# User's Manual

## Model UT150 **Temperature Controller**



Please read through this user's manual to ensure correct usage of the controller and keep it handy for quick reference.

Contents What is on the Front Panel?.. Installing the Controller .. Panel Cutout Dimensions and External Dimensions Hardware Specifications ..... **Key Operations** Troubleshooting

**Revision Record** 

IM 05C01E12-01E 1st Edition: Oct. '00 2nd Edition: Feb.'01 3rd Edition: Jun. '04 4th Edition: Mar. '16



IM 05C01F12-01F 1st Edition Oct. 2000 (YK 4th Edition Mar. 2016 (YK

Yokogawa Electric Corporation

■ Checking Package Contents

Before using the product, check that its model & suffix codes are as you ordered.

**Model and Suffix Codes** 

Model Suffix co		Description		
UT150		Temperature controller		
Control output for standard-		Relay output (time-proportional PID or on/off control) Voltage pulse output (time-proportional PID) 4 to 20mA output (continuous PID)		
Control output for cooling		No cooling output (standard type) Relay output (time-proportional PID or on/off control) Voltage pulse output (time-proportional PID) 4 to 20mA output (continuous PID)		
Option /RET /RS		Alarm outputs (2 points) Heater disconnection alarm (includes optional /AL function) SP1/SP2 switching, starting of timer, and RUN/STOP switching by external contacts PV retransmission output in 4 to 20mA Communication function Power Supply 24V DC / 24V AC		

Note: When specifying the /RS option, be sure to order the required number of copies of Communication Functions User's Manual separeately

Check the package contents against the list below Temperature controller Mounting bracket · User's manual (this manual)

### Notice

The following safety symbol is used both on the product and in this user's manual.



#### **WARNING**

This symbol stands for "Handle with Care." When displayed on the product, the operator should refer to the corresponding explanation given in the user's manual in order to avoid injury or death of personnel and/or damage to the product. In the manual the symbol is accompanied by an explanation of the special care that is required to avoid shock or other dangers that may result in injury or loss of life.

The following symbols are used in this manual only.



### CAUTION

Indicates that operating the hardware or software in a particular manner may lead to damage or result in system failure.

## **IMPORTANT**

Draws attention to information that is essential for understanding the operation and/or features of the product.

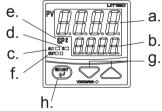
## **■** Exemption from Responsibility

Make sure that all of the precautions are strictly adhered to. Yokogawa Electric Corporation assumes no liability for any damage resulting from use of the instrument in contradiction to the

Also, Yokogawa Electric Corporation assumes no liability to any party for any loss or damage, direct or indirect, caused by the use or any unpredictable defect of the instrument.

# What is on the Front Panel?

# **UT150**



	Name	Function
a.	PV display (red)	Indicates PV (measured value) and character information such as parameter codes and error codes.
b.	SP display (green)	Indicates SP (target setpoint) and parameter values.
C.	Alarm 1 (AL1) lamp (red)	Lit when alarm 1 is activated.
d.	Alarm 2 (AL2) lamp (red)	Lit when alarm 2 is activated.
e.	SP2 lamp (green)	Lit when SP2 is being used for control operation.
f.	Output (OUT) display lamps (Left: orange; right: green)	Lit while control output is being output.  The left (upper) lamp is lit in orange during control output of standard type.  In heating/cooling control, the left (upper) lamp lights up in orange when the heating-side output is active; while the right (lower) lamp lights up in green when the cooling-side output is active.
g.	Data change keys (Indicated as simply the  and  and keys hereafter.)	<ul> <li>Changes SP and the parameter values.</li> <li>Pressing the key decreases the data value and pressing the key increases it. Holding down the key will gradually increase the speed of the change.</li> </ul>
h.	SET/ENT key (data registering key) (Indicated as simply the key hereafter.)	<ul> <li>Registers the data value changed using the data change keys.</li> <li>Switches between operating display or parameter setting displays sequentially.</li> <li>Pressing the key for 3 seconds or longer in the operating display retrieves the operating parameter setting display.</li> <li>Pressing the key for 3 seconds or longer in either an operating or setup parameter setting display transfers back to operating display 1. (See page 3.)</li> </ul>

## Installing the Controller



## **WARNING**

To prevent electric shock, the source of power to the controller must be turned off when mounting the controller on to a panel.

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You can download the latest manuals from the following website

http://www.yokogawa.com/ns/ut/im/

Authorised Representative in the EEA

Yokogawa Europe BV. (Address: Euroweg 2, 3825 HD Amersfoort, The Netherlands) is the Authorised Representative of Yokogawa Electric Corporation for this Product in the EEA.

Printed Manuals

Model UT150 Temperature Controller (IM 05C01E12-01E)

UT100 Series Communication Functions (IM 05C01E12-10E)

General Specifications

Model UT130, UT150 Temperature Controller (GS 05C01E02-01E)

#### **CAUTION**

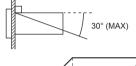
#### To install the controller, select a location where:

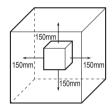
- 1. No-one may accidentally touch the terminals;
- 2. Mechanical vibrations are minimal;
- Corrosive gas is minimal;
- The temperature can be maintained at about 23°C with minimal fluctuation;
- There is no direct heat radiation;
- There are no resulting magnetic disturbances;
- The terminal board (reference junction compensation
- element, etc.) is protected from wind; There is no splashing of water; and
- 9. There are no flammable materials.

