User's **Manual** Model UP350 **Program Controller User's Manual** Installation



IM 05E01D02-01E



2nd Edition: Jul 1, 2001

Yokogawa M&C Corporation

This manual describes installation, wiring, and other tasks required to make the controller ready for operation.

Contents

- 1. Safety Precautions
- 2. Model and Suffix Codes
- 3. How to Install
- 4. How to Connect Wires
- 5. Hardware Specifications
- 6. Terminal Wiring Diagrams

Introduction

Thank you for purchasing the UP350 program controller.

The controller is shipped from the factory with 4 hardcopy user's manuals (A2 size) and 1 user's manual on CD-ROM. The 4 user's manuals in hardcopy format describe the operating procedures required for basic use. It is recommended that you refer to these user's manuals to understand [1] installation, [2] initial settings, [3] program settings, and [4] operating

The CD-ROM contains an User's Manual (Reference) with descriptions of various functions and setting ranges that can be set as necessary.

Moreover, the use of an optional parameter setting tool (model: LL100-E10) allows you to easily perform settings and adjustments with a PC.

■ How to Use the Manuals

Purpose	Manual Title	Il Title Description			
Setup	Installation	Describes the tasks (installation, wiring, and others) required to make the controller ready for operations.	A2-size paper, front		
Basic operation	Initial Settings	Describes examples of setting PV input types, and control output types. Making settings described herein and program creation in Programming User's Manual allow you to carry out basic control.	A2-size paper, front		
Program creation	Programming	Describes examples of creating basic programs. See Program Pattern Setup Charts on the back of Installation User's Manual, and program functions.	A2-size paper back and front		
Operating procedures and troubleshooting	Operations	Describes key operation sequences. For operation control through external contact inputs, see the back of Installation User's Manual.	A2-size paper, back		
Brief operation and setpoint recording	Parameters	Contains the parameter map used as a guideline for setting parameters and lists of parameters for recording User Settings.	A2-size paper, back and front		
Detailed description of functions	User's Manual (Reference)	Explains more advanced applications than those found in the 4 hardcopy user's manuals (A2 size).	CD-ROM		

1. Safety Precautions

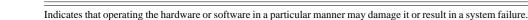
The following symbol is indicated on the controller to ensure safe use.



CAUTION

This symbol on the controller indicates that the operator must refer to an explanation in the user's manual in order to avoid the risk of injury or death of personnel or damage to the instrument. The manual describes how the operator should exercise special care to avoid electric shock or other dangers that may result in injury or loss of life.

The following symbols are used in the hardcopy user's manuals and in the user's manual supplied on the CD-ROM.



M NOTE



Draws attention to information that is essential for understanding the operation and/or features of the controller.

2. Model and Suffix Codes

Before using the controller, check that the model and suffix codes match your order.

Model	Suffix	Code	Description		
UP350		Program controller (provided with retransmission output and 15V loop power supply as standard)			
Туре	-0		Standard type		
Optional functions 0 1		0 1	None With communication		

Check that the following items are provided:

• Program controller (of ordered model): .. Brackets (mounting hardware):

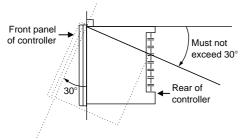
 User's Manuals: .. 4 (A2 size)

• User's Manual (Reference) (CD-ROM version): .

3. How to Install

Installation Position

Install the controller at an angle within 30° from horizontal with the front panel facing upward. Do not install it facing downward. The position of right and left sides should be hori-



♠ NOTE

To install the controller, select a location where

- (1) no one may accidentally touch the terminals
- (2) mechanical vibrations are minimal.
- (3) corrosive gas is minimal,
- (4) temperature can be maintained at about 23°C and the fluctuation is minimal, (5) no direct radiant heat is present.

(7) no wind blows against the terminal board (reference junction compensation

- element). (8) no water is splashed.

(6) no magnetic disturbances are caused.

(9) no flammable materials are around.

Never place the controller directly on flammable items or equipment. If the controller has to be installed close to flammable items or equipment, be sure to provide shielding panels all around the controller, at least 150mm away from every side; the panels should be made of either 1.43mm-thick metal-plated steel plates or 1.6mm-thick uncoated steel plates.

150mm

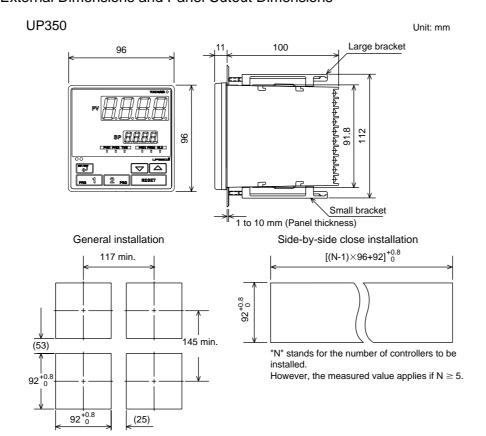
/150mm

150mm



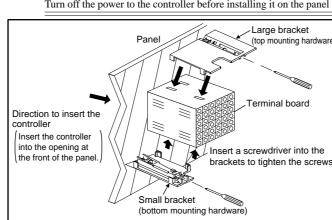
Never touch the opening at the bottom of the case. It is to be used in the factory at shipping

■ External Dimensions and Panel Cutout Dimensions



How to Install

Turn off the power to the controller before installing it on the panel because there is a possibility of electric shock.



After opening the mounting hole on the panel, follow the procedures below to install

> the controller: Insert the controller into the opening from the front of the panel so that the terminal board on the rear is at the far

Set the brackets in place on the top and bottom of the controller as shown in the figure on the left, then tighten the screws of the brackets. Take care not to overtighten them

4. How to Connect Wires



CAUTION

1) Before carrying out wiring, turn off the power to the controller and check that the cables to be connected are not alive with a tester or the like because there is a possibility of electric shock. Wiring must be carried out by personnel who have basic electrical knowledge and practical experience



1) Provide power from a single-phase instrument power supply. If there is a lot of noise in the power line, insert an insulating transformer into the primary side of the line and use a line filter (recommended part: ZAC2205-00U from TDK) on the secondary side.

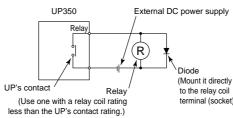
As a countermeasures against noise, do not place the primary and secondary power cables close to each other. 2) For thermocouple input, use shielded compensating lead wires for wiring. For RTD input, use shielded wires that have low conductor resistance and cause no significant differences in resistance between the three wires. The cables to be used for wiring, terminal specifications, and recommended parts are as shown below.

3) Control output relays may be replaced. However, because they have a life of 100,000 times that of the resis-

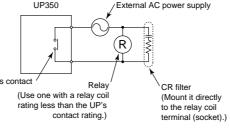
tance load, use auxiliary relays to turn on/off a load. 4) The use of inductance (L) loads such as auxiliary relays, motors and solenoid valves causes malfunction or relay failure; always insert a CR filter for use with alternating current or a diode for use with direct current, as a spark-removal surge suppression circuit, into the line in parallel with the load.

5) When there is possibility of being struck by external lightening surge, use the arrester to protect the instrument.

■ For DC Relay Wiring







Cable Specifications and Recommended Cables

Purpose	Name and Manufacturer
Power supply, grounding, relay contact outputs	600 V PVC insulated wires, JIS C 3307, 0.9 to 2.0 mm ²
Thermocouple	Shielded compensating lead wires, JIS C 1610, □X-□-□□-□ (See Yokogawa Electric's GS 6B1U1-E.)
RTD	Shielded wires (three conductors), UL2482 (Hitachi Cable)
Other signals	Shielded wires

Recommended Terminal Lugs

	Applicable wire size	Tightening torque	
	0.3 to 1.65 mm ²	0.8 N·m or less	
•	ssel ro mm r	or selection of the sel	3.7mm¢

Terminal Covers (Optional parts)

Target Model	Part Number	Sales Unit		
UP350	T9115YD	1		

5. Hardware Specifications

PV Input Signals

- Number of inputs: 1 (terminals ①-②-③)
- · Input type: Universal input system. The input type can be selected with the software.
- Sampling period: 250 ms
- · Burnout detection: Functions at TC, RTD, standard signal (0.4 to 2 V or 1 to 5 V) Upscale, downscale, and off can be specified.
- For standard signal, burnout is determined to have occurred if it is 0.1 V or less. • Input bias current: $0.05 \mu A$ (for TC or RTD b-terminal)
- · Measurement current (RTD): About 0.13 mA • Input resistance: 1 M Ω or more for thermocouple or mV input
- About 1 M Ω for DC voltage input
- Allowable signal source resistance: 250 Ω or less for thermocouple or mV input
- Effects of signal source resistance: 0.1 $\mu V/\Omega$ or less 2 $k\Omega$ or less for DC voltage input Effects of signal source resistance: About 0.01%/100 Ω
- · Allowable wiring resistance: for RTD input Maximum 150 Ω/wire: Conductor resistance between three wires should be equal However, 10 Ω/wire for a maximum range of -150.0 to 150.0°C
- Wire resistance effect: ± 0.1 °C /10 Ω - Allowable input voltage: $\pm 10 \text{ V}$ DC for thermocouple, mV, or
- ±20 V DC for DC voltage input

 Noise rejection ratio: 40 dB (50/60 Hz) or more in normal mode
- 120 dB (50/60 Hz) or more in common mode Reference junction compensation error: ±1.0°C (15 to 35°C) $\pm 1.5^{\circ}$ C (0 to 15°C, 35 to 50°C)
- · Applicable standards: JIS, IEC, DIN (ITS-90) for thermocouples and RTD

Loop Power Supply

(15 V DC: terminals (4-(5))

A resistor (10 to 250 Ω) connected between the controller and transmitter converts a current signal into a voltage signal, which is then read via the PV input terminal Supply voltage: 14.5 to 18.0 V DC, max. 21 mA (provided with a protection circuit against a field short-circuit)

Retransmission Output

Either PV, program setpoint, or control output is output. Either the retransmission output or the loop power supply

- Output signal: 4-20 mA DC
- Load resistance: 600 Ω or less
- Output accuracy: ±0.3% of span under standard operating

Control Output

Universal output system, The output type can be selected

· Current output

(Standard type: terminals (6-(7))

Number of outputs	(switched between a voltage pulse output and current output)
Output signal	4-20 mA DC
Load resistance	600 Ω or less
Output accuracy	$\pm 0.3\%$ of span under standard operating conditions (23 \pm 2 °C, 55 $\pm 10\%$ RH, power frequency of 50/60 Hz)

Output signal On-voltage = 12 V or more

Relay contact output

- can be used with terminals (4)-(5) • Number of outputs: 1 (terminals 4-45)
- conditions (23 \pm 2°C, 55 \pm 10% RH, power frequency of 50/60 Hz)

with the software.

