General Specifications

Turbomachinery I/O Modules



GS 33J60F90-01EN

■ GENERAL [Release 6]

This document of General Specification (GS) contains the hardware specifications of the Turbomachinery I/O Modules (FIO). For the field control stations that are applicable for the Turbomachinery I/O Modules, please refer to "Turbomachinery I/O Module Logic Builder Package" (GS 33J10U10-01EN).

■ STANDARD SPECIFICATIONS

Servo Modules (Isolated)

The Servo module receive LVDT or 1 to 5 V DC standardized signal for position feedback signal and 24V DC ON/OFF signals for quick close and outputs up to \pm 50 mA signal for servo control.

This can be used in dual redundant configuration.

Excitation voltage 5 Vrms at 30 mArms (max) Excitation current 30 mArms (max) Excitation frequency 2.8 k, 3.0 k, 3.2 kHz Accuracy ±1 % Input Voltage Drift due to ambient temperature change ±0.4 % / 10 °C Input impedance Powered: 220 kΩ; N Allowable input voltage ±30 Vpeak External power supply +11.4 to +13.2 V, 0.3 Filterring Collectively Voltage Inputs Number of input channels 4, isolated Input signal 1 to 5 V Accuracy ±4 mV Drift due to ambient temperature change ±4 mV / 10 °C Input impedance Powered: 1 MΩ; No Allowable input voltage 30 V DC Filtering Collectively Number of output channels 2, isolated Output signal ±25 mA/±50 mA; S Accuracy ±150 μA/±300 μA Accuracy ±150 μA/±300 μA Drift due to ambient temperature change ±50 μA/10 °C/±10 Allowable load resistance 270 Ω at ±25 mA 10 °C/±10 Allowable load resistance 270 Ω at ±25 mA/±50 mA; S Circuit-open detection Available External power supply +11.4 to +13.2 V, 0.3 Dither 0 to ±20 % of the ra Digital Inputs Number of input channels 2, isolated Rated input voltage 18 to 26.4 V DC (Sink) Input ON voltage 18 to 26.4 V DC or less Input Current 4.1 mA±20 % Maximum allowable input voltage 30 V DC Scan cycle	Specification		
Wiring type	AGS813		
Excitation voltage 5 Vrms at 30 mArms (max) Excitation current 30 mArms (max) Excitation frequency 2.8 k, 3.0 k, 3.2 kHz Accuracy ±1 % Input Voltage Drift due to ambient temperature change ±0.4 % / 10 °C Input impedance Powered: 220 kΩ; N Allowable input voltage ±30 Vpeak External power supply +11.4 to +13.2 V, 0.3 Filterring Collectively Voltage Inputs Number of input channels 4, isolated Input signal 1 to 5 V Accuracy ±4 mV Drift due to ambient temperature change ±4 mV / 10 °C Input impedance Powered: 1 MΩ; No Allowable input voltage 30 V DC Filtering Collectively Current Outputs Number of output channels 2, isolated Output signal ±25 mA / ±50 mA; S Accuracy ±150 µA / ±300 µA Drift due to ambient temperature change ±50 µA / 10 °C / ±10 Allowable load resistance 270 Ω at ±25 mA 16 Circuit-open detection Available External power supply +11.4 to +13.2 V, 0.3 Dither Number of input channels 2, isolated Rated input voltage 18 to 26.4 V DC (Sink) Input OFF voltage 18 to 26.4 V DC or less Input current 4.1 mA ±20 % Maximum allowable input voltage 30 V DC Scan cycle 5 ms			
Excitation current 30 mArms (max)	3 Wires; 5 Wires; 6 Wires (*1)		
Excitation frequency	5 Vrms at 30 mArms (*2)		
Accuracy			
Drift due to ambient temperature change ±0.4 % / 10 °C	2.8 k, 3.0 k, 3.2 kHz; Selectable (independently) ±1 % Input Voltage: 0.7 to 5 Vrms, Span: 2.5 Vrms minimum ±0.4 % / 10 °C Powered: 220 kΩ; Not powered: 100 kΩ		