#### Never place the controller directly on flammable items.

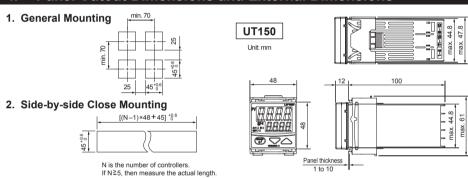
If the controller has to be installed close to flammable items or equipment, be sure to enclose the controller in shielding panels positioned at least 150mm away from each side. These panels should be made of either 1.43mm thick metal-plated steel plates or 1.6mm thick uncoated steel plates

 Mount the controller at an angle within 30° from horizontal with the screen facing upward. Do not mount it facing downward.





# **Panel Cutout Dimensions and External Dimensions**

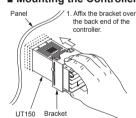


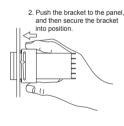


## **CAUTION**

Splash-proof construction is not available when the side-by-side close mounting method shown in the above figures, is chosen for any of the controllers.

## ■ Mounting the Controller





To move the bracket, push down the center of the upper and lower parts of the controller softly The bracket is released from the latch

## Wiring



## **WARNING**

- 1) Before you start wiring, turn off the power source and use a tester to check that the controller and cables are not receiving any power in order to prevent electric shock.
- 2) For safety, be sure to install a circuit breaker switch (of 5A and 100V AC or 220V AC, and that conforms to IEC60947) near the instrument so as to be operated easily, and clearly indicate that the device is used to de-energize the instrument.
- 3) Wiring should be carried out by personnel with appropriate electrical knowledge and experience
- 4) For the wiring cable, the temperature rating is 60 °C or more.

## CAUTION

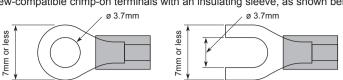
- 1) Use a single-phase power source. If the source has a lot of noise, use an isolation transformer for the primary side and a line filter (we recommend TDK's ZAC2205-00U product) for the secondary side. When this noise-prevention measure is taken, keep the primary and secondary power cables well apart. Since the controller has no fuse, be sure to install a circuit breaker switch (of 5A and 100V AC or 220V AC, and that conforms to IEC standards) and clearly indicate that the device is used to de-energize the controller.
- 2) For thermocouple input, use shielded compensating lead wires. For RTD input, use shielded wires which have low resistance and no resistance difference between the 3 wires. See the table given later for the specifications of the cables and terminals and the recommended products.
- The control output relay cannot be replaced even though it has a limited service life (100,000 relay contacts for the resistance load). Thus, an auxiliary relay should be used so that the load can be turned on and off.
- 4) When using an inductive load (L) such as an auxiliary relay and solenoid valve, be sure to insert a CR filter (for AC) or diode (for DC) in parallel as a spark-rejecting surge suppressor to prevent malfunctions or damage to the relay.
- 5) When there is the possibility of being struck by external lightening surge, use the arrester to protect the instrument.

#### ■ Cable Specifications and Recommended Products

Power supply and relay contact output	600V vinyl insulated wire/cable, JIS C3307, 0.9 to 2.0mm <sup>2</sup>
Thermocouple input	Shielded compensating lead wire, JIS C1610
RTD input	Shielded wire (3-wire), UL2482 (Hitachi cable)
Other signals	Shielded wire

#### ■ Recommended Terminals

Use M3.5 screw-compatible crimp-on terminals with an insulating sleeve, as shown below.



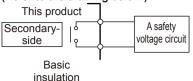
#### **IMPORTANT**

Always fix a terminal cover bracket to the UT150 controller before wiring if an optional anti-electric-shock terminal cover (part number: L4000FB) is used.



#### **CAUTION**

Safety Precaution in IEC61010-1 Since the insulation provided to between relay output terminal and secondary terminal is Reinforced insulation, the connected circuit should use a safety voltage circuit to comply with IEC61010-1. (Refer to the drawing below.)





#### **WARNING**

To prevent damage to the controller, never provide 100-240V AC power supply for power supply AC/DC 24V model (when "/V24" is specified).



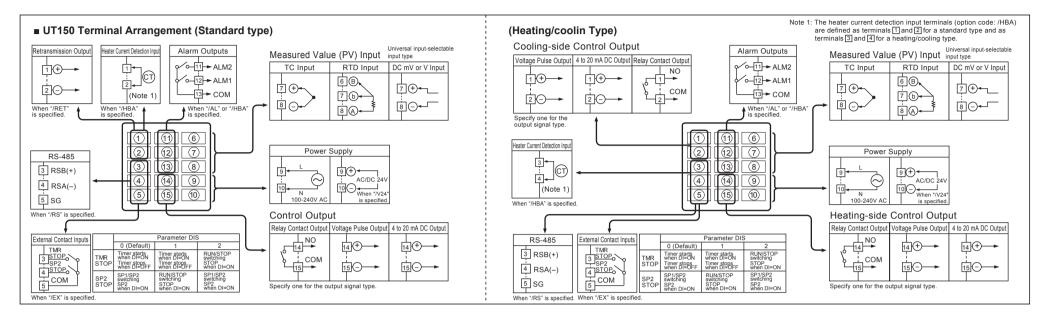
#### **CAUTION**

The  $\oplus$  and  $\bigcirc$  stand for the polarity for DC 24V power supply.



#### **CAUTION**

Do not use unassigned terminals as relay terminals.