Number of outputs	(switched between a voltage pulse output and current output)				
Output signal	4-20 mA DC				
Load resistance	600 Ω or less				
Output accuracy	$\pm 0.3\%$ of span under standard operating conditions (23 \pm 2 °C, 55 $\pm 10\%$ RH, power frequency of 50/60 Hz)				
. V-1					

(Standard type: terminals (6)-(7))

Number of outputs 1 (switched between a voltage pulse output Off-voltage = 0.1 V DC or less Resolution

(Standard type: terminals (1)-(2)-(3))

(Standard type: terminals (5 (5 (5))				
1				
Three terminals (NC, NO, and common)				
250 V AC or 30 V DC, 3 A (resistance load)				
10 ms				

Contact Outputs

Contact Inputs

Purpose: Run/Reset switching

Number of inputs: 2 points

• Purpose: PV event outputs (2) and time event output (1) · Number of outputs: 3 points

• Input contact rating: 12 V DC, 10 mA or more

resistance of 20 k Ω or more as "off."

exceed 100 µA when "off."

• Relay contact rating: 240 V AC, 1 A, or 30 V DC, 1 A

· Minimum status detection hold time: About 1 second

• Input type: Non-voltage contact or transistor open collector input

resistance of 1 k Ω or less is determined as "on" and contact

For transistor open collector input, input voltage of 2 V or

less is determined as "on" and leakage current must not

· On/off determination: For non-voltage contact input, contact

Display Specifications

- PV display: 4-digit, 7-segment red LED display, character height of 20 mm
- Setpoint display: 4-digit, 7-segment red LED display character height of 9.3 mm
- Status indicating lamps: LEDs

Safety and EMC Standards

• Safety: Compliant with IEC1010-1: 1990 and EN61010-1: 1992 Approved by CSA1010 CSA1010 installation category (overvoltage category): CATII (IEC1010-1)

Approved by UL508 • EMC standards: Complies with EN61326. The instrument continues to operate at a measuring accuracy of within ±20% of the range during tests.

Construction, Installation, and Wiring

Construction: Only the front panel is dust-proof and drip-proof (protection class IP55) For side-by-side close installation the controller loses its

- dust-proof and drip-proof protection · Material: ABS resin and polycarbonate
- Case color: Black · Weight: About 1 kg or less • Dimensions: 96 (W) × 96 (H) × 100 (depth from panel face) mm
- Installation: Panel-mounting type. With top and bottom mounting hardware (1 each)
- Panel cutout dimensions: $92^{+0.8}_{0}$ (W) \times $92^{+0.8}_{0}$ (H) mm
- Installation position: Up to 30° upward facing (not designed for facing downward) · Wiring: M3.5 screw terminals (for signal wiring and power

ground wiring as well)

- Power Supply Specifications Power supply: Rated voltage of 100 to 240 V AC (±10%), 50/60 Hz
- Power consumption: Max. 20 VA (8.0 W max.) · Internal fuse rating: 250 V AC, 1.6A time-lug fuse
- · Data backup: Non-volatile memory (can be written to up to
- 100,000 times) Withstanding voltage
- Between primary terminals* and secondary terminals** At least 1500 V AC for 1 minute (Note)
- Between primary terminals* and grounding te At least 1500 V AC for 1 minute (Note)
- Between grounding terminal and secondary terminals**
 At least 1500 V AC for 1 minute Between secondary terminals*
- * Primary terminals indicate power terminals and relay output terminals ** Secondary terminals indicate analog I/O signal, voltage
- pulse output, and contact input terminals Note: The withstanding voltage is specified as 2300 VAC per minute to provide a margin of safety

At least 500 V AC for 1 minute

• Insulation resistance: $20 \text{ M}\Omega$ or more at 500 V DC between power terminals and grounding terminal Grounding resistance: Class 3 grounding (grounding resistance)

COM 20

Signal Isolations

internal circuit.

- PV input terminals: Isolated from other input/output terminals. Not isolated from the internal circuit.
- 15 V DC loop power supply terminals: Not isolated from 4-20
- mA analog output and voltage pulse control output. Isolated from other input/output terminals and internal circuit.
- 4-20 mA analog output terminals (for control output and retransmission): Not isolated between 4-20 mA outputs and from 15 V DC loop power supply and voltage pulse control output. Isolated from other input/output terminals and
- internal circuit. • Voltage pulse control output terminals: Not isolated from 4-20 mA outputs and 15 V DC loop power supply. Isolated from
- other input/output terminals and internal circuit. · Relay contact control output terminals: Isolated between contact output terminals and from other input/output terminals and
- Contact input terminals: Not isolated between contact input terminals and from communication terminals. Isolated from other input/output terminals and internal circuit.
- · Relay contact event output terminal: Not isolated from each other; isolated from other input/output terminals and the internal circuit.
- RS-485 communication terminals: Not isolated from contact input terminals. Isolated from other input/output terminals and internal circuit.
- Power terminals: Isolated from other input/output terminals and internal circuit. Grounding terminals: Isolated from other input/output terminals

Environmental Conditions

and internal circuit.

 Normal operating conditions Ambient temperature: 0 to 50°C (40°C or less for side-by-side

close installation) Temperature change rate: 10°C/h or less Ambient humidity: 20 to 90% RH (no condensation allowed) Magnetic field: 400 A/m or less

Continuous vibration at 5 to 14 Hz: Full amplitude of 1.2 mm or Continuous vibration at 14 to 150 Hz: 4.9 m/s² or less Short-period vibration: 14.7 m/s², 15 seconds or less

- Shock: 147 m/s² or less, 11 ms Installation height: Height above sea level of 2000 m or less Warm-up time: 30 minutes or more after power on
- · Transportation and storage conditions: Temperature: -25 to 70°C Temperature change rate: 20°C/h or less Humidity: 5 to 95% RH (no condensation allowed)
- Effects of changes in operating conditions - Effects from changes in ambient temperature - On voltage or thermocouple input, $\pm 1~\mu\text{V/°C}$ or $\pm 0.01\%$
- of F.S./°C, whichever is larger - On RTD input, ±0.05°C /°C (ambient temperature) or less - On analog output, $\pm 0.05\%$ of F.S./°C or less - Effects from power supply fluctuation (within rated voltage
- On analog input, $\pm 1~\mu\text{V}/10~\text{V}$ or $\pm 0.01\%$ of F.S./10 V,

- On analog output, $\pm 0.05\%$ of F.S./ $10\,V$ or less

6. Terminal Wiring Diagrams

■ UP350 Standard Type (Model UP350-0□)

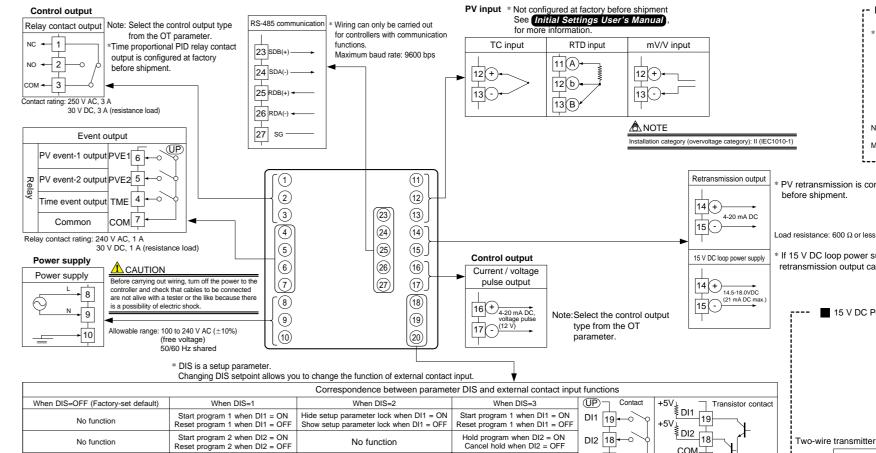
Start program 2 when DI2 = ON

Reset program 2 when DI2 = OFF

Common

No function

Common



No function

Commor

Contact rating: 12 V DC, 10 mA or more * OT is a setup parameter Correspondence between parameter OT and control output types You can change the settings of the OT=1 OT=3 control output. See Initial Settings On-off control Relay output (terminals ①, ②and ③) Time proportional control Time proportional contro User's Manual, for more information

Hold program when DI2 = ON

COM 20

Cancel hold when DI2 = OFF

Common

250 Ω 4-20mA Note: Connecting a 250 Ω resistor to the terminals is Model: X010-250-2 (resistor with M3.5 crimp-on terminal * PV retransmission is configured at factory

- ■ Receiving 4-20 mA DC Current ----

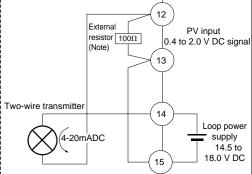
When receiving 4-20 mA DC current signals,

set the PV input type to 1-5 V DC (setpoint "41")

Signals with the Controller

* If 15 V DC loop power supply is used, retransmission output cannot be used

15 V DC Power Supply Wiring to Two-wire Sensor ·



Note: Connecting a 100 Ω resistor to the terminals is optional Model: X010-100-2 (resistor with M3.5 crimp-on terminal lugs)

Program Pattern Setup Charts

See "1. Overview of Program Patterns" and "2. Example of Program Pattern Setup Charts" in the **Programming User's Manual** for details on how to use the setting charts. There are two identical charts shown below because two programs can be registered with the UP350. Fill in the fields with bold-face borders in the order of steps 1 to 10, as shown below. Then, input these setup data items to the UP350.