Input impedance			
Allowable input voltage			
External power supply			
Filterring Collectively			
Number of input channels	.3 A (*2)	-13.2 to -11.4 V, 0.3 A (*2)	
Input signal			
Accuracy Drift due to ambient temperature change ±4 mV / 10 °C Input impedance Powered: 1 MΩ; No Allowable input voltage 30 V DC Filtering Collectively Current Outputs Number of output channels 2, isolated Output signal ±25 mA / ±50 mA; S Accuracy ±150 μA / 10 °C / ±10 Allowable load resistance 270 Ω at ±25 mA 10 Circuit-open detection Available External power supply +11.4 to +13.2 V, 0.3 Dither 0 to ±20 % of the rail Digital Inputs Number of input channels 2, isolated Rated input voltage 24 V DC (Sink) Input ON voltage 18 to 26.4 V DC Input OFF voltage 5 V DC or less Input current 4.1 mA ±20 % Maximum allowable input voltage 30 V DC Scan cycle 5 ms			
Drift due to ambient temperature change	1 to 5 V		
Input impedance	±4 mV		
Allowable input voltage 30 V DC	±4 mV / 10 °C		
Filtering Collectively	Powered: 1 MΩ; Not powered: 100 kΩ		
Current Outputs Number of output channels 2, isolated Output signal ±25 mA/±50 mA; S Accuracy ±150 μA/±300 μA Drift due to ambient temperature change ±50 μA/10 °C/±10 Allowable load resistance 270 Ω at ±25 mA 10 Circuit-open detection Available External power supply +11.4 to +13.2 V, 0.3 Dither 0 to ±20 % of the rail Number of input channels 2, isolated Rated input voltage 24 V DC (Sink) Input ON voltage 18 to 26.4 V DC Input OFF voltage 5 V DC or less Input current 4.1 mA ±20 % Maximum allowable input voltage 30 V DC Scan cycle 5 ms			
Output signal			
Accuracy			
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Selectable (ir	ndependently)	
Allowable load resistance 270 Ω at ±25 mA 10			
Circuit-open detection Available External power supply +11.4 to +13.2 V, 0.3 Dither 0 to ±20 % of the ra Number of input channels 2, isolated Rated input voltage 24 V DC (Sink) Input ON voltage 18 to 26.4 V DC Input OFF voltage 5 V DC or less Input current 4.1 mA ±20 % Maximum allowable input voltage 5 ms	00 μA / 10 °C	>	
External power supply	00 Ω at ±50	mA	
Dither			
Digital Inputs Number of input channels 2, isolated Rated input voltage 24 V DC (Sink) Input ON voltage 18 to 26.4 V DC Input OFF voltage 5 V DC or less Input current 4.1 mA ±20 % Maximum allowable input voltage 30 V DC Scan cycle 5 ms	.3 A	-13.2 to -11.4 V, 0.3 A	
Rated input voltage	0 to ±20 % of the range at 33 Hz		
Input ON voltage			
Input OFF voltage	24 V DC (Sink)		
Input current			
Maximum allowable input voltage 30 V DC Scan cycle 5 ms	5 V DC or less		
Scan cycle 5 ms	4.1 mA ±20 %		
-	30 V DC		
Withstanding voltage Between system an	5 ms		
Between different ty	Between system and field: 500 V AC for 1 minute Between different type inputs/outputs: 500 V AC for 1 minute		
External connection Dedicated cable (Al	Dedicated cable (AKB337-M005, M007, M010)		
Maximum power consumption 500 mA (5 V DC)	500 mA (5 V DC)		
Weight Approx. 0.36 kg	Approx. 0.36 kg		

^{*1:} The channel used for Excitation Power and for LVDT Input is same.

^{*2:} This excitation voltage is adjustable 4 to 7 Vrms. When the excitation voltage exceeds 5 Vrms, an external power supply (+14 to +16 V, -14 to -16 V) should be used.