## 6. Hardware Specifications

#### Measured Value (PV) Input

- Input: 1 point Input type: Universal: can be selected by software

- Input: 1 point

  Input: 1 point

  Input type: Universal; can be selected by software

  Input accuracy (at 23 ±2"C ambient temperature)

  Thermocouple: ±2"C ±1 digit

  However,

  ±4"C for thermocouple input −270 to −100"C

  ±5"C for type R and S (±9"C for 0 to 500"C)

  ±5"C for type R (accuracy is not guaranteed for 0 to 400"C)

  RTD: ±1"C ±1 digit

  Voltage(m/, V) : ±0.3%

  Sampling period for measured value input: 500ms

  Bum-out detection: Functions for thermocouple or RTD input (bum-out upscale only; cannot be switched off)

  Input resistance: 1MΩ or greater for thermocouple or DC mV input. Approx. 1MΩ for DC V input

  Maximum allowable signal source resistance: 250Ω for thermocouple or DC mV input. 10Ω/wire (The resistance values of three wires must be the same.)

  Allowable input voltage:

  ±10V DC for thermocouple or DC mV input

  Noise rejection ratio:

  Normal mode noise: Min. 40dB (50/60Hz)

  Common mode noise: Min. 40dB (50/60Hz)

  Common mode noise: Min. 40dB (50/60Hz)

  Error of reference junction compensation:

  ±1.5"C(at 15-35"C)

  ±2.0"C (at 0-50"C)

  The reference junction compensation cannot be switched off.

  Applicable standards:

  Thermocouple and resistance temperature detector JIS/ IEC/DIN (ITS90)

# **Control Output**

- · Output: 1 point (for standard type) or 2 points (for heating/cooling type)
  Output type: Choose one from (1) to (3) below:
- (1) Relay contact output
- Contact capacity: 3A at 240V AC or 3A at 30V DC (with resistance load)

  Note: The control output relay cannot be replaced by users.
- (2) Voltage pulse output
  On voltage: 12-18V DC (load resistance: 600Ω or
- Off voltage: 0.1V DC or less (short-circuit current:
- (3) Current output Output signal: 4 to 20mA Maximum load resistance: 600Ω
- Output accuracy: ±0.3% of span
- (at 23±2°C ambient temperature)

#### **Alarm Functions**

- Alarm Functions
   Alarm Functions (Option Code /AL or /HBA)
   Alarm types: 22 types
   (waiting action can be set by software):
   PV high limit, PV low limit, Deviation high limit,
   Deviation low limit, De-energized on deviation high
   limit, De-energized on deviation low limit, Deviation
   high and low limits, High and low limits within deviation,
   De-energized on PV high limit, De-energized on PV low
   limit, Fault diagnosis output, FAIL output
   Alarm output: 2 relay contacts
   Relay contact capacity: 1A at 240V AC or 1A at 30V DC
   (with resistance load)
   Note: The alarm output relays cannot be replaced by
- Note: The alarm output relays cannot be replaced by
- Heater Disconnection Alarm (Option Code /HBA) The heater disconnection alarm is available when tin proportional PID control or on/off control is selected.

- oroportional PID control or on/or control is selected.

   Heater current setting range: 1 to 80A

   Alarm output: 1 relay contact
  (The terminals are the same as those of the /AL option.)
   On time of burn-out detection: Min. 0.2 second
   Sensor: CTL-6-S-H or CTL-12-S36-8
- (URD Co., Ltd.)

■ Timer Function (Option Code /AL/EX or /HBA/EX)
The output contact status changes when the preset time has passed since external contact (TMR) turned on.
The contact action can be selected by software from:
(1) Make contact—the contact closes upon time-up.

# Input contact type: See Contact Inputs below

# Retransmission Output

The retransmission output is provided only when the /RET option is specified, but is not available for the heating/

- option is specified, but is not available in 4-20mA DC cooling type.

  Output signal: Measured value in 4-20mA DC

  Maximum load resistance: 600Ω

  Output accuracy: ±0.3% of span (at 23±2°C ambient temperature)

## **Contact Inputs**

The contact inputs are provided only when the /EX option

- is specified.

  Functions: (1) SP1/SP2 switching
  (2) Starting a timer (See the Alarm Functions...)
  (3) RUN/STOP switching
  Can be selected by parameter DIS.

  Input: 2 points (with the shared common terminal)
- Input type: Non-voltage contact or transistor contact
- Contact capacity: At least 12V/10mA
- On/off judgment: On state for  $1k\Omega$  or less; off state for  $20k\Omega$  or greater

#### **Communication Function**

The communication function is provided only when the /RS option is specified. (For details, read the instruction manual of the communications functions IM OSCO4E42 40E \

- Communication Protocol
  Personal computer link: Used for communication with a personal computer, or UT link module of the FA-M3 controller (from Yokogawa Electric Corporation).
  Ladder communication: Used for communication with a ladder communication module of the FA-M3, or a programmable controller of other manufacturers.
  MODBUS communication: Used for communication with equipment featuring the MODBUS protocol.

- **■** Communication Interface
- Applicable standards: Complies with EIA RS-485 Number of controllers that can be connected: Up to 31 Maximum communication distance: 1,200m
- · Communication method: Two-wire half-duplex, startstop synchronization, non-procedural
  Baut rate: 2400, 4800, or 9600 bps

# Safety and EMC Standards



# WARNING

This instrument is classified into the Measurement Category No.1 in the Do not use for the measurements in locations where the categories are No.2, No.3, and No.4.



 Safety: Compliant with IEC/EN 61010-1 (CE), IEC/EN 61010-2-201 (CE), IEC/EN 61010-2-030 (CE), approved by CAN/CSA C22.2 No. 61010-1 (CSA), approved by UL 61010-1.

- Installation category: II
  Pollution degree: 2
  Measurement category: I (CAT I) (UL, CSA)
  O (Other) (CE)
  Rated measurement input voltage: Max. 10 V DC
  Rated transient overvoltage: 1500 V (\*) This is a reference safety standard value for measurement category I of CSA/UL 61010-1 and for measurement category O of IEC/EN 61010-2-030. This value is not necessarily a
- guarantee of instrument performance.