- 1. Maximum value of PV input range: Setpoint of the setup parameter "Maximum Value of PV Input Range (RH)"
- 2. Minimum value of PV input range: Setpoint of the setup parameter "Minimum Value of PV Input Range (RL)"
- 3. PV input unit: Setpoint of the setup parameter "PV Input Unit (UNIT)"
- 4. Program time unit: Setpoint of the setup parameter "Program Time Unit (TMU)"
- Segment setting method: Setpoint of the setup parameter "Segment Setting Method (SEG.T)"
 Starting target setpoint: Setpoint of the program parameter "Starting Target Setpoint (SSP)"
- 7. Start code: Setpoint of the program parameter "Start Code (STC)"
- 8. Junction code: Setpoint of the program parameter "Junction Code (JC)"
- 9. Target setpoint, Segment time, PV events 1 and 2, and Time event: Setpoint of each program parameter
- 10. Draw the program pattern.

	n name													
Progra	am No.			Dr	ogram tim	o unit /T	MID L	4	\neg	Starting to	argot ooto	oint (CCT) 6	\neg
Progra	am name			_				5	-			OIII (SSF	7	\dashv
Model		UP350) -	56	egment settii	ng metnoa	(SEG.I)	,		Start code			8	\dashv
Serial No.									Junction (code (JC)		٥		
			6		,					10				
			Unit 3		<u> </u>					10 				
Maxim	ium value of	PV input	range (RH) 1		/									
			100%						ļ					
			<u>[</u>		<u>.</u>									
Minimu	um value of l	PV input r	ange (RL) 2				I	i		i	i	I	.i	
			0%											
	Segment	No.			1	2	3	4	5	6	7	8	9	10
	Target se		:P)		'			 	<u> </u>	 	'	 	 	10
	Segment									+	 		 	
			Event type (AL1)								· · · · · ·			
9 🗸	PV eve	nt1 ⊢	Event setpoint (A1)											
)			Event type (AL2)											
	PV eve	nt2 ⊢	Event setpoint (A2)											
			On time of time event (
	Time e	/ent ⊢	Off time of time event (
ς.														
Progra	n name am No. am name				ogram tim			4	7	Starting to		oint (SSF	o) 6 7	\Box
Model		UP350) -	36	gineni setti	ig memou	(3EG.1)			Junction			8	\dashv
Serial	No.									Junction	oue (JC)		Ů.	
			Unit 3		1					10				
					<u> </u>					Ϊ				
Maxim	ium value of	PV input	range (RH) 1 100%											
			10070											
Minimu	um value of l	PV input r	ange (RL) 2											
		·par.	0%		j									
	Segment	No.			1	2	3	4	5	6	7	8	9	10
	Target se	tpoint (S	SP)											
	Segment	time (T	M)											
	PV eve	ent1 ⊦	Event type (AL1)											
9 🕇			Event setpoint (A1)											
	PV eve	ent2 ⊦	Event type (AL2)											
			Event setpoint (A2)											
	Time e	vent l	On time of time event(
			Off time of time event(EOF)	<u> </u>									

IM 05E01D02-01E (2)

User's **Manual** **Models UT350 / UT320 Digital Indicating Controllers User's Manual**

Initial Settings



IM 05D01D02-02E

YOKOGAWA • Yokogawa M&C Corporation

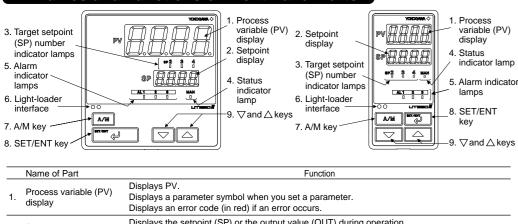
2nd Edition: Jul 1, 2001

This manual describes examples of setting PV input types, control output types, and alarm types. Carrying out settings described herein allows you to perform basic control. Refer to examples of various settings to understand how to set parameters required. Refer to "1. Parameter Map" in **Parameters User's Manual** for an easy to understand explanation of setting various parameters. If you cannot remember how to carry out an operation during setting, press the well key for more than 3 seconds. This brings you to the display (operating display) that appears at power-on.

Contents

- 1. Names and Functions of Front Panel Parts
- 2. Setting PV Input Type (Setting First at Power-on)
- 3. Changing PV Input Type
- 4. Setting Control Output Type 5. Changing Alarm Type
- 6. Description of Multiple Setpoints and PID

1. Names and Functions of Front Panel Parts



		1 7			
2.	Setpoint display	Displays the setpoint (SP) or the output value (OUT) during operation. Displays the set value of parameters on the parameter setting display.			
3.	Target setpoint (SP) number indicator lamps	When the SP number currently used for operation is 2, 3 or 4, the respective SP No. indicator lamp lighits. When the SP number is 1, the lamp does not lighit.			
4.	Status indicator lamp	Is lit in green during manual operation. MAN: Is lit when in manual mode. Blinks during auto-tuning			
5.	Alarm indicator lamps	If any of alarms 1 to 3 occurs, the respective alarm indicator lamp (AL1 to AL3) is lit (in orange).			
6.	Light-loader interface	Interface for an adapter cable used when setting and storing parameters from a PC. This requires an optional parameter setting tool.			
7.	A/M key A/M	Used to switch between the AUTO and MAN modes. Each time you press the key, it switches to the AUTO or MAN mode alternately.			
8.	SET/ENT SET/ENT key	Used to switch or register a parameter. Pressing the key for more than 3 seconds allows you to switch between the operating display and the menu for operating parameter setting display alternately.			
9.	∇and △ keys	Used to change numerical values. On setting displays for various parameters, you can change target setpoints, parameters, and output values (in manual operation). Pressing the ∇ key decreases a numerical value, while pressing the \triangle key causes it to increase. You can hold down a key to gradually increase the speed of change.			

IMPORTANT

The controller automatically returns to the display at the time of power-on (i.e., operating display) if no key is operated for at least one minute

Although only figures of the UT350 front panel are cited in "2. Setting PV Input Type (Setting First at Power-on)," and thereafter, the UT320 is identical to the UT350 in terms of front panel operation.

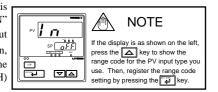
■ Setting of Main Parameters at the Factory before Shipment

Item	Factory-set defaults for standard type controllers	Factory-set defaults for heating/cooling type controllers			
Control output	Time proportional PID relay output (variable)	Heating side: Time proportional PID relay output (variable) Cooling side: Time proportional PID relay output (variable)			
Control action	Reverse action (variable)	Not specified			
PID parameter	P = 5.0%, I = 240 seconds, D = 60 seconds.				
Alarm output	Alarm-1: PV high limit, Alarm-2: PV low limit, Alarm-3: PV high limit				

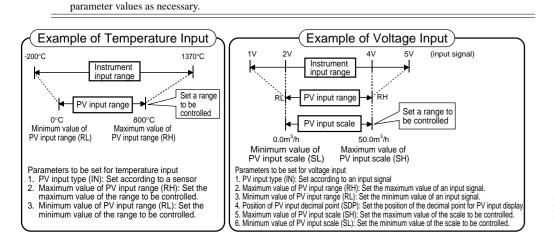
2. Setting PV Input Type (Setting First at Power-on)



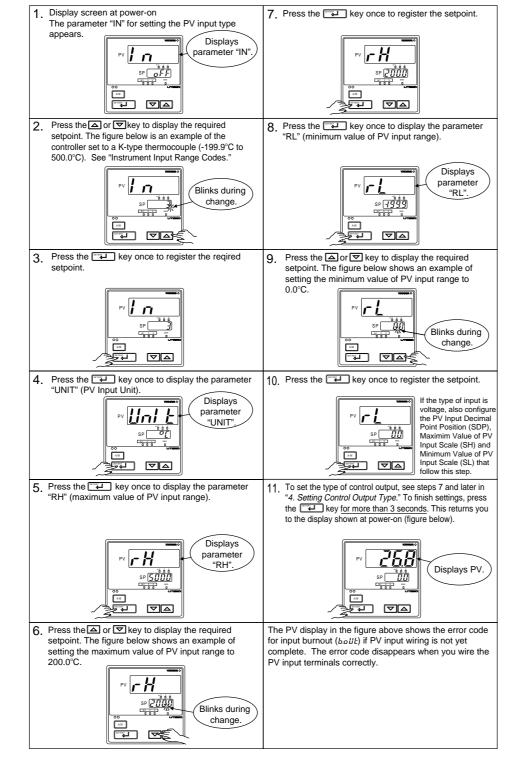
The controller displays the operating display when the power is turned on. However, if PV input type has not been set, "IN" appears. In this case, first use the key to display the input range code to use, then press the key to register it. Then, set the maximum value (RH) and minimum value (RL) of the PV input range (for voltage input, set the maximum value (SH) and minimum value (SL) of the PV input scale).



The controller is configured to the initial value of each parameter at the factory before shipment First check the initial values shown in "2. Lists of Parameters," in Parameters User's Manual and change



The following operating procedure describes an example of setting the controller to a K-type thermocouple (-199.9°C to 500.0°C) and the measurement range of 0.0°C to 200.0°C.