• High Speed Protection Module (Isolated)

ltem			Specification		
Model			AGP813		
Voltage Inputs	Number of input channels		4 channels at high-speed cycle; isolated 6 channels at basic cycle; isolated		
	Input signal		1 to 5 V		
	Accuracy		±4 mV		
	Drift due to ambient tempe	erature change	±4 mV / 10 °C		
	Input impedance		Powered: 1 MΩ, Not powered: 100 kΩ		
	Allowable input voltage		30 V DC		
	Filtering		Collectively		
Pulse Inputs	Number of input channels		4 channels at basic cycle ; isolated		
	Input impedance		10 kΩ (at AEGP1D)		
	Magnetic Pickup (MPU)	Input signal	0.5 to 150 Vpp		
		Input frequency	50 Hz to 25 kHz		
		Accuracy	±1 Hz (50 Hz to 2 kHz) ±0.05 % of reading (2 kHz to 25 kHz)		
		Input sensitivity	Without hysteresis 50 to 500 Hz: 0.5 Vpp or more 500 Hz to 5 kHz: 1.0 Vpp or more 5 to 25 kHz: 2.0 Vpp or more With Hysteresis 50 to 500 Hz: 1.0 Vpp or more 500 Hz to 5 kHz: 2.0 Vpp or more 5 to 25 kHz: 4.0 Vpp or more		
	Active Pickup	Input signal	When the threshold is TYPE1 VH: 2.0 to 24 V VI: 0 to 0.8 V Duty: 50 % ±5 % When the threshold is TYPE2 VH: 2.4 to 24 V VI: 0 to 1.2 V Duty: 50 % ±5 %		
		Input frequency	0.04 Hz to 2 kHz		
		Accuracy	±0.1 % of reading		
Digital Inputs (SOE)	Number of input channels		4 channels at high-speed cycle; isolated 8 channels at basic cycle; isolated		
	Rated input voltage		24 V DC (Sink)		
	Input ON voltage		18 to 26.4 V DC		
	Input OFF voltage		5 V DC or less		
	Input current		4.1 mA ±20 %		
	Maximum allowable input ve	oltage	30 V DC		
Digital Outputs	Number of output channels	s	4 channels at high-speed cycle; isolated 8 channels at basic cycle; isolated		
	Output type		Current sinking		
	Maximum load (*1)		100 mA / channel; 30 V DC		
	Maximum voltage for On		0.3 V DC (*2)		
	Maximum current leak for	Off	0.1 mA		
	On/Off delay		1 ms (Typ.)		
Scan cycle			5 ms at high-speed cycle 10 ms at basic cycle		
Withstanding voltage			Between system and field: 500 V AC for 1 minute Between different type inputs/outputs: 500 V AC for 1 minute		
External connection			Dedicated cable (AKB337-M005, M007, M010)		
Maximum power consumption			900 mA (5 V DC)		
			······ \		

Connect a spark killer diode when driving DC relay. By the length of the cable, added 0.22 V/m.

• Terminal Board

Model	Application	Number of Channels	Module Connected	Cable Connected	Weight	Insulation Resistance	Withstanding Voltage
AEGS1D	Servo Module (Single and dual-redundant)	LVDT: 4 Inputs (*1) Voltage: 4 Inputs Current: 2 Outputs Digital: 2 Inputs	AGS813	AKB337-M005, M007, M010	Approx. 2.0 kg	10 MΩ or more at 500 V DC.	500 V AC for 1 minute. (Between inputs/outputs
AEGP1D	High Speed Protection Module (Single and dual-redundant)	Voltage: 4 or 6 Inputs Pulse: 0 or 4 Inputs (*2) (*3) Digital: 4 or 8 Inputs and 4 or 8 Outputs	AGP813	AKB337-M005, M007, M010	Approx. 2.0 kg		

- *1: In case of 3 Wiring, A terminal and C terminal or B terminal and D terminal of each channel would be connected with affiliated short bar.
 - Affiliated short bar (T9084CH): 8
- The Shield of MPU and Active Pickup is connected to the SHLD terminal of PI.
- For Active Pickup Input requiring external feeding, COM terminal and C terminal of each channel would be connected with affiliated short bar. The channel should be used respectively Ch4, Ch3, Ch2 and Ch1.

 C terminal of unused Ch should not be connected with short bar.