   EMC standards: Complies with EN 61326.
- Eliko stantidatos. Corriplies with ETA 01250. The instrument continues to operate at a measuring accuracy of within ±20% of the range during tests.
   KC marking: Electromagnetic wave interference prevention standard, electromagnetic wave protection standard compliance

prot	protection standard compliance							
No.	IEC/EN/CSA/ UL 61010-1	EN 61010- 2-030	Description					
No.1	Measurement Category I	O (Other)	For measurements performed on circuits not directly connected to MAINS.					
No.2	Measurement Category II	Measurement Category II	For measurements performed on circuits directly connected to the low voltage installation.					
No.3	Measurement Category III	Measurement Category III	For measurements performed in the building installation.					
No.4	Measurement Category IV	Measurement Category IV	For measurements performed at the source of the low-voltage installation.					

# Power Supply and Isolation



Caution to comply with EMC Standards: When operating this instrument by external power supply, use an independent power unit conforming to CE marking.

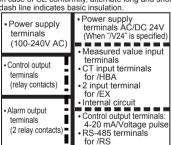
## ■ Power Supply

Power supply	Voltage	Rated at 100-240VAC (±10%) AC/DC 24V when "/V24" is specified.	
	Frequency	50 or 60Hz	
Maximum consumpt		8VA max. (4W max.) 3W max. when "/V24" is specified.	
Memory		Non-volatile memory	
Withstanding voltage	Between primary terminals and secondary terminals (See notes 1 and 3.)	CE: 3000 V AC for 1 minute (Between relay terminals and secondary terminals 1500 V AC for 1 minute) UL/CSA: 1500 V AC for 1 minute (Note 2)	
	Between primary terminals and secondary terminals (See notes 1 and 3.)	20MΩ or more at 500V DC	

Note 1: The primary terminals are the power supply terminals and relay output terminals. The secondary terminals are the analog input and output terminals, the voltage pulse output terminals, and the contact input terminals.

Note 2: The withstanding voltage is specified as 2300 VAC per minute to provide a margin of safety. Note 3: AC/DC 24V terminals are secondary terminals. Isolation

The bold lines below indicate reinforced insulation and the broken line indicates functional insulation in case of CE conformity, alternate long and short



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internal circuit.

Reinforced insulation Functional insulation In case of CE conformity,

input terminals for the /HBA option, nor 2 input terminals for the /EX option are isolated from the

alternate long and short dash Note: Neither the measured value input terminals, CT

# Construction, Mounting, and Wiring

- Construction: Dust-proof and drip-proof front panel conforming to IP65. For side-by-side close installation the controller loses its
- dust-proof and drip-proof protection.
  Casing: ABS resin and polycarbonate
  Case color: Black
- Mounting: Flush panel mounting
- Terminals: Screw terminals

### **Environmental Conditions**

- Normal Operating Conditions
   Warm-up time: At least 30 minutes
- Ambient temperature: 0-50°C (0-40°C when mounted side-by-side)
- Rate of change of temperature: 10°C/h or less
   Ambient humidity:
- 20-90% RH (no condensation allowed)
   Magnetic field: 400A/m or less
   Continuous vibrations of 5 to 14Hz:
   Amplitude of 1.2mm or less
- Continuous vibrations of 14 to 150Hz: 4.9m/s² (0.5G) or less
- Short-period vibrations:
   14.7m/s² (1.5G) for 15 seconds or less
   Shock: 98m/s² (10G) for 11 milliseconds or less
   Shock: 98m/s² (10G) for 12 milliseconds or less
- Mounting angle: Upward incline of up to 30 degrees downward incline is not allowed
- · Altitude: 2000m or less above sea level
- Maximum Effects from Operating Conditions (1) Temperature effectsThermocouple, DC mV and DC V input:
- Resistance temperature detector: ±0.05°C/°C Analog output: ±0.05% of F.S./°C (2) Effect from fluctuation of power supply voltage
- (within rated voltage range)

   Analog input: ±0.2µV/V or ±0.002% of F.S./V, whichever

±2μV/°C or ±0.02% of F.S./°C, whichever is the larger

- is the larger
   Analog output: ±0.05% of F.S. /V
- Transportation and Storage Conditions Temperature: -25 to 70°C
  Humidity: 5 to 95% RH (no condensation allowed)
  Shock: Package drop height 90cm (when packed in the
- dedicated package)

### **Key Operations**



#### **WARNING**

To prevent electric shock, the controller should be mounted on the panel so that you do not accidentally touch the terminals when power is being applied.

#### **IMPORTANT**

The temperature controller is shipped with the parameters set at the factory-set defaults. Check the default values against the "Parameter Lists" in the following page, and change the parameter settings that need to be changed.

This section explains how to set and register parameter values.

The procedure for changing SP (target setpoint) and A1 (alarm 1 setpoint) can be found on "Changing Target Setpoint (SP)" and "Changing Alarm 1 Setpoint (A1)," respectively. You can set the other parameters in the same way.

There are no setup displays for parameters specific to functions, such as the optional alarm output functions or heating/cooling control, if they were not selected at ordering.

The setting of some parameters (such as the control mode parameter CTL) determines whether the other parameters are displayed or not.

The flowchart below will help you understand how this works.

