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## General <br> Specification

High-Resolution Analog Input Module

## GS 34M06H11-04E

## - General

F3AD04-5R, F3AD08-6R, F3AD08-5R and F3AD08-4R are analog-to-digital conversion input modules for the FA-M3.
F3AD04-5R and all F3AD08- $\square \mathrm{R}$ models are equipped with 16 -bit A/D converters.

- Super-high conversion speed of $50 \mu$ s per point
- A single module can handle four or eight differential signal inputs.
- Input signal range can be selected on channel basis from 0 to 5 V , 1 to 5 V , -10 to $10 \mathrm{~V}, 0$ to 10 V DC, 0 to 20 mA DC and 4 to 20 mA DC.

- 4 input points / 8 input points can be multiplexed during sequential $A / D$ conversion.
- The input terminals are isolated from the internal circuit by photocouplers.
- Conversion cycle can be selected on module basis from $50 \mu \mathrm{~s}, 100 \mu \mathrm{~s}$, $250 \mu \mathrm{~s}, 500 \mu \mathrm{~s}, 1 \mathrm{~ms}, 16.6 \mathrm{~ms}, 20 \mathrm{~ms}$ and 100 ms .
- Advanced and easy-to-use features such as scaling and filtering are provided.


## - Specifications

| Item | Specifications |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | F3AD04-5R | F3AD08-6R | F3AD08-5R | F3AD08-4R |
| Number of inputs | 4 differential inputs | 8 differential inputs |  |  |
| Absolute maximum rating | 18 V DC or 25 mADC max. -18 V DC or - 25 mA DC min. |  |  |  |
| Input signal range*1 | Voltage signal only <br> 0 to 5 V DC ( -0.25 to 5.25 V DC) 1 to 5 V DC ( -0.25 to 5.25 V DC) -10 to 10 V DC (-11.0 to 11.0 V DC) 0 to 10 V DC ( -0.5 to 10.5 V DC) | Voltage signal or current signal 0 to 5 V DC ( -0.25 to 5.25 V DC) 1 to 5 V DC ( -0.25 to 5.25 V DC) -10 to 10 V DC (-11.0 to 11.0 V DC) 0 to 10 V DC (-0.5 to 10.5 V DC) 0 to $20 \mathrm{mADC}(-1.0$ to 21.0 mADC$)$ 4 to 20 mADC ( -1.0 to 21.0 mADC ) | Voltage signal only <br> 0 to 5 V DC ( -0.25 to 5.25 V DC) 1 to 5 V DC ( -0.25 to 5.25 V DC) -10 to 10 V DC (-11.0 to 11.0 V DC) 0 to 10 V DC $(-0.5$ to 10.5 V DC) | Current signal only <br> 0 to $20 \mathrm{mADC}(-1.0$ to 21.0 mADC$)$ 4 to $20 \mathrm{mADC}(-1.0$ to 21.0 mADC$)$ |
| Conversion cycle ${ }^{\text {2 }}$ | $50 \mu \mathrm{~s} / 100 \mu \mathrm{~s} / 250 \mu \mathrm{~s} / 500 \mu \mathrm{~s} / 1 \mathrm{~ms} / 16.6 \mathrm{~ms} / 20 \mathrm{~ms} / 100 \mathrm{~ms} \times$ (number of inputs); selectable on module basis. |  |  |  |
| Allowable common-mode voltage | ```\pm6 V DC max. (0 to 5V DC, 1 to 5V DC, 0 to 20mA DC, 4 to 20mA DC) \pm1 V DC max. (-10 to 10 V DC, 0 to 10 V DC)``` |  |  |  |
| Isolation method | Across input terminals and internal circuit: Photocoupler isolation Across input terminals: Not isolated |  |  |  |
| Withstanding voltage | 500 V DC for one minute |  |  |  |
| Input resistance | $1 \mathrm{M} \Omega \mathrm{min}$. ${ }^{3}$ | $1 \mathrm{M} \Omega$ min. when configured for <br> voltage input ${ }^{3}$ <br> $250 \Omega$ when configured for current <br> input | 1M $\Omega$ min. ${ }^{\text {3 }}$ | $250 \Omega$ |
| Maximum Resolution ${ }^{\text {4 }}$ | 0.4 mV : <br> 0 to 5 V DC or 1 to 5 V DC or -10 to 10V DC or 0 to 10 V DC input signal range(16bitA/D conversion) | 0.4 mV for 0 to $5 \mathrm{VDC}, 1$ to $5 \mathrm{VDC},-10$ to $10 \mathrm{~V} D \mathrm{C}$ or 0 to 10 V DC input signal range $1.6 \mu \mathrm{~A}$ for 0 to 20 mA DC or 4 to 20 mA DC input signal range (16-bit A/D conversion) |  |  |
| Overall accuracy | $\begin{aligned} & 23 \pm 2^{\circ} \mathrm{C}: \pm 0.1 \% \text { (full scale) } \\ & 0 \text { to } 55^{\circ} \mathrm{C}: \pm 0.2 \% \text { (full scale) }{ }^{* 5} \end{aligned}$ |  |  |  |