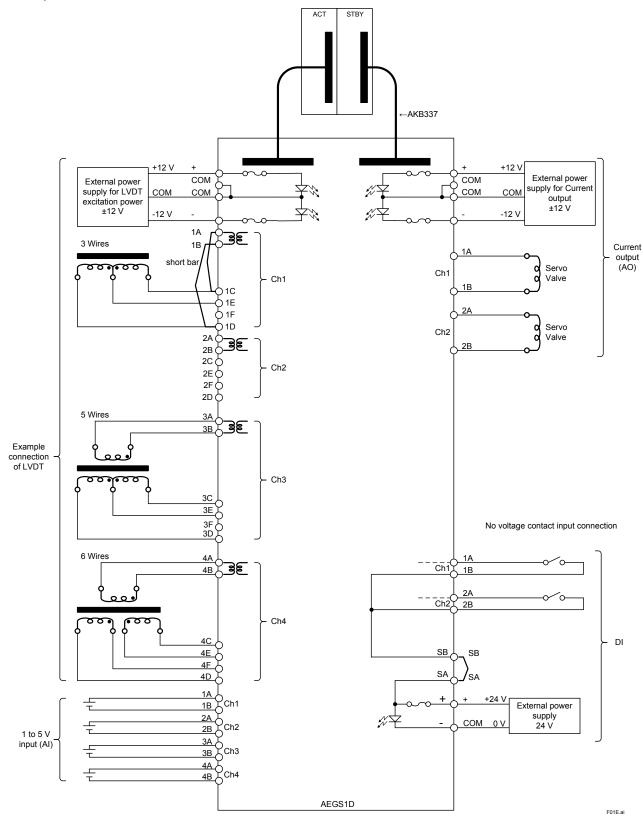
Affiliated short bar

For the connection between COM terminal and C terminal of Ch4 (T9084CH): 1

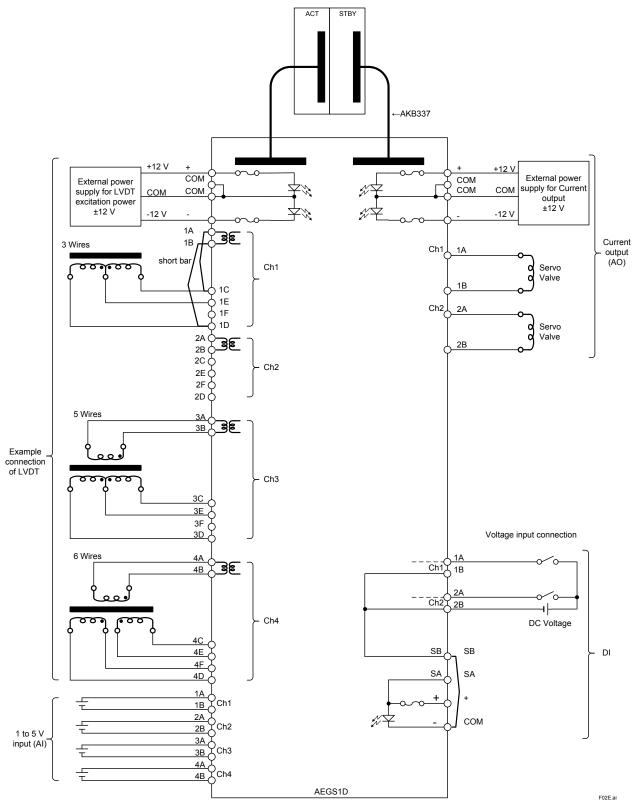
For the connection between each C terminal of channel (T9084CJ): 3