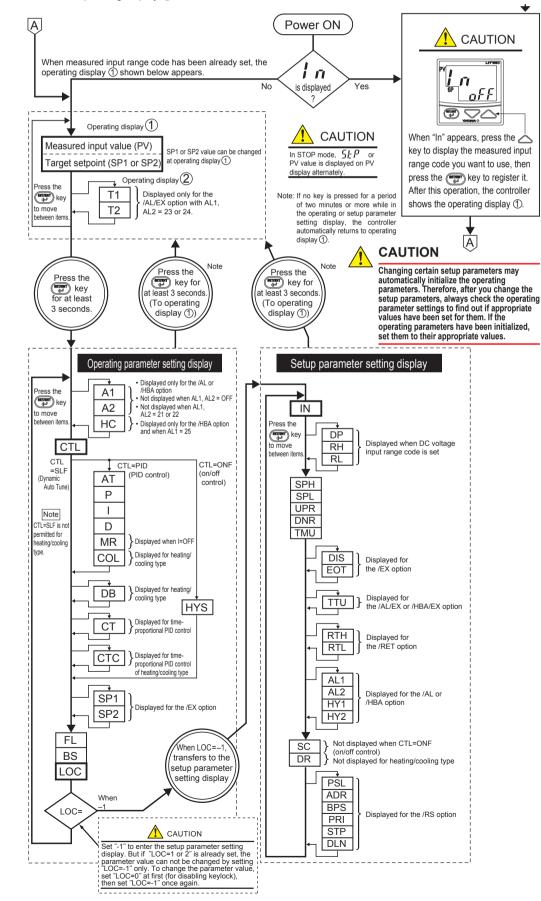
## **CAUTION**

At power-on, the temperature controller displays the operating display ①, but if the measured input range setting remains OFF, then "IN" appears. In this case, press the key to display the measured input range code you want to use, then press the key to register it. (Refer to the flowchart below.) - - - -

- (1) You can move between parameter setting displays using the key.
- (2) To change the set value,
- (i) Change the display value with the  $\bigcirc$  or  $\bigcirc$  key (the period flashes).
- (ii) Press the register the setting.

Note: If you cannot change the parameter setting value, check the key-lock parameter (LOC) setting.

- (3) At the operating display ① or ②, pressing the 🐨 key for at least 3 seconds retrieves the operating parameter setting display.
- (4) At the operating parameter setting display, pressing the pkey for at least 3 seconds transfers back to the operating display ①. Registering the key-lock parameter LOC to "-1" retrieves the setup parameter setting display.
- (5) At the setup parameter setting display, pressing the present the setup parameter setting display, pressing the setup parameter setting display p to the operating display 1.



#### ■ Changing Target Setpoint (SP)

The following instructions assume that the controller is already receiving power.

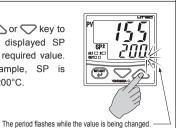
#### Step 1:

Confirm that the controller shows the operating display ① during normal operation (PV and SP are displayed on the indicators)



### Step 2:

Press the  $\bigcirc$  or  $\bigcirc$  key to change the displayed SP value to the required value. In this example, SP is changed to 200°C.



Step 3: Press the result key once to register the setting. The period goes out. SP is now changed.



## ■ Changing Alarm 1 Setpoint (A1)

(This setpoint appears only if the /AL or /HBA option is specified.)

#### Step 1:

Confirm that the controller shows the operating display ① during normal operation (PV and SP are displayed on the indicators).



#### Step 2:

To enter the operating parameter setting display, press the r key for at least 3 seconds. If your controller has the /AL or /HBA option, the display for the Alarm 1 setpoint (A1) appears. (If not, control

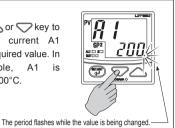


#### Step 3:

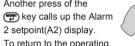
Step 4:

Press the  $\bigcirc$  or  $\bigcirc$  key to change the current A1 value to a required value. In this example, A1 changed to 200°C.

mode (CTL) appears.}



Press the reward key once to register the setting The period goes out. A1 is now changed. Another press of the



To return to the operating

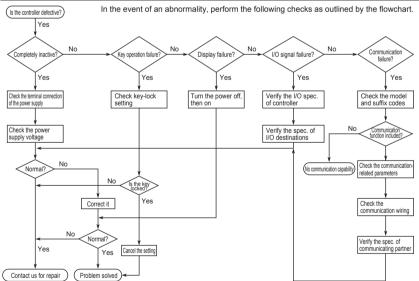


display ①, press the key for at least 3 seconds.

#### UT150 Measured Input Ranges

		ured input Kanges				-	
ш	nput type	Range (°C)	Range code (°C)	Range (°F)	Range code (°F)		
		–270 to 1370°C	1	–300 to 2500°F	31		
	K	0.0 to 600.0°C	2	32.0 to 999.9°F	32		
	N.	0.0 to 400.0°C	3	32.0 to 750.0°F	33		
		-199.9 to 200.0°C	4	–300 to 400°F	34		
<u>e</u>	J	-199.9 to 999.9°C	5	–300 to 2100°F	35		
Thermocouple	Т	-199.9 to 400.0°C	6	-300 to 750°F	36	PV &	
8	E	-199.9 to 999.9°C	7	-300 to 1800°F	37		
ΙĔ	R	0 to 1700°C	8	32 to 3100°F	38	]	
le le	S	0 to 1700°C	9	32 to 3100°F	39	37	
	В	0 to 1800°C	10	32 to 3200°F	40		
	N	–200 to 1300°C	11	-300 to 2400°F	41	10HOOMEN C	
	L	-199.9 to 900.0°C	12	-300 to 1600°F	42	מז גר	
	U	-199.9 to 400.0°C	13	-300 to 750°F	43	] (' ' '	
	Platinel 2	0 to 1390°C	14	32 to 2500°F	44	]	
		-199.9 to 850.0°C	15	-199.9 to 999.9°F	45	For example, to select	
	Pt100	0.0 to 400.0°C	16	32.0 to 750.0°F	46	thermocouple type E (°F	
RTD	P1100	F1100	-199.9 to 200.0°C	17	-300 to 400°F	47	set the range code to 37
۳		-19.9 to 99.9°C	18	-199.9 to 999.9°F	48		
	JPt100	-199.9 to 500.0°C	19				
ge	0 to 100mV	0.0 to 100.0	20				
olta	0 to 100mV 0 to 5V 1 to 5V	0.000 to 5.000 User-scale	21				
1 0	1 to 5V	1.000 to 5.000 User-scal	22				
DC	0 to 10V	0.00 to 10.00	23				