■ Instrument Input Range Codes

Select the unit from the UNIT parameter

			1			
Input	Туре	Instrument Input Range Code	Instrument Input Range	Measurement Accuracy		
Unspecified		OFF	Set the data item PV In type undefined.	nput Type "IN" to the OFF option to leave the PV input		
		1	-200 to 1370°C			
	K	2	-300 to 2500°F -199.9 to 999.9°C			
		3	0 to 2300°F -199.9 to 500.0°C	±0.1% of instrument range ±1 digit for temperatures		
	J	4	-199.9 to 999.9°F -199.9 to 999.9°C	equal to or higher than 0°C ±0.2% of instrument range ±1 digit for temperatures		
	3		-300 to 2300°F -199.9 to 400.0°C	below 0°C		
	Т	5	-300 to 750°F 0.0 to 400.0°C			
		6	-199.9 to 750.0°F			
	В	7	0 to 1800°C 32 to 3300°F	$\pm 0.15\%$ of instrument range ± 1 digit for temperatures equal to or higher than 400°C $\pm 5\%$ of instrument range ± 1 digit for temperatures below 400°C		
	s	8	0 to 1700°C 32 to 3100°F			
	R	9	0 to 1700°C 32 to 3100°F	±0.15% of instrument range ±1 digit		
Thermocouple	N	10	-200 to 1300°C -300 to 2400°F	±0.1% of instrument range ±1 digit ±0.25% of instrument range ±1 digit for temperatures below 0°C		
	E	11	-199.9 to 999.9°C -300 to 1800°F			
	L(DIN)	12	-199.9 to 900.0°C -300 to 1300°F	±0.1% of instrument range ±1 digit for temperatures equal to or higher than 0°C		
	U(DIN)			13	-199.9 to 400.0°C -300 to 750°F	±0.2% of instrument range ±1 digit for temperatures below 0°C
		14	0.0 to 400.0°C -199.9 to 750.0°F			
	w	15	0 to 2300°C 32 to 4200°F	±0.2% of instrument range ±1 digit		
	Platinel 2	16	0 to 1390°C 32 to 2500°F	±0.1% of instrument range ±1 digit		
	PR20-40	17	0 to 1900°C 32 to 3400°F	±0.5% of instrument range ±1 digit for temperatures equal to or higher than 800°C No guarantee of accuracy for temperatures below 800°C		
	W97Re3- W75Re25	18	0 to 2000°C 32 to 3600°F	±0.2% of instrument range ±1 digit		
	ID: 400	30	-199.9 to 500.0°C -199.9 to 999.9°F	±0.1% of instrument range ±1 digit (Note1) (Note2)		
	JPt100	31	-150.0 to 150.0°C -199.9 to 300.0°F	±0.2% of instrument range ±1 digit (Note1)		
RTD		35	-199.9 to 850.0°C -300 to 1560°F			
	Pt100	36	-199.9 to 500.0°C -199.9 to 999.9°F	±0.1% of instrument range ±1 digit (Note1) (Note2)		
		37	-150.0 to 150.0°C -199.9 to 300.0°F	±0.2% of instrument range ±1 digit (Note1)		
Standard	0.4 to 2 V	40	0.400 to 2.000 V			
		-		-		
signal	1 to 5 V	41	1.000 to 5.000 V	±0.1% of instrument range ±1 digit		
	0 to 2 V	50	0.000 to 2.000 V	The read-out range can be scaled between -1999 and		
DC voltage	0 to 10 V	51	0.00 to 10.00 V	19999.		
DC voltage	-10 to 20 mV	55	-10.00 to 20.00 mV	0000.		
•	10 10 20 1111			1		

Performance in the standard operationg condition (at 23±2°C, 55±10%RH, and 50/60Hz power frequency) Note1: The accuracy is ±0.3°C of instrument range ±1 digit for a temperature range from 0°C to 100°C.

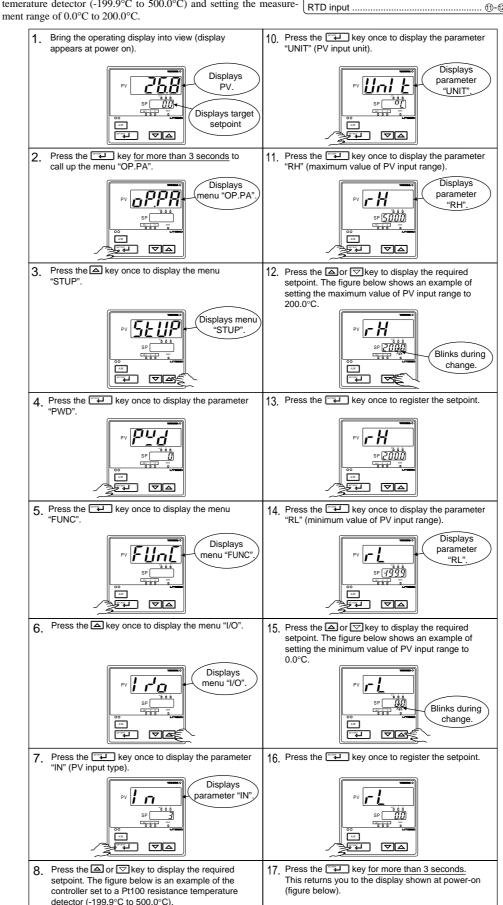
Note2: The accuracy is $\pm 0.5^{\circ}$ C of instrument range ± 1 digit for a temperature range from -100°C to 200°C. To receive a 4-20 mA DC signal, select a standard signal of 1 to 5 V DC and connect it to a 250Ω resistor. This resistor is optional. Model: X010-250-2 (resistor with M3.5 crimp-on terminal lugs)

NOTE

The controller may automatically initialize the registered operating parameter setpoints if any change is made to the data item PV Input Type (IN), Maximum Value of PV Input Range (RH), Minimum Value of PV Input Range (RL), PV Input Decimal Point Position (SDP), Maximum Value of PV Input Scale (SH) or Minimum Value of PV Input Scale (SL). After a change has been made to any of these data items, be sure to verify the registered operating parameter setpoints to ensure that they are correct. If any data item has been changed to its default, set it to a required value.

3. Changing PV Input Type

The following operating procedure describes an example of changing PV input terminal the K-type thermocouple (-199.9°C to 500.0°C) to a Pt100 resistance Thermocouple/mV/V input... temerature detector (-199.9°C to 500.0°C) and setting the measure-. 10-12-13



4. Setting Control Output Type

i n

9. Press the key once to register the setpoint.

i n

Blinks during

_ change.

The following operating procedure describes an example of changing time proportional PID relay output (0: factory-set default) to current output (2).

Control output terminal Values in parentheses are setpoints Time proportional PID relay (0)/on-off(3) output... Current (2)/time proportional PID voltage pulse (1) output... .. 16-17

If the type of input is voltage, also configure the PV Input Decimal Point Position (SDP),

Maximim Value of PV Input Scale (SH) and

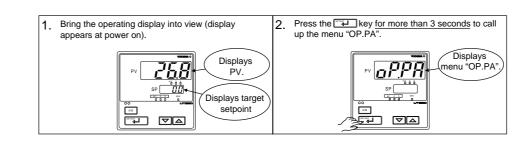
displayed after parameter RL

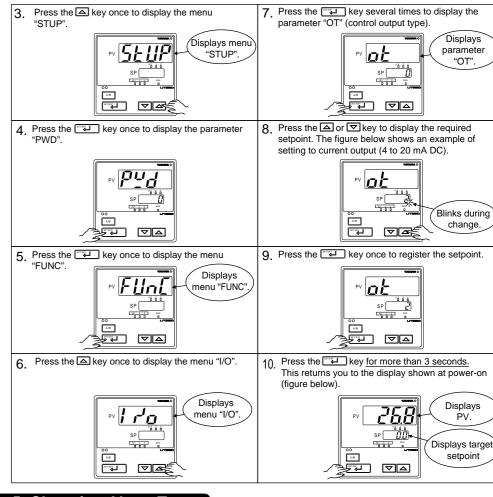
Minimum Value of PV Input Scale (SL) that are

Displays PV.

Displays target setpoint

For details on the heating/cooling control output terminals, see "6. Terminal Wiring Diagrams" in Installation User's Manual



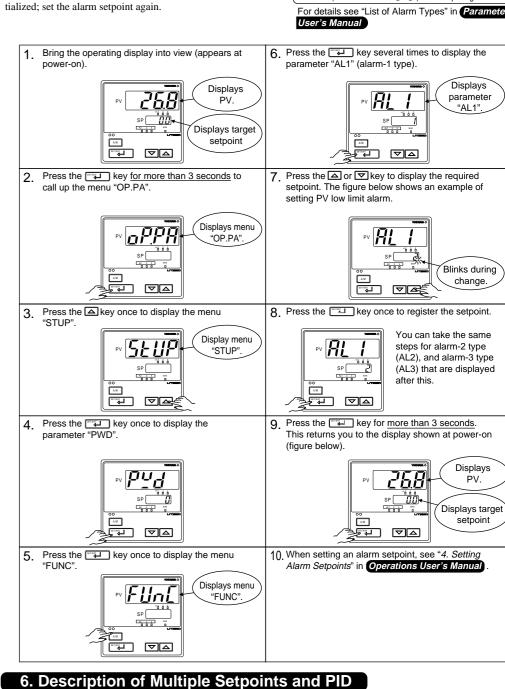


5. Changing Alarm Type

The following operating procedure describes an example of changing alarm-1 (factory-set default: PV high limit alarm) to PV low limit alarm

Alarm-1 (terminal numbers 6-7)......PV input high limit alarm Alarm-2 (terminal numbers ⑤-⑦)......PV input low limit alarm Alarm-3 (terminal numbers ④-⑦)......PV input high limit alarm

When you have changed alarm type, the alarm setpoint will be ini-For details see "List of Alarm Types" in Parameters



The UT350/UT320 controllers have a maximum of four target setpoint (SP) parameters and has PID for each of these setpoints. The following shows the correspondence between the target setpoint numbers (SP.NO), target setpoints (SP), and PID parameters.

For example, if you have set "2" to the target setpoint number (SPNO), the control parameters available are target setpoint (2.SP), proportional band (heating-side proportional band) (2.P), integral time (heating-side integral time) (2.I), derivative time (heating-side derivative time) (2.D), cooling-side proportional band (2.Pc), cooling-side integral time (2.Ic), and cool-

To use multiple target setpoints, see the table below to check the corresponding parameters.

