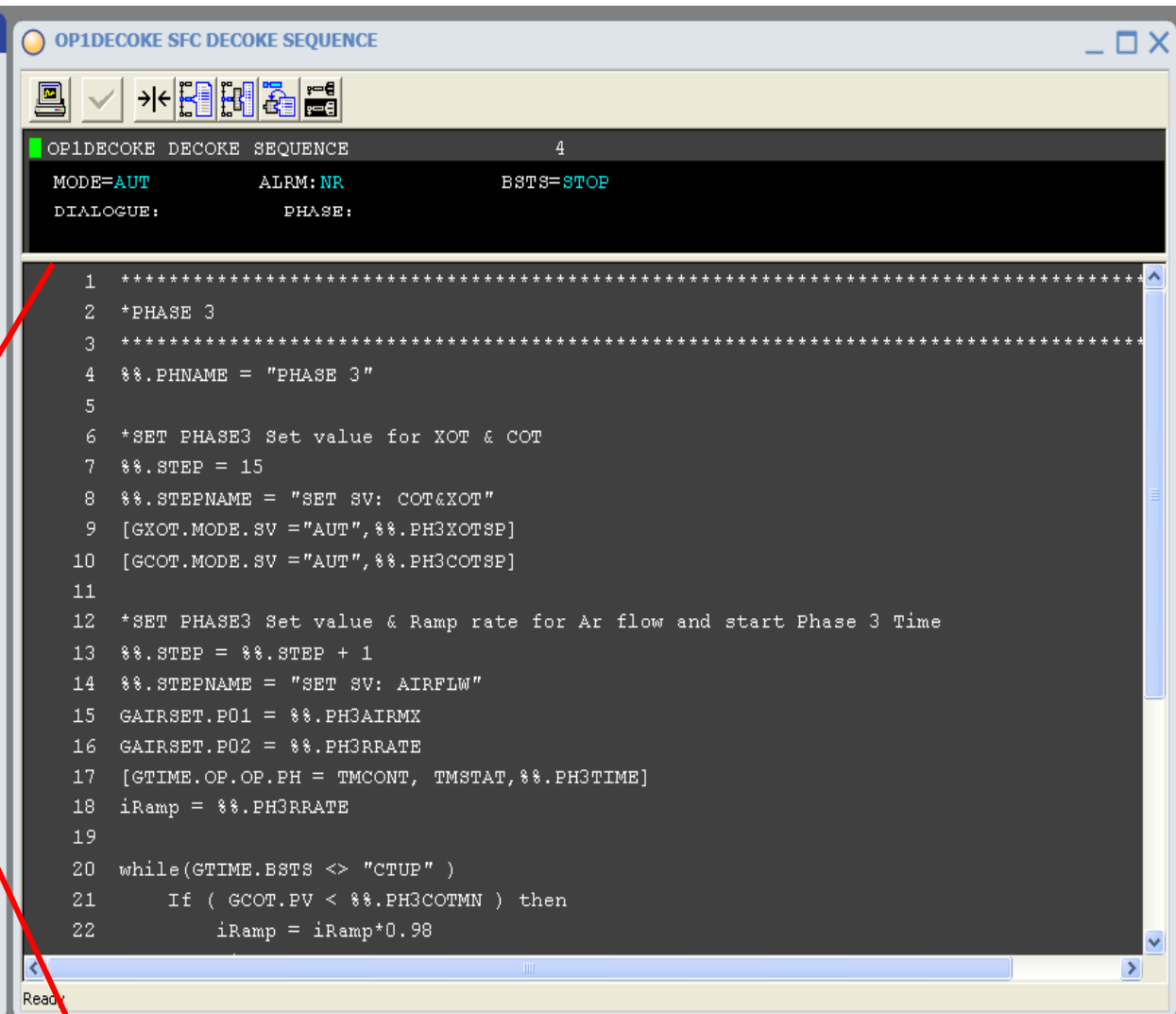


# Centum Unit Instrument Example



```

1 INITIALIZATION
|
2 PHASE 1
|
3 PHASE 2
|
4 PHASE 3
|
5 END
    
```

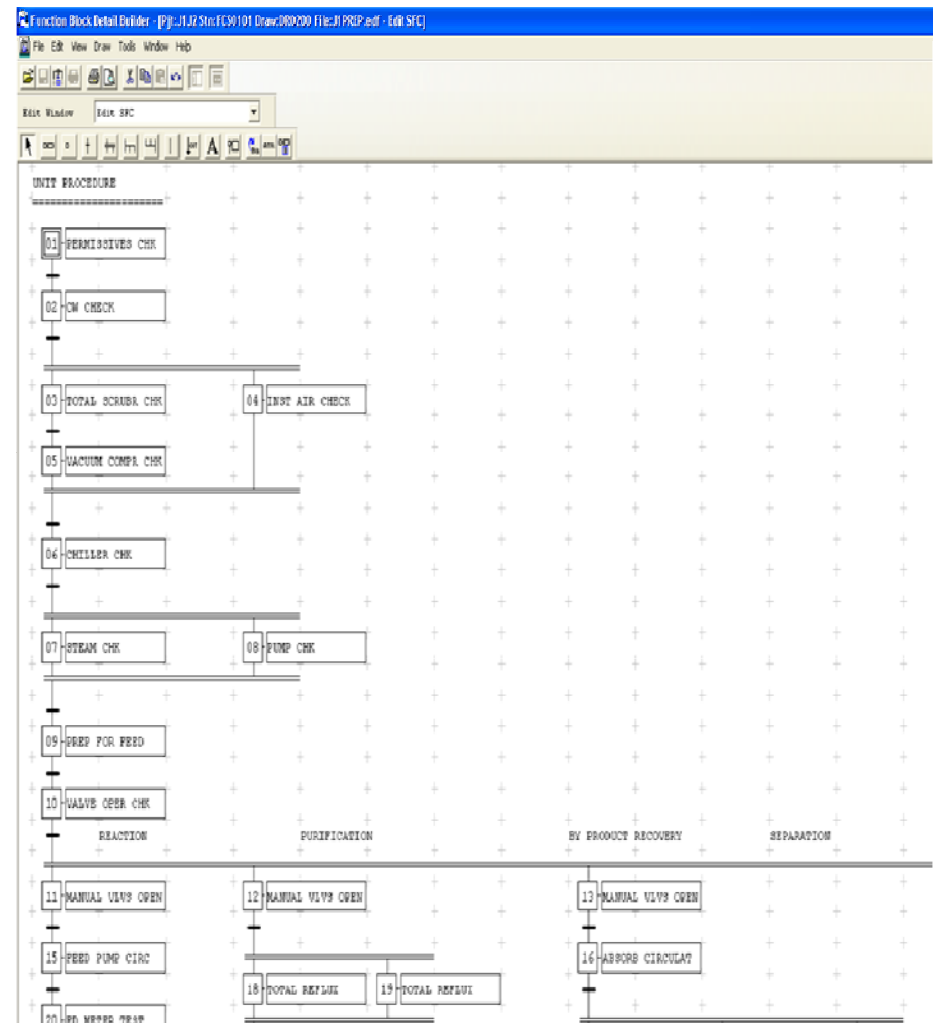


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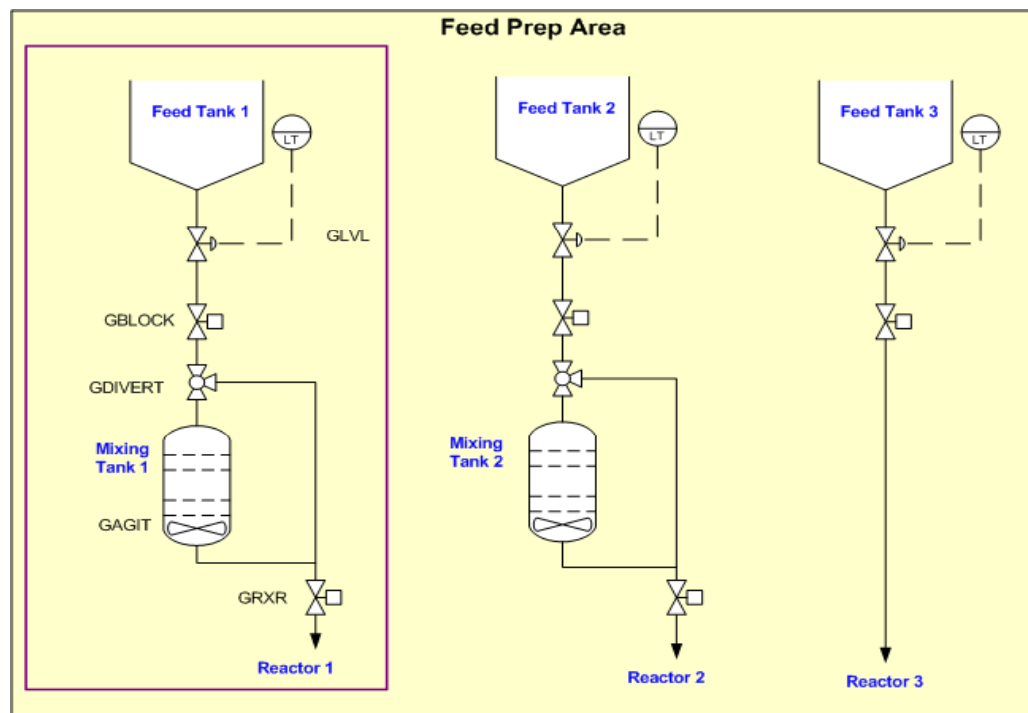
1 *****
2 *PHASE 3
3 *****
4 %%.PHNAME = "PHASE 3"
5
6 *SET PHASE3 Set value for XOT & COT
7 %%.STEP = 15
8 %%.STEPNAME = "SET SV: COT&XOT"
9 [GXOT.MODE.SV ="AUT",%%.PH3XOTSP]
10 [GCOT.MODE.SV ="AUT",%%.PH3COTSP]
11
12 *SET PHASE3 Set value & Ramp rate for Ar flow and start Phase 3 Time
13 %%.STEP = %%.STEP + 1
14 %%.STEPNAME = "SET SV: AIRFLW"
15 GAIRSET.P01 = %%.PH3AIRMX
16 GAIRSET.P02 = %%.PH3RRATE
17 [GTIME.OP.OP.PH = TMCNT, TMSTAT,%%.PH3TIME]
18 iRamp = %%.PH3RRATE
19
20 while(GTIME.BSTS <> "CTUP" )
21     If ( GCOT.PV < %%.PH3COTMN ) then
22         iRamp = iRamp*0.98
    
```

# Example of Unit-based Procedure:

- Preparation for Startup of Train XYZ
  - Utilities Check (check of utilities valves, instrumentation, etc.)