CONNECTION

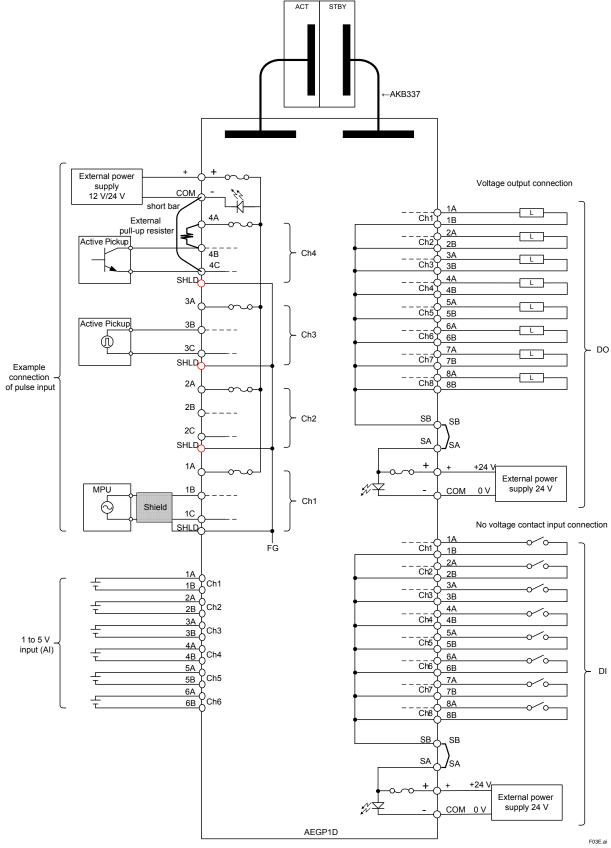
Example Connection for AEGS1D

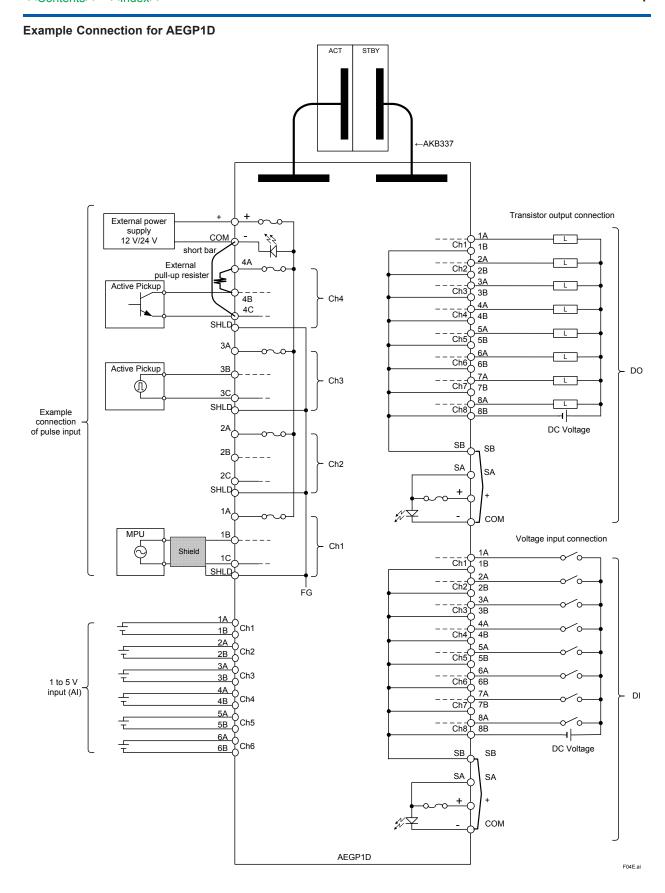


Example Connection for AEGS1D



Example Connection for AEGP1D





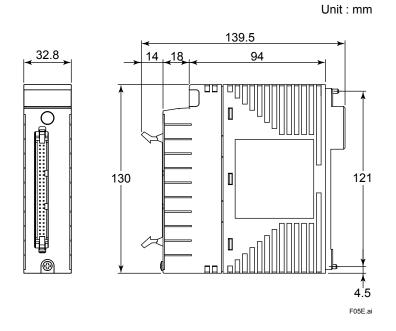
• LIMITATIONS

As for mounting limitations, please refer to FIO System Overview (GS 33J60A10-01EN).