Target setpoint Target		PID parameter							
number (SP.NO)	(SP)	Proportional band (heating-side proportional band)	Integral time (heating-side integral time)	Derivative time (heating-side derivative time)	Cooling-side proportional band	Cooling-side integral time	Cooling-side derivative time		
SP.NO=1	1.SP	1.P	1.l	1.D	1.Pc	1.lc	1.Dc		
SP.NO=2	2.SP	2.P	2.1	2.D	2.Pc	2.lc	2.Dc		
SP.NO=3	3.SP	3.P	3.1	3.D	3.Pc	3.lc	3.Dc		
SP.NO=4	4.SP	4.P	4.1	4.D	4.Pc	4.lc	4.Dc		

User's **Manual** **Models UT350 / UT320 Digital Indicating Controllers User's Manual**



IM 05D01D02-02E

YOKOGAWA • Yokogawa M&C Corporation

2nd Edition: Jul 1, 2001

This manual describes key entries for operating the controller. For operations using external contact inputs, see "6. Terminal Wiring Diagrams" in Installation User's Manual . If you cannot remember how to carry out an operation during setting, press the way key for more than 3 seconds. This brings you to the display (operating display) that appears at

Operations

Contents

- Setting Target Setpoint (SP)
 Performing/Canceling Auto-tuning
- 3. Setting PID Manually 4. Setting Alarm Setpoints
- 5. Selecting Target Setpoint Numbers (SP.NO)
- 6. Switching between Run and Stop
- 7. Switching between AUTO and MAN 8. Manipulating the Control Output in Manual Operation
- 9. Troubleshooting

MOTE

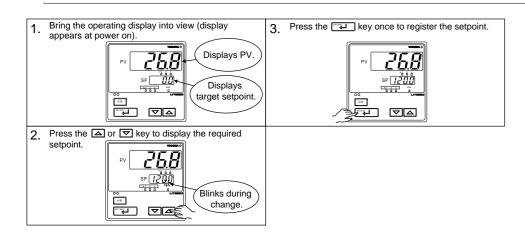
Do not use the instrument generating strong magnetic field such as radio equipment and the like near the controller. This may cause the fluctuation of the PV value.

1. Setting Target Setpoint (SP)

The following operating procedure describes an example of setting 120.0 to a target setpoint. In automatic operation, the controller starts control using set target setpoints.



When the target setpoint is set through communication, the target setpoint cannot be changed by keystroke.



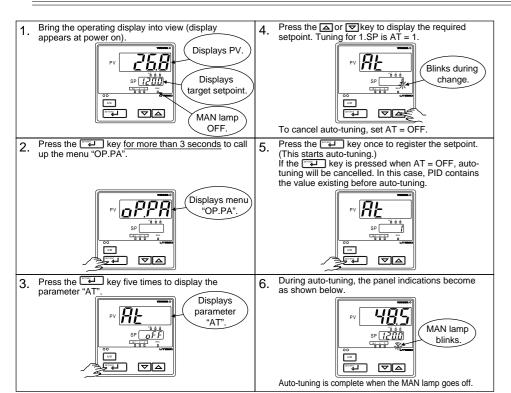
2. Performing/Canceling Auto-tuning

Auto-tuning should be carried out after setting a target setpoint (SP). Make sure the controller is in automatic operation mode (AUTO) and in running state (RUN) before carrying out auto-tuning. See "7. Switching between AUTO and MAN." to change to AUTO and "6. Switching between RUN and STOP," to change to RUN.



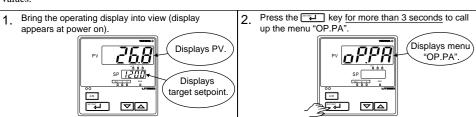
When on-off control is being used, auto-tuning cannot be carried out. Moreover, do not perform auto-tuning when contolling any of following processes.

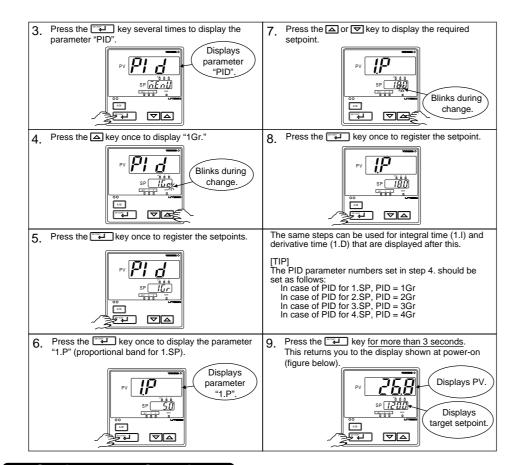
- Control processes with quick response such as flow control or pressure control Processes where even temporary output on/off results in inconvenience Processes where a large output change at control element results in inconvenience
- Processes where variations in PV may exceed an allowable range, adversely affecting product quality



3. Setting PID Manually

If you know the values to be set or if suitable PID constants cannot be obtained by auto-tuning, follow the procedure below

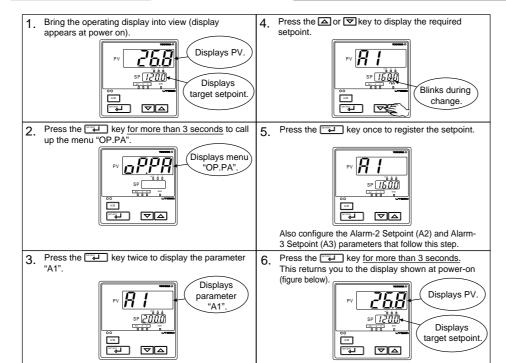




4. Setting Alarm Setpoints

The following operating procedure describes an example of setting Alarm output terminals 160.0 to alarm-1 setpoint. Check alarm type before setting the alarm Alarm-1 (terminal numbers ®-⑦)..... setpoint. To change the type of alarm, see "5. Changing Alarm Type" Initial Setting User's Manual

Alarm-2 (terminal numbers (5)-(7)) PV low limit alarm Alarm-3 (terminal numbers 4-7).....PV high limit alarm



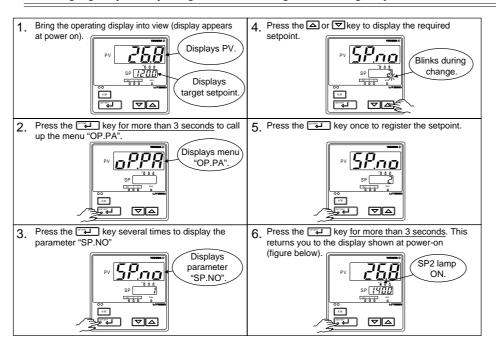
5. Selecting Target Setpoint Numbers (SP.NO)

The following operating procedure describes an example of changing a target setpoint number (SP.NO) from 1 to 2.

MOTE

If a target setpoint number has been switched using contact input, when the contact input is on, that number cannot

When using target setpoint ramp setting function, PV tracking works if the target setpoint number is switched.

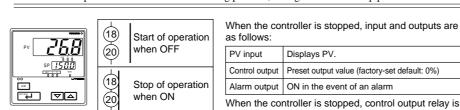


6. Switching between Run and Stop

Switching between the RUN and STOP states can be performed only using external contact input.



When the controller is shipped from the factory, it is configured so that switching between the RUN and STOP states cannot be performed. To make the switching possible, configure the DIS setup parameter as "DIS = 4".

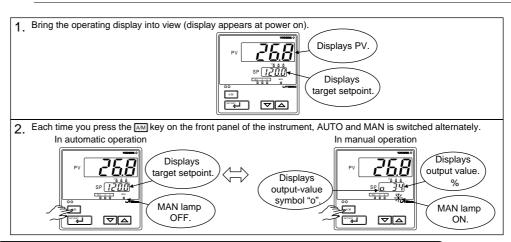


as follows: PV input Displays PV. Control output | Preset output value (factory-set default: 0%) Alarm output ON in the event of an alarm When the controller is stopped, control output relay is

7. Switching between AUTO and MAN



If AUTO and MAN have been switched using contact input, when the contact input is ON, switching between AUTO and MAN cannot be achieved by keystroke.

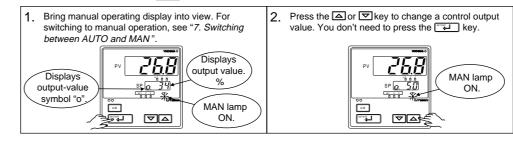


8. Manipulating the Control Output in Manual Operation



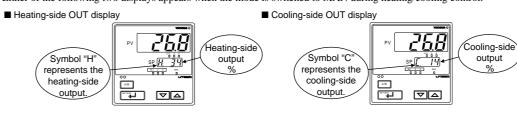
Control output cannot be changed if the controller is stopped. In this case, the preset output value (setup parameter PO) will be output.

A control output value is linked with a display value changed using the 🔻 or 🖾 key. Note that the control output changes as displayed without requiring the key.



■ Manipulating the Control Output during Heating/Cooling Control

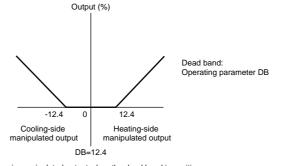
Either of the following two displays appears when the mode is switched to MAN during heating/cooling control.



Controller behavior and control output manipulation when the dead band is positive The following is an example when the DB parameter is set at 12.4%.

If you hold down the \Box key with the heating-side output under manipulation (i.e., cooling-side output C = 0.0%), the heating-side output (H =) decreases. Consequently, both the heating-side and cooling-side outputs change to 0.0%. If you keep the 👿 key held down longer, you enter the state of manipulating the cooling-side output, and its value begins to

Inversely, if you hold down the 🔼 key with the cooling-side output under manipulation (i.e., heating-side output H = 0.0%), the cooling-side output (C =) decreases. Consequently, both the heating-side and cooling-side outputs go to 0.0%. If you keep the 🛕 key held down longer, you enter the state of manipulating the heating-side output, and its value begins to



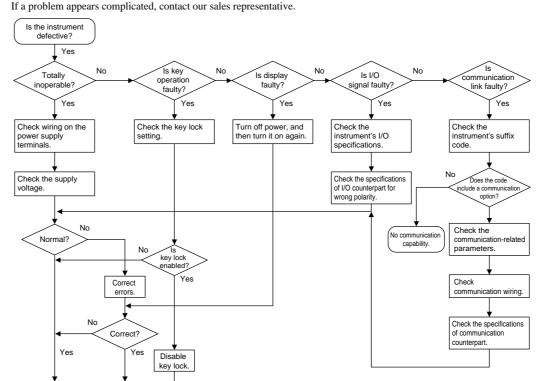
Change in manipulated output when the dead band is positive

9. Troubleshooting

■ Troubleshooting Flow

(Ask the vendor for repair.) (Find the cause

If the operating display does not appear after turning on the controller's power, follow the measures in the procedure below.