| Item | Specifications |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | F3AD04-5R | F3AD08-6R | F3AD08-5R | F3AD08-4R |
| Scaling | Upper and lower limit values can be set to any value between -30,000 and 30,000. ${ }^{*} 6$ |  |  |  |
| Offset | Offset value can be set to any value between -5,000 and 5,000 |  |  |  |
| Filter ${ }^{\text {7 }}$ | First-order lag filter or moving average computation can be enabled or disabled for individual channels. ${ }^{*} 8$ |  |  |  |
| Hold data | Supports recording of peak values and trough values |  |  |  |
| Self diagnosis | Hardware self-diagnosis during operation Over-range input detection |  |  |  |
| Current consumption | 210 mA (5 V DC) |  |  |  |
| External connection | 18-point terminal block, M3.5 screws |  |  |  |
| External dimensions | 28.9 (W) $\times 100$ (H) $\times 106.1$ (D) mm ${ }^{\text {* }}$ |  |  |  |
| Weight | 200 g |  |  |  |

*1: The default input signal range is 0 to 20 mA DC for F3AD08-4R, and -10 to 10 V DC for F3AD04-5R, F3AD08-5R and F3AD08-6R. Conversion results are valid within the selected input signal range.
*2: The conversion cycle is configurable on module basis. It is affected by the number of channels in use (number of unskipped channels). By default, the conversion cycle is 1 ms . Data of 8 channel module is updated every 8 ms (=Conversion cycle $1 \mathrm{~ms} \times 8 \mathrm{inputs}$ ) Data of 4 channel module is updated every 4 ms (=Conversion cycle $1 \mathrm{~ms} \times 4$ inputs).
*3: The input resistance is about $2 \mathrm{M} \Omega$ for channels where the input terminal IND- is not connected to the AG terminal.
*4: The module uses 16 -bit $A / D$ converters internally. The maximum resolution given here is due to scaling computation. The available input signal ranges vary with module type (see "Input Signal Range" row)
*5: Accuracy is $\pm 1 \%$ (full scale) when drift compensation is disabled.
*6: Upper and lower limit values can be set to any value between -20,000 and 20,000 with a firmware prior to Rev. 03.
*7: First-order lag filter or moving average cannot be used when the conversion cycle is set to $50 \mu \mathrm{~s}$.
*8: First-order lag filter and moving average computation cannot be used concurrently on the same channel.
When first-order lag filter is enabled, the actual time constant during operation is affected by the conversion cycle and number of skipped channels. The filter time constant is specified in milliseconds.
The number of data points to be used for moving average computation can be set to any integer from 2 to 32 .
*9: Dimensions excluding protrusions (for details, see external dimensions drawing)

## Environment specification

| Item | Specifications |
| :---: | :---: |
| Surrounding air | Operating : 0 to $55^{\circ} \mathrm{C}$ |
| temperature range | Storage $\quad:-20^{\circ} \mathrm{C}$ to $75^{\circ} \mathrm{C}$ |
| Surrounding | Operating : 10 to 90\% RH (non-condensing) |
| humidity range | Storage : 10 to 90\% RH (non-condensing) |
| Surrounding atmosphere | Must be free of corrosive gases, flammable gases or heavy dust. |