  - Reaction Process (start of circulation, heating, flow check, etc.)
  - Purification Process (manual valves open check, etc.)
  - By-product Recovery Process (temperature checks, etc.)
  - Separation Process (scrubber circulation, pH check, etc.)
- Possible States of the Train XYZ
  - WAIT
  - READY FOR START
  - START-UP
  - RUNNING
  - STOP

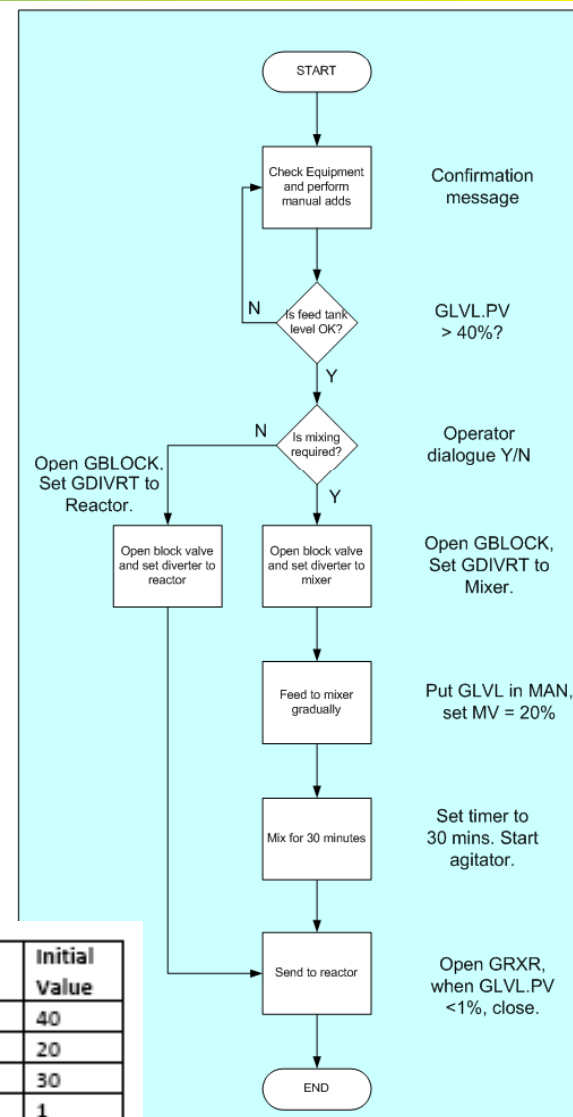


# Unit Instruments – Generic Functions



Generic Tag	Feed1	Feed2	Feed3
GLVL	LC-101	LC-201	LC-301
GBLOCK	SV-102	SV-202	SV-302
GDIVERT	SV-103	SV-203	SV-303
GAGIT	HC-104	HC-204	*
GRXR	SV-105	SV-205	*

Parameter Item	Type	Format	Low Limit	Hi Limit	Eng Units	Initial Value
MINLVL	Float	4.1	10	90	%	40
LVLSP	Float	4.1	20	50	%	20
MIXTM	Integer	3	10	60	MIN	30
MTLVL	Float	4.1	0	5	%	1



PARAMETERS/  
DATA ITEMS

MINLVL

LVLSP

MIXTM

MTLVL

## MPA - Where to Start?

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- Look for opportunities – Any time one needs to move from one state to another that requires a discrete set of activities
  - Startups / Shutdowns
  - Crude Switches
  - Grade Changes
  - Cleaning / Regeneration
- Find Justifications based on:
  - Safety & Exposure
  - Productivity
  - Cost Efficiency
  - Knowledge Capture
- Start Small
  - Use the best tool for the job
  - Get users involved (buy-in and better results)
  - Create Templates

# Modular Procedural Automation - Applications

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- Wednesday 10-31-2012, Technology Session Track 2
  - Wayne Hawkins, Chevron  
"Modular Procedural Automation in Gulf of Mexico Deepwater Operations"
  - Zahra Kerkan, Shell  
"Modular Design Approach to Subsea MCS"
  - Exhibit Area – Exapilot Demo

# Modular Procedural Automation - Summary

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- Consulting Methodology
  - Capture best practices
  - Modular
- Available Today
- ISA-106 Upcoming Standard
  - Systematic, model-based approach
- Tool Selection
  - Exapilot
  - Unit Instrument Function Block



# Questions?

Thank you.