IMPORTANT

Take note of the parameter settings when asking the vendor for repair.

■ Errors at Power On

Error indication Description

The following table shows errors that may be detected by the fault diagnosis function when the power is turned on.

(on PV display unit)	of error	PV	output	output	output	cation	Remedy
<i>E □ □ □ □</i> (E000)	Faulty RAM	Name			00/!	04	
<i>E 🗓 🖟</i> (E001)	Faulty ROM	None	0% or less or OFF	OFF	0% or less	Stopped	Faulty
<i>E002</i> (E002)	System data error	0%	0. 0		0%		Contact us
PV decimal point blinks.	Faulty calibration value	Normal action (out of accuracy)	rmal action Normal action out of Normal action out		Normal action	for repair.	
<i>E Ч₿₿</i> (E400)	Parameter error	0%	Preset value output	OFF	0%		Check and set the parameters, as they have been set to the limited values.

Control Alarm Retransmission Communi-

■ Possible Errors during Operation

The following shows possible errors occurring during operations

Error indication (on PV display unit)	Description of error	PV	Control output	Alarm output	Retransmis- sion output	Commu- nication	Remedy
Displays "RJC" and PV alternately	RJC error	Measured with RJC=OFF	Normal action	Normal action	Normal action	Normal action	Faulty Contact us for repair.
PV value blinks.	EEPROM error	Normal action	Normal action	Normal action	Normal action	Normal action	Faulty Contact us for repair.
<i>E ∄⊞</i> (E300)	A/DC error	105%	Preset value output	Normal action	Normal action	Normal action	
<i>⊾.a.U.೬</i> (B.OUT)	PV burnout error	Dependent on the BSL parameter Up-scale: 105% Down-scale: -5%	Preset value output	Normal action	Normal action	Normal action	Check wires and sensor.
០ម៉ូក (OVER) or - ០ម៉ូក(-OVER)		-5% or 105%	Normal action	Normal action	Normal action	Normal action	Check process.
<i>E 2∏∏</i> (E200)	Auto-tuning failure (Time-out)	Normal action	Normal action	Normal action	Normal action	Normal action	Check process. Press any key to erase error indication.
SP decimal point blinks. (on setpoint display unit)	Faulty communi- cation line	Normal action	Normal action	Normal action	Normal action	Normal action	Check wires and communication parameters and make resetting. Recovery at normal receipt
All indications off	Runaway (due to defective power or noise)	None	0% or less or OFF	OFF	0% or less	Stopped	Faulty if power off/on does not reset start the unit. Contact us for repair.
All indications off	Power off	None	0%	OFF	0%	Stopped	Check for abnormal power

■ If a Power Failure Occurs during Operation

Momentary power failures shorter than 20 ms

The controller is not affected at all and continues normal operation.

Power failures of 20 ms or longer

- The alarm function of the controller continues to work normally. (Alarms with the stand-by feature temporarily return
- · Setting parameters that have already been configured retain their settings.
- Auto-tuning is cancelled.
- · After recovery from a power failure, control action resumes in the same mode as the one before the occurrence of the power failure. The control output begins with the preset output value.

■ Troubleshooting When the Controller Fails to Operate Correctly

If your control tasks are not successful, check the preset parameters and controller wiring before concluding the controller to be defective. The following show some examples of troubleshooting you should refer to in order to avoid the possibility of other problems.

The controller does not show the correct measured input (PV).

• The UT350/UT320 controllers have a universal input.

The type of PV input can be set/changed using the parameter "IN". At this point, the controller must be wired correctly according to the selected type of PV input. Check the wiring first if the controller fails to show the correct PV. To do this, refer to Initial Settings User's Manual

With the parameters "RH", "RL", "SDP", "SH" and "SL", it is possible to scale the input signal and change its number of decimal places. Also check that these parameters are configured correctly.

The controller does not provide any control output or the control output does not change at all.

• The UT350/UT320 controllers have a universal output.

The type of control output can be set/changed using the parameter "OT" At this point, the controller must be wired correctly according to the selected type of control output. Check the wiring first if the controller provides no control output. To do this, refer to "6. Terminal Wiring Diagrams," in Installation

With the parameters "OH" and "OL", it is possible to set/change the high and low limits of control output. The control output may not change at all, however, because of restrictions on these parameters. Also check the restrictions on these

• The control output can only be changed when the controller is in the MAN mode.

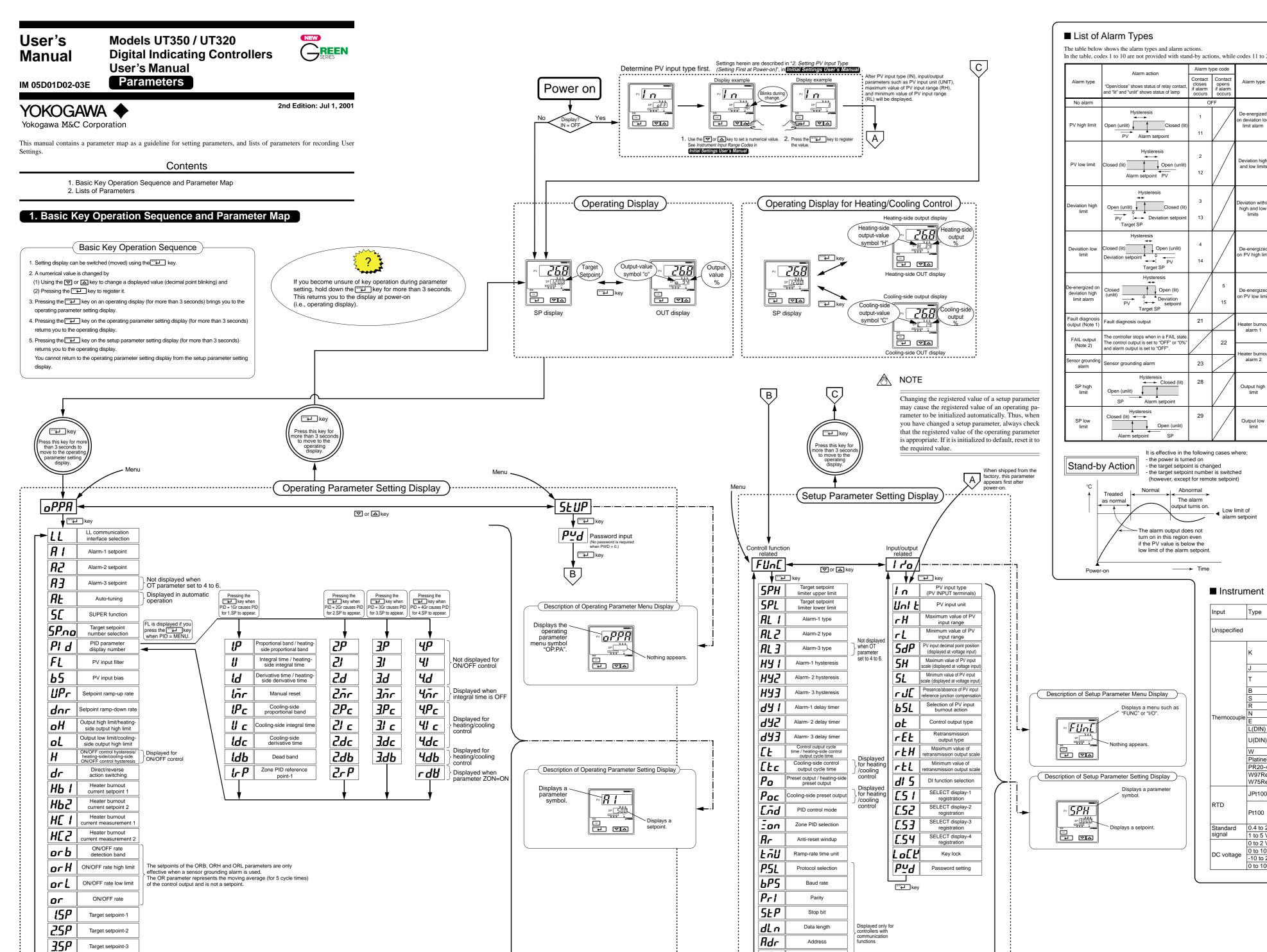
If the MAN lamp is off (i.e., the controller is in the AUTO mode), you cannot change the control output using key

• The control output does not change soon after the target setpoint SP has been

• If this happens, check the setpoint of the parameter "C.MD". In cases where fixed-point control is selected as the PID control mode (C.MD = 1), tracking based on the I-term works to prevent the control output from changing suddenly even if the target setpoint SP is varied.

The control output therefore may appear to be working incorrectly at first; however it gradually adapts itself to the new

IM 05D01D02-02E (2)



To switch the parameter display, press the key.

Target setpoint-4

≝≝≝ key

r P.Ł

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₩ey

Minimum response time

is not to be set.