## Components and Functions

- F3AD04-5R
R

18-point terminal block. M3.5 screws with square captive washers.
*: Calibration data is stored in the module to achieve the intended accuracy. These data are written during calibration at the factory and cannot be overwritten by a user.
-F3AD08-6R, F3AD08-5R, F3AD08-4R


- Internal Circuit Diagram


F110-2.vsd

Note: The above figure shows the internal circuit diagram for F3AD08-6R.
The $250 \Omega$ resistor is not provided in F3AD04-5R or F3AD08-5R, but is always connected in F3AD08-4R. F3AD04-5R module has channels from 1 to 4 only.


The SHIELD terminal is connected to the frame ground of the power supply module via the base module
The $A G$ terminal is grounded to the analog ground in the base module.

## Operating Environment

There is no restriction on the type of CPU modules that can be used with this module.

## Model and Suffix Codes

| Model | Suffix Code | Style Code | $\begin{gathered} \text { Optio } \\ \text { n } \\ \text { Code } \end{gathered}$ | Description |
| :---: | :---: | :---: | :---: | :---: |
| F3AD04 | -5R | ...... | ...... | 0 to $5 \mathrm{~V}, 1$ to $5 \mathrm{~V},-10$ to $10 \mathrm{~V}, 0$ to 10 V DC 4 differential inputs, 16 -bit A/D conversion |
| F3AD08 | -6R | $\ldots$ | $\ldots$ | 0 to $5 \mathrm{~V}, 1$ to 5 V , -10 to 10 V , <br> 0 to 10 V DC, 0 to $20 \mathrm{~mA}, 4$ to 20 mADC <br> 8 differential inputs, 16 -bit $\mathrm{A} / \mathrm{D}$ conversion |
|  | -5R | $\ldots$ | $\ldots .$. | 0 to $5 \mathrm{~V}, 1$ to 5 V , -10 to $10 \mathrm{~V}, 0$ to 10 V DC 8 differential inputs, 16 -bit $\mathrm{A} / \mathrm{D}$ conversion |
|  | -4R | $\ldots$ | $\ldots .$. | 0 to $20 \mathrm{~mA}, 4$ to 20 mADC <br> 8 differential inputs, 16 -bit A/D conversion |

## External Dimensions



Unit: mm


## General <br> Specification

## GS 34M06H11-04E

## - General

F3AD04-5V, F3AD08-5V, F3AD08-4W are analog-to-digital conversion input modules for the FA-M3.
These models are equipped with 12 -bit A/D converters.

- Conversion speed of 1 ms per point.
- A single module can handle four or eight differential signal inputs.
- Input signal range can be selected on channel basis from 0 to 5 V , 1 to 5 V , -10 to $10 \mathrm{~V}, 0$ to $10 \mathrm{~V} \mathrm{DC}, 0$ to 20 mA DC and 4 to 20 mADC .
- 4 input points / 8 input points can be multiplexed during sequential A/D conversion.
- The input terminals are isolated from the internal circuit by photocouplers.

- Advanced and easy-to-use features such as scaling and filtering are provided.