## 8. Troubleshooting



## ■ Error Display during Operation

(1) If the controlle	er displays one of the following, ca	arry out the appropriate remedy for the particular error.		
Display	Error content	Remedy		
P.Er P.Er	The parameter is abnormal	Check the settings of all the parameters and set them at their proper values.		
<b>Ь</b> . <b>о</b> в.о	Input burnout	Check the sensor wiring and correct it.		
000 000	PV over-scale (PV exceeds its effective range.)	Check the input type and range settings and correct them.		
LILLI UUU	PV under-scale (PV falls below its effective range.)			
Flashing period on PV display	Communication failure (for /RS option only)	Press any key to stop the flashing.		

# (2) The controller needs to be repaired if any of the indications in the table below appear.

In these cases, do not try to repair the controller yourself. Order a new controller or contact us for repair. Error content Display Error content Unknown (at power-on) CPU failure Flashing "Err" (at power-on) RAM or ROM failure All extinguished (at power-on) Power source failure Flashing "Err" A/D converter failure. RJC failure, or EEPROM failure (during operation)

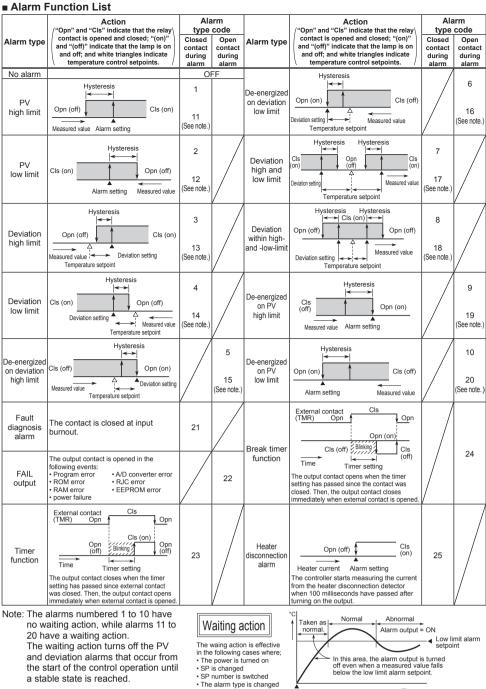
## ■ When Power Failure Occurred during Operation

- Momentary power failures of less than 20ms(or less than 1ms when "/V24" is specified) have no effect on the controller operation (i.e., normal operation continues).
- For power failures longer than 20ms(or longer than 1ms when "/V24" is specified), however the status will be as follows.
  - (The controller action at power recovery is the same as at power-on.) Alarm action: Continues (but alarms with a waiting action enter the waiting state once)

Calibration abnormal

- · Setting parameters: Maintained
- · Auto-tuning: Canceled

"Err" (at power-on)



### ■ Description of Parameters

This section describes the parameter functions specific to the UT150 temperature controller.

(The functions described in other sections of this manual and the general functions are not discussed.) Parameter Function Parameter Function Select one from the following:
a. Dynamic auto tune control (SLF) (See note)
b. PID control (PID)
c. On/off control (ONF) his function adds a bias value to the measure and the result is used for display and control co V input bias PV value inside the controller = measured input value + PV bias This function is useful for carrying out fine adjustment when the PV value is within the required accuracy but it differs from the value obtained by other equipment. Note: Dynamic auto tune control is not available for heating cooling control. Read the section below this table to find out more about ynamic auto tune control. CTL BS You can set this parameter only for control without an integral action (when registered as CTL=PID and I=OFF). The controller outputs the manual reset (MR) value when PV=SP. For example, if you set MR=50%, the controller outputs (OUT) 50% when PV=SP. Decimal point of For DC voltage input, the input signal can be scaled for the particular engineering unit. For example, if you set the input measurement type (IN) at range code 22, the initial range is 0.0 to 100.0. measurement a. Using DP, set the decimal point position fit for the engineering unit you want to use. (In the example below, the 2 digits to the right of the decimal point) MR Next, register the scale values of the measured input scale using RH and RL. (In the example below, RH=10.00 and RL=0.00)