In the table, codes 1 to 10 are not provided with stand-by actions, while codes 11 to 20 are provided with stand-by actions

	Alarm action	Alarm ty	pe code		Alarm action	Alarm ty	pe code
Alarm type	"Open/close" shows status of relay contact, and "lit" and "unlit" shows status of lamp	Contact closes if alarm occurs	Contact opens if alarm occurs	Alarm type	"Open/close" shows status of relay contact, and "lit" and "unlit" shows status of lamp	Contact closes if alarm occurs	Contact opens if alarm occurs
No alarm		0	FF		Hysteresis	/	
PV high limit	Open (unlit) Closed (lit)	1 11		De-energized on deviation low limit alarm	Open (lit) Deviation Setpoint Target SP Open (lit) PV Closed (unlit) PV		6 16
PV low limit	Closed (lit) Open (unlit) Alarm setpoint PV	2		Deviation high and low limits	Hysteresis Hysteresis Closed Open (lit) Deviation setpoint PV Target SP	7	
Deviation high limit	Open (unlit) Closed (lit) PV Deviation setpoint Target SP	3		Deviation within high and low limits	Hysteresis Closed Hysteresis Open (unlit) Open (unlit) Deviation setpoint Target SP	8	
Deviation low limit	Closed (lit) Open (unlit) Deviation setpoint PV Target SP	4		De-energized on PV high limit	Closed (unlit) Open (lit) PV Alarm setpoint		9
De-energized on deviation high limit alarm	Closed (unlit) Open (lit) PV Deviation setpoint Target SP		5 15	De-energized on PV low limit	Open (lit) Closed (unlit) Alarm setpoint PV		10 20
Fault diagnosis output (Note 1)	Fault diagnosis output	21		Heater burnout		24	
FAIL output (Note 2)	The controller stops when in a FAIL state. The control output is set to "OFF" or "0%" and alarm output is set to "OFF".		22	Heater burnout	Heater burnout alarms 1 and 2		
Sensor grounding alarm	Sensor grounding alarm	23		alarm 2		25	
SP high limit	Open (unlit) SP Hysteresis Closed (lit) Alarm setpoint	28		Output high limit	Open (unlit) Output value Hysteresis Closed (lit) Alarm setpoint	30	
SP low limit	Hysteresis Closed (iit) Open (unlit) Alarm setpoint SP	29		Output low limit	Hysteresis Closed (lit) Open (unlit) Alarm setpoint Output value	31	

Note 1: The fault diagnosis output turns on in case of input burnout, A/D converter failure, or reference junction compensation (RJC) failure. The control output in case of input burnout or A/D converter failure is set to the value of the PO (Preset Output Value) setup parameter. In case of RJC failure, the controller continues control under the condition of "RJC = OFF".

Note 2: The FAIL output is on during normal operation and turns off in case of failure

■ Instrument Input Range Codes

Input	Туре	Instrument Input Range Code	Input Range
Jnspecified K J T B S R N E L(DIN) U(DIN) W Platinel PR20-4i W97Re:			Set the data item PV Input Typ
Unspecified		OFF	"IN" to the OFF option to leave
•			the PV input type undefined.
Unspecified Thermocouple RTD Standard signal		1	-200 to 1370°C
	K	2	-199.9 to 999.9°C
		3	-199.9 to 500.0°C
	J	4	-199.9 to 999.9°C
	т	5	-199.9 to 400.0°C
Thermocouple		6	0.0 to 400.0°C
	В	7	0 to 1800°C
	S	8	0 to 1700°C
	R	9	0 to 1700°C
		10	-200 to 1300°C
	E	11	-199.9 to 999.9°C
	L(DIN)	12	-199.9 to 900.0°C
	U(DIN)	13	-199.9 to 400.0°C
		14	0.0 to 400.0°C
	W	15	0 to 2300°C
	Platinel 2	16	0 to 1390°C
	PR20-40	17	0 to 1900°C
	W97Re3- W75Re25	18	0 to 2000°C
	ID:400	30	-199.9 to 500.0°C
	JPt100	31	-150.0 to 150.0°C
RTD		35	-199.9 to 640.0°C
	Pt100	36	-199.9 to 500.0°C
		37	-150.0 to 150.0°C
Standard	0.4 to 2 V	40	0.400 to 2.000V
signal	1 to 5 V	41	1.000 to 5.000V
_	0 to 2 V	50	0.000 to 2.000V
DC valtage	0 to 10 V	51	0.00 to 10.00V
DC voitage	-10 to 20 mV	55	-10.00 to 20.00mV
	0 to 100 mV	56	0.0 to 100.0mV

2. Lists of Parameters

■ Operating Parameters

Parameters relating to PV or setpoints should all be set in real numbers. For example, use temperature values to define target setpoints and alarm setpoints for temperature input.

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
L L	LL communication interface selection	OFF: Communication is carried out via the RS485 communication terminals. ON: Communication is carried out via the light-loader adapter.	with communication : OFF without communication : ON	ı	_
A ,	Alarm 1-setpoint	PV alarm / SP alarm: -100.0 to 100.0% of PV input range Deviation alarm: -100.0 to 100.0% of PV input	PV high limit/SP high limit alarm: 100.0% of PV input range Deviation alarm: 0.0% of PV		_
A2 (A2)	Alarm 2-setpoint	range span Output alarm: -5.0 to 105.0% An alarm common to the 1.SP to 4.SP parameters.	input range span Other PV/SP low limit alarm: 0.0% of PV input range		_
A3	Alarm 3-setpoint		Output high limit alarm: 100.0% Output low limit alarm: 0.0%		_
AL	Auto-tuning	OFF: No auto-tuning 1: Auto-tuning for 1.SP 2: Auto-tuning for 2.SP - 3: Auto-tuning for 3.SP 4: Auto-tuning for 4.SP AUTO: Performs auto-tuning to all groups 1 to 4.	OFF		_
5 [(SC)	"Super" function	OFF: Disable 1: Overshoot suppressing function Suppresses overshoots generated by abrupt cha in the target setpoint or by disturbances. 2: Hunting suppressing function (Stable mode) Suitable to stabilize the state of control when the varies greatly, or the target setpoint is changed. Enables to answer the wider characteristic chang- compared with Response mode. 3: Hunting suppressing function (Response mode) Enables quick follow-up and short converging tin PV for the changed target setpoint. Note: Use "SUPER" function (SC) 2 or 3 in PID con "SUPER" function 2 or 3 is not available in the fo 1) ON/OFF control 2) P control (control for proportional band and det 4) Heating/cooling control Do not use hunting suppressing function when cont with response such as flow or pressure control.	pes ne of trol or PI control. Illowing control:		Ref.2.1(5)
5P.no (SP.NO)	Target setpoint number selection	Uses target setpoint via communication Selects target setpoint 1 (1.SP). Selects target setpoint 2 (2.SP). Selects target setpoint 3 (3.SP). Selects target setpoint 4 (4.SP).	1		Ref.4.1(1
Pi d	PID parameter display number	MENU: Move to FL parameter display 1Gr to 4Gr: Display of each PID parameter	MENU		
FL (FL)	PV input filter	OFF, 1 to 120 second. Used when the PV input fluctuates.	OFF		
65 (BS)	PV input bias	-100.0% to 100.0% of PV input range span Used to correct the PV input range.	0.0% of PV input range span		Ref.1.1(1)
UPr (UPR)	Setpoint ramp-up-rate	OFF 0.0% + 1 digit of PV input range span to 100.0% of PV input range span	OFF		
dnr (DNR)	Setpoint ramp-down- rate	Set ramp-up-rate or ramp-down-rate per hour or minute. Sets unit in ramp-rate-time unit (TMU).	OFF		Ref.4.1(4)
oł oł	Output high limit Heating-side output high limit (in heating/cooling control) Output low limit Cooling-side output high limit	-5.0 to 105.0% Heating-side limiter in heating/cooling control: 0.0 to 105.0% (OL < OH) -5.0 to 105.0% Cooling-side limiter in heating/cooling control: 0.0 to	100% Heating/cooling control: 100.0% 0.0% Heating/cooling control:		Ref.2.1(3)
H (H)	(in heating/cooling control) ON/OFF control hysteresis Heating-side/cooling-side ON/OFF control hysteresis (in heating/cooling control)	105.0% (OL < OH) In ON/OFF control: 0.0 to 100.0% of PV input range span In heating/cooling control: 0.0 to 10.0%	100.0% ON/OFF control: 0.5% of PV input range span Heating/cooling control: 0.5%		_
dr (DR)	Direct/reverse action switching	0: reverse action, 1: direct action Control output 100% Reverse action Ow Direct action Deviation (PV-SP)	0		Ref.2.1(1)
Hb !	Heater burnout current setpoint 1	OFF, or 1 to 50 A	OFF		
H62 H[1 H[2	Heater burnout current setpoint 2 Heater burnout current measurement 1 Heater burnout current measurement 2	These are not setpoints.	The current value of the heater burnout detector is shown on the display of the HC1 or HC2 parameter.		Ref.3.3(5
orb	ON/OFF rate detection band	0.0 to 100.0% of PV input range span	1.0% of PV input range		
ORB)	ON/OFF rate high limit	ORL + 1 digit to 105.0%	span 100.0%		
(ORH)	ON/OFF rate low limit	-5.0% to ORH - 1 digit	0.0%		Ref.3.3(4)
(ORL) (OR) (OR) (1.SP)	ON/OFF rate Target setpoint-1	This is not a setpoint. 0.0 to 100.0% of PV input range However, between target setpoint limiter lower limit (SPL) and upper limit (SPH).	The moving average (for 5 cycle times) of the control output is shown. 0.0% of PV input range		
2.SP)	Target setpoint-2 Target setpoint-3				Ref.4.1(1)
3.3F (3.SP)	Target setpoint-4				
			ı	1	1

PID-related Parameters

The following parameters are displayed when "1Gr" is set to PID parameter display number (PID). In this case, the corresponding target setpoint is 1.SP

moint 2 to 4 gat "2C2" ("2C2" on "4C2" to DID. The relevant monometers will then be displayed

To set PID corr	esponding to target setpoint 2	2 to 4, set "2Gr", "3Gr", or "4Gr" to PID. T	he relevant parameters will then	be displayed	
Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
!P	Proportional band/Heating- side proportional band (in heating/cooling control)	0.1 to 999.9% In heating/cooling control: 0.0 to 999.9% (heating-side ON/OFF control applies when 0.0)	5.0%		
(1.1)	Integral time Heating-side integral time (in heating/cooling control)	OFF, 1 to 6000 second	240 second		
(1.D)	Derivative time Heating-side derivative time (in heating/cooling control)	OFF, 1 to 6000 second	60 second		
(1.MR)	Manual reset	-5.0 to 105.0% (enabled when integral time "1.1" is OFF) The manual reset value equals the output value when PV = SP is true. For example, if the manual reset value is 50%, the output value is 50% when PV = SP becomes true.	50.0%		Ref.4.1(1)
!Pc	Cooling-side proportional band	0.0 to 999.9% (Cooling-side ON/OFF control applies when 0.0)	5.0%		
(1.lc)	Cooling-side integral time	OFF, 1 to 6000 second	240 second		

The "User Setting" column in the table below is provided for the customer to record setpoints.