## - Specifications

| Item | Specifications |  |  |
| :---: | :---: | :---: | :---: |
|  | F3AD04-5V | F3AD08-5V | F3AD08-4W |
| Number of inputs | 4 differential inputs | 8 differential inputs |  |
| Absolute maximum rating | 18 V DC or 25 mA DC max. -18 V DC or - 25 mADC min. |  |  |
| Input signal range*1 | Voltage signal only <br> 0 to 5 V DC ( -0.25 to 5.25 V DC) 1 to 5 V DC ( -0.25 to 5.25 V DC) -10 to 10 V DC (-11.0 to 11.0 V DC) 0 to 10 V DC ( -0.5 to 10.5 V DC) |  | Current signal only $\begin{aligned} & 0 \text { to } 20 \mathrm{mADC}(-1.0 \text { to } 21.0 \mathrm{~mA} \mathrm{DC}) \\ & 4 \text { to } 20 \mathrm{mADC}(-1.0 \text { to } 21.0 \mathrm{~mA} \mathrm{DC}) \\ & \hline \end{aligned}$ |
| Conversion cycle*2 | $1 \mathrm{~ms} \times$ (number of inputs) |  |  |
| Allowable common-mode voltage | $\pm 6 \mathrm{~V}$ DC max. ( 0 to 5 V DC, 1 to 5 V DC, 0 to 20mA DC, 4 to 20mA DC) <br> $\pm 1 \mathrm{~V}$ DC max. (-10 to $10 \mathrm{~V} D C, 0$ to $10 \mathrm{~V} D C$ ) |  |  |
| Isolation method | Across input terminals and internal circuit: Photocoupler isolation Across input terminals: Not isolated |  |  |
| Withstanding voltage | 500 V DC for one minute |  |  |
| Input resistance | $1 \mathrm{M} \Omega$ min. ${ }^{\text {3 }}$ |  | $250 \Omega$ |
| Maximum Resolution | 1.4 mV : 0 to $5 \mathrm{~V} D \mathrm{DC} 1$ to 5 V DC or 0 to 10 V DC input signal range 5.7 mV : -10 to $10 \mathrm{~V} D$ input signal range (12bitA/D conversion) |  | $5.6 \mu \mathrm{~A}$ for 0 to 20 mA DC or 4 to 20 mA DC input signal range <br> (12-bit A/D conversion) |
| Overall accuracy | $\begin{aligned} & 23 \pm 2^{\circ} \mathrm{C}: \pm 0.2 \% \text { (full scale) } \\ & 0 \text { to } 55^{\circ} \mathrm{C}: \pm 0.5 \% \text { (full scale) }{ }^{4} \end{aligned}$ |  |  |
| Scaling | Upper and lower limit values can be set to any value between $-30,000$ and 30,000 . ${ }^{5}$ |  |  |
| Offset | Offset value can be set to any value between $-5,000$ and 5,000 |  |  |
| Filter | First-order lag filter or moving average computation can be enabled or disabled for individual channels. ${ }^{6} 6$ |  |  |
| Hold data | Supports recording of peak values and trough values |  |  |
| Self diagnosis | Hardware self-diagnosis during operation Over-range input detection |  |  |
| Current consumption | 210 mA (5 V DC) |  |  |
| External connection | 18-point terminal block, M3.5 screws |  |  |
| External dimensions | 28.9 (W) $\times 100$ (H) $\times 106.1$ (D) mm ${ }^{7}$ |  |  |
| Weight | 200 g |  |  |

*1: The default input signal range is -10 to 10 V DC for F3AD04-5V, F3AD08-5V and 0 to 20 mA DC for F3AD08-4W. Conversion results are valid within the selected input signal range.
*2: By default, data of 8 channel module is updated every 8 ms ( $=$ Conversion cycle $1 \mathrm{~ms} \times 8$ inputs). Data of 4 channel module is updated every 4 ms ( $=$ Conversion cycle $1 \mathrm{~ms} \times 4$ inputs).
*3: The input resistance is about $2 \mathrm{M} \Omega$ for channels where the input terminal IND- is not connected to the AG terminal.
*4: Accuracy is $\pm 1 \%$ (full scale) when drift compensation is disabled.
*5: Upper and lower limit values can be set to any value between -20,000 and 20,000 with a firmware prior to Rev. 03.
*6: First-order lag filter and moving average computation cannot be used concurrently on the same channel.
When first-order lag filter is enabled, the actual time constant during operation is affected by the conversion cycle and number of skipped channels. The filter time constant is specified in milliseconds.
The number of data points to be used for moving average computation can be set from 2 to 32 .
*7: Dimensions excluding protrusions (for details, see external dimensions drawing)