0.0 (1V) | 100.0 (50.0) DP For heating/cooling control, you can set the ratio between the cooling-side output and heating-side output. For example, if you set CoL=2.0 and the heating-side output is 10% at a certain deviation (SP-PV), then the cooling-side output will be 20% when the cooling-side also reaches that deviation. Cooling-side Maximum/ value of measured input scale Measured input scale (after being scaled) 10.00 (RH) 0.00 (RL) COL RH. RL You can only set a deadband for heating/cooling control. In a positive deadband, there are neither heating-side nor cooling-side outputs. In a negative deadband, there are both heating-side and cooling-side outputs, which overlap Deadband Using the SPH and SPL parameters, you can limit the setting range of the target setpoint (SP) within the measured input Maximum minimum value of target setpoint This function prevents SP from being mistakenly set at too large or too small a value (beyond the setting range). each other When the deadband of a heating/
 When both the heating and coordinates. cooling type is positive (Proportional band [P] control) range HYŞ SPH. OFF DB SPL PV -→ 100% PV -→ 100% To prevent a sudden change in SP, or to change SP at a constant rate, ramp-up and ramp-down rates can be se separately. This function operates at the following event Setpoint Hysteresis for For on/off control (CTL=ONF), you can set a hysteresis ramp around the on/off point (SP) to prevent chat up/ramp down . SP change . SP1/SP2 switching On/off point (SP) rate . Power-on At power-on, SP starts from the current PV value.
When the operation mode is switched from STOP to RUN, OFF Hysteresis SP starts from the current PV value. Set the ramp-rate time unit using parameter TMU. HYS UPR, DNR Control output
The cycle time is the period of on/off repetitions of a relay
or voltage pulse output in time proportional PID control. The Hysteresis for alarms are output as relay outputs. Since a relay has a limited life, excessive on/off actions will shorten the life of the alarm. To prevent this, you can set a hysteresis to prevent control output control output value. excessive on/off actions for both alarm 1 and alarm 2. Cycle time t ON CT CTC HY1, HY2 The SUPER function is effective in the following cases: This function should be used when the PV display value SUPER may fluctuate greatly, for example, when the measured input signal contains noise. The filter is of the first-order lag type, and FL sets the time constant. If a larger time constant is set, the filter can remove more noise. a. An overshoot must be suppressed. function The rise-up time needs to be shortened. The load often varies. C. The load unter varies.

d. SP is changed frequently.

Note 1: The SUPER function will not work when on/off control is selected, or I or D constants is set at OFF in PID control.

Note 2: For some types of systems, the SUPER function may not be so useful. If this is the case, turn off the 2-seconds filter **WWW** 

## ■ What is Dynamic Auto Tune Control?

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Dynamic auto tune control is one of the features offered by the temperature controller.

When the controller is turned on or the measured input value (PV) starts "hunting", this mode of control monitors the behavior of the PV and/or OUT (control output value) to automatically determine the optimum PID constants. This means that the PID constants may be changed automatically. If this is not desirable for your system, operate the controller in the normal "PID control".

SC

If you want to automatically determine the PID constants at the initial startup of the controller, first define the target setpoint (SP) and then turn the controller off once and then back on again. Do not use dynamic auto tune control for a system where there is interference or continual disturbances.

#### ■ Parameter Lists

Numbers in ( ) are the parmeter setpoints that apply when the (1) Target Setneint (SD) and Timer Setting 1 and 2

(') ''	Target Detport (Of ) and Timer Detting Taria 2						
Code Name		Name	Setting range and unit	Default	User setting		
(SP value display) Target setpoint Minimum value (SPL) to maximum value (SPH) of target setp Unit: °C/°F		Minimum value (SPL) to maximum value (SPH) of target setpoint range Unit: °C/°F	SPL				
Timer setting 1		Timer setting 1	0.0 to 99.59 Unit: minutes Set the timer time unit using parameter TTU.	0.00			
T2	62	Timer setting 2	For example, 15.25 sets 15 minutes and 25 seconds. (T1 is for AL1, and T2 is for AL2)	0.00			

,	Code	1	s : Parameters changed rather frequently during	Default	Haan aattina
	Code	Name	Setting range and unit		User setting
<b>\1</b>	R I	Alarm 1 setpoint	■ PV alarm Unit: "C/F"  Setting range: minimum value to maximum value of measured input range (scale)  Deviation alarm Unit: "C/F"	Max. value of measured input range (scale) (PV alarm)	
<b>\</b> 2	<i>R2</i>	Alarm 2 setpoint	Setting range: –100 to 100% of the measured input range (scale) span  Heater disconnection alarm Unit: A (ampere) Setting range: OFF(0), 1 to 80 (can be set for the alarm 1 setpoint only)	Min. value of measured input range (scale) (PV alarm)	
HC	HE	Heater disconnection current measured value	"HC" is not a parameter to be set. The current value (0 to 80) of heater disconned displayed. Unit: A (ampere) Settings: When the display value is ———, the heater current is not being measur		
CTL	[EL	Control mode	ONF(0): On/off control PID(1): PID control SLF(2): Dynamic auto tune control (cannot be set for heating/cooling control)	SLF(2) :for standard type; PID(1) : for heating/ cooling type	
AT.	RŁ	Auto-tuning	OFF(0): Stop auto-tuning ON(1): Start auto-tuning	OFF(0)	
<b>.</b>	P	Proportional band	$1^{\circ}\text{C}\textsc{l}^{\circ}\textsc{F}$ to the temperature that corresponds to 100% of the measured input range (scale) span	5% of measured input range (scale) span	
	1	Integral time	1 to 3600 seconds; OFF(0): no integral action	240 seconds	
)	ď	Derivative time	1 to 3600 seconds; OFF(0): no derivative action	60 seconds	
ИR	ñr	Manual reset	-100 to 100%	50.0% for standard type; 0.0% for heating/cooling type	
COL	[oL	Cooling-side gain	0.01 to 9.99 times	1.00 times	
ОВ	dЬ	Deadband	■ PID control Unit: °C/°F  Setting range: -(proportional band setting) to +(proportional band setting)  On/off control Unit: °C/°F  Setting range: -50 to +50% of measured input range (scale)span	0% of measured input range (scale) span	
HYS	HY5	Hysteresis for on/off control	$0^{\circ}\text{C}\textsc{l}^{\circ}\textsc{F}$ to the temperature that corresponds to 100% of the measured input range (scale) span	0.5% of measured input range (scale) span	
СТ	[E	Control output cycle time	1 to 240 seconds	30 seconds	
стс	[E]	Cooling-side control output cycle time	1 to 240 seconds	30 seconds	
SP1	5P !	Target setpoint 1	Minimum value (SPL) to maximum value (SPH) of target setpoint range	SPL	
SP2	582	Target setpoint 2	There are also optional engineering units for voltage input.	SPL	
-L	FL	PV input filter	OFF(0), 1 to 120 seconds	OFF(0)	
3S	<i>6</i> 5	PV input bias	-100 to 100% of measured input range (scale) span	0% of measured input range (scale) span	
_OC	LoE	Key lock	O: No key lock 1: Prevents operations from being changed except for the changing of SP in the operating display 2: Prevents all parameter changing operations -1: Set -1*1 to enter the setup parameter setting display.  But if "LOC=1 or 2* is already set, the parameter value can not be changed by setting "LOC=-1* only. To change the parameter value, set "LOC=0* at first (for disabling keylock), then set "LOC=1* cone again.	0	