■ EXTERNAL DIMENSIONS

• I/O Module

AGS813/AGP813

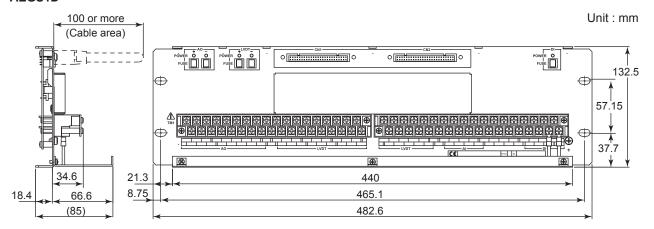


Nominal Tolerances:

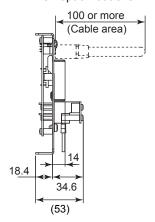
When the reference dimension is over 0.5 mm and equal or less than 120 mm, its nominal tolerance is \pm 0.8 mm, while its combination of nominal tolerance is \pm 1.5 mm. When the reference dimension is over 120 mm, its nominal tolerance is in accordance with JEM 1459.

Terminal Board

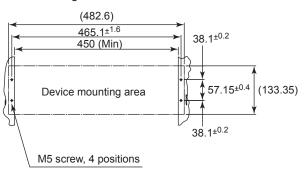
AEGS1D



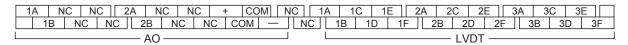
When option code is "/NTRY".



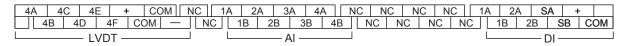
Rack Mounting Dimension



Left side terminal No.



Right side terminal No.



NC: Not connected.

F06E.ai

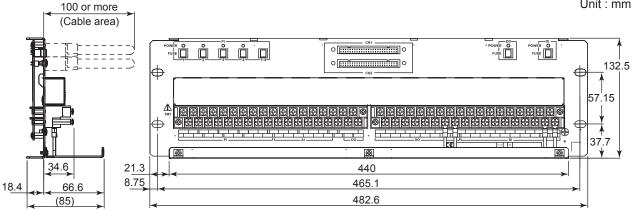
Nominal Tolerances:

When the reference dimension is over 0.5 mm and equal or less than 120 mm, its nominal tolerance is \pm 0.8 mm, while its combination of nominal tolerance is \pm 1.5 mm.

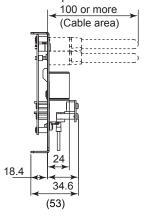
When the reference dimension is over 120 mm, its nominal tolerance is in accordance with JEM 1459.

AEGP1D

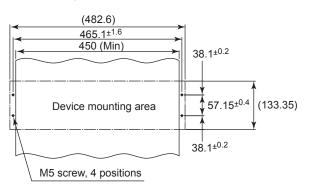




When option code is "/NTRY".



Rack Mounting Dimension



Left side terminal No.



Right side terminal No.



NC: Not connected.

F07E.ai

Nominal Tolerances:

When the reference dimension is over 0.5 mm and equal or less than 120 mm, its nominal tolerance is ± 0.8 mm, while its combination of nominal tolerance is ± 1.5 mm.

When the reference dimension is over 120 mm, its nominal tolerance is in accordance with JEM 1459.

■ MODEL AND SUFFIX CODES

		Description
Model	AGS813	Servo Module (Isolated)
Suffix Codes	-S	Standard type
	1	Always 1
	0	Basic type
	1	With ISA Standard G3 option

		Description
Model	AGP813	High Speed Protection Module (Isolated)
Suffix Codes	-S	Standard type
	1	Always 1
	0	Basic type
	1	With ISA Standard G3 option

		Description
Model	AEGS1D	Terminal Board for Servo (Single and dual-redundant)
	-0	Always 0
Suffix Codes	0	Basic type
	1	With ISA Standard G3 option
Option Code	/NTRY	Without cable tray

		Description		
Model	AEGP1D	Terminal Board for High Speed Protection (Single and dual-redundant)		
	-0	Always 0		
Suffix Codes	0	Basic type		
	1	With ISA Standard G3 option		
Option Code	/NTRY	Without cable tray		

■ APPLICABLE STANDARDS

Refer to the GS "Integrated Production Control System CENTUM VP System Overview" (GS 33J01A10-01EN).

■ ORDERING INFORMATION

When placing an order, the models and suffix codes must be correctly specified.

■ TRADEMARKS

- CENTUM is registered trademark of Yokogawa Electric Corporation.
- Other company and product names appearing in this document are trademarks or registered trademarks of their respective holders.