## Environment specification

| Item | Specifications |
| :--- | :--- |
| Surrounding air <br> temperature range | Operating: 0 to $55^{\circ} \mathrm{C}$ |
| Surrounding <br> Surage $:-20^{\circ} \mathrm{C}$ <br> humidity range <br> ha | Operating $: 10$ to $90 \% \mathrm{CH}$ (non-condensing) |
| Surrounding <br> atmosphere | Storage $: 10$ to $90 \%$ RH (non-condensing) <br> Must be free of corrosive gases, flammable gases or <br> heavy dust. |

## Components and Functions

- F3AD04-5V



■ Internal Circuit Diagram


F110-3.vsd
The above figure shows the internal circuit diagram for
F3AD08-4W.
The 250 resistor is not provided in F3AD04-5V, F3AD08-5V.
F3AD04-5V module has channels from 1 to 4 only.

## - External Connection Diagram



- The SHIELD terminal is connected to the frame ground of the power supply module via the base module
The AG terminal is grounded to the analog ground in the base module.


## Operating Environment

There is no restriction on the type of CPU modules that can be used with this module.

## Model and Suffix Codes

| Model | Suffix Code | Style Code | Option Code | Description |
| :---: | :---: | :---: | :---: | :---: |
| F3AD04 | -5V | $\ldots$ | … | 0 to $5 \mathrm{~V}, 1$ to 5 V , -10 to $10 \mathrm{~V}, 0$ to 10 V DC 4 differential inputs, 12 -bit $\mathrm{A} / \mathrm{D}$ conversion |
| F3AD08 | -5V | $\ldots$ | $\ldots$ | 0 to $5 \mathrm{~V}, 1$ to $5 \mathrm{~V},-10$ to $10 \mathrm{~V}, 0$ to 10 V DC 8 differential inputs, 12 -bit $\mathrm{A} / \mathrm{D}$ conversion |
|  | -4W | $\ldots$ | ... | 0 to $20 \mathrm{~mA}, 4$ to 20 mADC <br> 8 differential inputs, 12 -bit A/D conversion |

External Dimensions


Unit: mm


## Functional Overview

For F3AD04-5R, F3AD08-6R, F3AD08-5R, F3AD08-4R, F3AD04-5V, F3AD08-5V, F3AD08-4W

## 1. Scaling

1.1 Scaling

The scaling function maps the digital output values of the upper limit and lower limit of the input signal range to user-specified values between -30,000 and 30,000.

Example: Input signal range: 1 to 5 V DC; upper limit for scaling: 10,000; lower limit for scaling: 0


### 1.2 Offset

The offset function applies a user-specified offset amount between $-5,000$ and 5,000 to the digital output.
Example: Input signal range: 1-5V DC; upper limit for scaling: 10,000; lower limit for scaling: 0; offset amount: -125


## 2. Filtering

### 2.1 First-order Lag Filter

Filtering is used to suppress sudden changes in the digital output. A digital low-pass first-order lag filter can be configured for each input channel by specifying the time constant in ms .

## Response of Filter to Step Change in Input Signal



Note: The conversion output responds in small steps at each data update period, given by conversion cycle $\times$ number of channels in use.
TIP: Time constant ( $T$ ) and the cutoff frequency $\left(f c\right.$ ) are related by the equation: $f c=\frac{1}{2 \pi T}$

### 2.2 Moving Average Computation

The moving average function is used to suppress sudden changes in the digital output by computing moving averages of converted values for an input channel using a user-specified number of up to 32 data points.

## Example: Response of Moving Average Computation to Step Change in Input Signal (when 8 data points are using for averaging)


(*) Data update period is given by:
conversion cycle $\times$ Number of unskipped channels
Note: The conversion output responds in small steps at each data update period, given by conversion cycle $\times$ number of channels in use.

## 3. Hold Data

The Hold Data function records maximum and minimum digital output values for each channel internally. These values can be read by a program, just like conversion output values, or cleared by a program at any time.

## Conceptual Diagram of Hold Data Operation



Note: The hold data function stores final conversion output values after scaling, offset and filtering. It records the minimum and maximum values periodically according to the data update period, given by conversion cycle $\times$ number of channels in use.