<u> </u>				n normal use after on		
	Code	Name	Setting range a	Default	User setting	
IN	l n	Measured input type	1 to 23, 31 to 48 (See input range code list.) OFF(0): No input (If no input type is specified at the time of ord	lering, you must set the input type )	OFF(0), or the input range code specified with order	
DP	dР	Decimal point position of measured input	0: No decimal place (nnnn) 1: One decimal place (nnn.n) 2: Two decimal places (nn.nn)	splayed at voltage input)	1	
RH	r H	Maximum value of measured input scale	3: Three decimal places (n.nnn)  (RL + 1) to 9999 (Dis	splayed at voltage input)	100.0	
RL	rL	Minimum value of measured input scale	-1999 to (RH -1) (Dis	splayed at voltage input)	0.0	
SPH	5PH	Maximum value of target setpoint range	(SPL+1°C) to the maximum value of the mea °C/°F	sured input range (scale) ; Unit:	Maximum value of measured input range (scale)	
SPL	SPL	Minimum value of target setpoint range	Minimum value of measured input range (sca Unit: °C/°F	ale) to (SPH –1°C)	Minimum value of measured input range (scale)	
UPR	UPr	Setpoint ramp- up-rate	OFF(0) or a value from the minimum to the maximum (scale)	n value of the measured input range	OFF(0)	
DNR	dnr	Setpoint ramp- down-rate	Unit: °C/min or °C/hour, °F/min or °F/hour Set the ramp-rate time unit using parameter	TMU.	OFF(0)	
тми	<u>EñU</u>	Setpoint ramp- rate time unit	0 : °C or °F / hour 1 : °C or °F / min		1	
DIS	d1 5	DI-function selection	External Contact Inputs	FF When DI=OFF When DI=ON  RUN/STOP SP1/SP2 switching switching	0	
EOT	Eot	Output in STOP mode	In STOP mode by contact input, fixed control 0:0%, 1:100%	0		
TTU	LLU	Timer time unit	0 : hour.minute 1 : minute.second	1		
RTH	rĿH	Maximum value of retransmission output	Temperature input : Within measured input ra		Maximum value of measured input range (scale)	
RTL	rEL	Minimum value of retransmission output	Voltage input : RTL+1digit to max. value of m Min. value of measured input (scale)(RL) to F However, RTL <rth< td=""><td></td><td>Minimum value of measured input range (scale)</td><td></td></rth<>		Minimum value of measured input range (scale)	
AL1	AL I	Alarm 1 type	OFF(0) or a value from 1 to 22 (see the table 23 or 24 (if the timer function [/EX option] is in 25 (if the heater disconnection function [/HBA	ncluded), and	1 (PV high limit alarm)	
AL2	<u> </u>	Alarm 2 type	OFF(0) or a value from 1 to 22 (see the table 23 or 24 (if the timer function [/EX option]) is		2 (PV low limit alarm)	
HY1	<u> </u>	Alarm 1 hysteresis	0 to 100% of measured input range (scale) sp Unit: °C/°F	pan	0.5% of measured input range (scale)	
HY2	<u> </u>	Alarm 2 hysteresis			span	
sc	<u> 5E</u>	SUPER function	ON(1): Uses the SUPER function OFF(0): Does not use SUPER function Note: Not displayed when on/off control		OFF(0)	
DR	dr	Direct/reverse action	0: Reverse action 1: Direct action Note: Not displayed for heating/cooling type		0	
PSL	P5L	Protocol selection	PC-link communication     PC-link communication with sum check     Ladder communication     MODBUS in ASCII mode     MODBUS in RTU mode		0	
ADR	Adr	Controller address	1 to 99 However, the number of controllers that can be at the maximum.	1		
BPS	<i>6P5</i>	Baud rate	2.4(0): 2400 bps 4.8(1): 4800 bps 9.6(2): 9600 bps	9.6(2)		
PRI	Pr !	Parity	NON(0): Disabled EVN(1); Even parity ODD(2): Odd parity		EVN(1)	
STP	SEP	Stop bit	1 or 2 bits		1 bit	
	ďLn	1	7 or 8 bits • 8 bits when ladder, MODBUS (RTU)	8 bits		

## **IMPORTANT**

To use dynamic auto tune control,

(1) be sure to turn on the final control element, such as a heater, before starting the control, and (2) make sure the controlled loop is a closed loop.

If you do not follow these precautions, improper PID constants may be written into the controller. If this occurs, carry out the following:

- · Set the parameter CTL at PID.
- Set the PID constants at the factory-set defaults (P = (upper range-limit lower rangelimit) × 5%; I = 240 s.; and D = 60 s.)
- Set the parameter CTL at SLF.

If the control still doesn't work properly, stop using the dynamic auto tune control function. Change the parameter CTL setting to PID and execute auto-tuning to obtain the PID constants.