Fig. The "Target Item in CD-ROM" column in the table below provides references from User's Manual (Reference) (CD-ROM Version) which describes items in more detail and items that are not contained in this manual.

(1.Dc)	Cooling-side derivative time	OFF, 1 to 6000 second	60 second	
(1.DB)	Deadband	-100.0 to 50.0% In heating/cooling control, a reagion where both of the heating- and cooling-side outputs are presented, or none of them is presented, can be set.	3.0%	Ref.4.1(1)
(1.RP)	Zone PID reference point-1	0.0 to 100.0% of PV input range. Note that 1.RP \leq 2.RP.	100% value of PV input range	

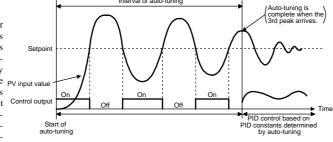
Refer to the table below for recording setpoints when two sets or more of PID parameters are used.

Parameter	n=2	n=3	n=4
n.P			
n.l			
n.D			
n.MR			
n.Pc			
n.lc			
n.Dc			
n.DB			
n.RP		None	None

r db	Reference deviation	OFF, 0.0 to100.0% of PV input range span Used to select PID constants according to a deviation from the setpoint. The 4th group of PID constants is used when the controller fails to keep track of the deviation.	OFF	F	Ref.4.1(1)

Auto-tuning

Auto-tuning is a function with which the controller automatically measures the process characteristics to automatically set the optimum PID constants. This function does not work when the controller is performing on-off control. The UT350/UT320 employ the "Limit Cycle Method." As shown in the figure PV input vali on the right, the controller temporarily changes its control output in a step-waveform manner. Then, it Control output calculates the optimum proportional band (P), integral time (I) and derivative time (D) from the result-



ing response to set them in their respective parameters. If the Output High Limit (OH) and Output Low Limit (OL) parameters are already configured, the control output turns on and off only between the output's high and low limits during auto-tuning

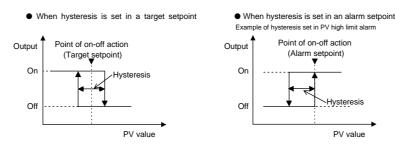
● Auto-tuning Using Zone PID (see "■ PID Switching (Zone PID)" later in this manual)

Setting of AT Parameter	Auto-tuned Setpoint	Remarks
OFF	-	Auto-tuning is turned off (disabled).
1	The setpoints when auto- tuning is started	Determines the values of 1.P, 1.I and 1.D parameters by auto-tuning.
2		Determines the values of 2.P, 2.I and 2.D parameters by auto-tuning.
3		Determines the values of 3.P, 3.I and 3.D parameters by auto-tuning.
4		Determines the values of 4.P, 4.I and 4.D parameters by auto-tuning.
AUTO	Median value of each zone width	Determines the values of all PID parameters in use by auto-tuning.

The AT parameter settings numbered 1 to 4 in the table above are dependent on how many zones have been set. For example, if you have set $two\ zones, you\ can\ use\ AT\ parameter\ settings\ 1,\ 2\ and\ 3.$

■ Hysteresis (for Target Setpoints (On-Off Control) and Alarm Setpoints)

Hysteresis can be set in on-off control setpoints and alarm setpoints as well. With the hysteresis settings, it is possible to prevent relays from



■ Target Setpoint Ramp Setting Function

Use this function to prevent the target setpoint from changing suddenly. The ramp setting function works when:

- [1] the target setpoint is changed (example: change in "1.SP" from 100° C to 150° C);
- [2] the target setpoint number is switched (example: switch from "1.SP" to "3.SP");
- [3] the power is turned on or the controller is recovered from power failure; [4] a change is made from manual operation to automatic operation; or

If the target setpoint before switching is smaller than the target setpoint $_{2.SP=640^{\circ}C}$ after switching, the controller operates according to the settings of the Setpoint Ramp UP (UPR) and Ramp Time Unit (TMU) parameters. If the target setpoint before switching is greater than the target setpoint after switch-Down (DNR) and Ramp Time Unit (TMU) parameters. The figure on the right shows an example when the Target Setpoint Number (SP.NO) parameter is switched. The 1.SP and 2.SP parameters are set to 500°C and 640°C, respectively. Thus, there is a temperature difference of 140°C between the

example, the UPR parameter is 70°C and the TMU parameter is 1 minute.

[5] a change is made from the STOP state to the RUN state.

2.SP 1.SP (140°C/2 min) rate of temperature change 2-minute interval of Switching from 1.SP to 2.SP parameter 1.SP and 2.SP parameters. This example shows how the temperature is changed by as much as this temperature difference over a period of two minutes. In this ANOTE

When using target setpoint ramp setting function, PV tracking works in case of the above conditions [2] to [5].

PID constants

- Operated with 2nd group of

➤ Operated with 1st group of

Zone 2:

■ PID Switching (Zone PID)

Using a zone PID, you can automatically switch between groups of PID constants according to the temperature zone. You can set a maximum of three temperature zones. input range (RH) Operated with 3rd group of

[1] Set the Zone PID Selection (ZON) parameter to [2] Define a reference point. Reference point 2 When using two zones, define only reference point 1 (1.RP) between the minimum and maximum values of the PV input range. When using three zones, define reference points 1 and 2 (1.RP and 2.RP) in the same way as noted above. → PID constants

Note: Set the maximum and minimum values, as close as possible to those of the actual range to be controlled, in the Maximum Value of PV Input Range (RH) and Minimum Value of PV Input Range (RL) parameters. Otherwise, the controller may fail to determine the optimum values when autotuning is carried out.

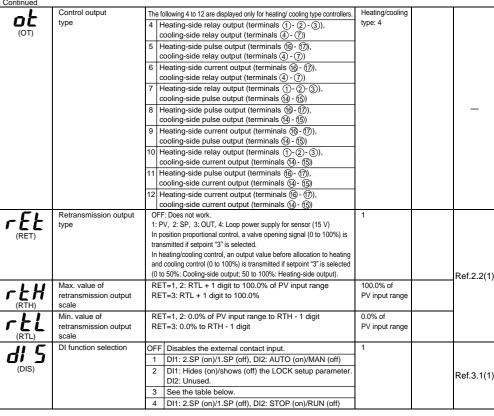
■ Setup Parameters

Control Function-related Parameters

Parameter	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Iter
Symbol	Target setpoint	0.0 to 100.0% of PV input range where, SPL < SPH	100.0% of		in CD-RO
SPH)	limiter upper limit Target setpoint	Places a limit on the range within which the target setpoint is changed.	PV input range 0.0% of		_
JPL (SPL)	limiter lower limit		PV input range		_
AL (AL1)	Alarm-1 type	OFF, 1 to 25, 28 to 31 1: PV high limit (energized, no stand-by action) 2: PV low limit (energized, no stand-by action)	1		
AL2	Alarm-2 type	3: Deviation high limit (energized, no stand-by action) 4: Deviation low limit (energized, no stand-by action) 5: Deviation high limit (de-energized, no stand-by action) 6: Deviation low limit (de-energized, no stand-by action)	2		Ref.3.3(
AL3	Alarm-3 type	These Alarm Type parameters are common to the parameters 1.SP to 4.SP. See "List of Alarm Types" on the back for other alarm types.	1		
HY!	Alarm-1 hysteresis	0.0 to 100.0% of PV input range span Output alarm: 0.0 to 100.0% Hysteresis for PV high limit alarm	0.5% of PV input range span Output alarm:		
HY2)	Alarm-2 hysteresis	Output Point of on-off action (Alarm setpoint)	0.5%		Ref.3.3(
HY3	Alarm-3 hysteresis	Off			
dy i	Alarm-1 delay timer	An alarm is output when the delay timer expires after the alarm setpoint is reached. 0.00 to 99.59 (min, sec.) (enabled when alarm-1 type "AL1" is 1 to 20 or 28 to 31) Alarm setpoint Delay timer Delay timer Hysteresis	0.00		_
6472 (DY2)	Alarm-2 delay timer	0.00 to 99.59 (min, sec.) (enabled when alarm-2 type "AL2" is 1 to 20 or 28 to 31)			
443	Alarm-3 delay timer	0.00 to 99.59 (min, sec.) (enabled when alarm-3 type "AL3" is 1 to 20 or 28 to 31)			
[F	Control output cycle time Heating-side control output cycle time (in heating/cooling control)	1 to 1000 second	30 second		Ref.3.3(
	Cooling-side control output cycle time	1 to 1000 second	30 second		_
Po	Preset output/Heating-side preset output (in heating/cooling control)	-5.0 to 105.0% In heating/cooling control: Heating side 0.0 to 105.0% In Stop mode, fixed control output can be generated.	0.0%		Ref.2.1(
POC (POc)	Cooling-side preset output	0.0 to 105.0% In Stop mode, cooling-side fixed control output can be generated.	0.0%		,
	PID control mode	Standard PID control (with output bump at SP change) Fixed point control (without output bump at SP change) Choose "fixed point control" when controlling pressure or flow rate.	0		Ref.2.1(
Zon (ZON)	Zone PID selection	OFF: SP selection ON: Zone PID	ON		Ref.4.1(
A r	Anti-reset windup (Excess integration prevention)	AUTO (0), 50.0 to 200.0% Used when the control output travels up to 100% or down to 0% and stays at this point. The larger SP, the sooner PID computation (integral computation) stops.	AUTO		Ref.2.1(
L MU)	Ramp-rate time unit setting	0: hour, 1: minute Time unit of setpoint ramp-up (UPR) and setpoint ramp-down (DNR)	0		Ref.4.1(
P.5L (P.SL)	Protocol selection	D: PC link communication PC link communication (with sum check) Ladder communication Coordinated master station MODBUS (ASCII) Coordinated slave station (loop-1 mode) Coordinated slave station (loop-2 mode)	0		
bP5	Baud rate	0: 600, 1: 1200, 2: 2400, 3: 4800, 4: 9600 (bps)	4		
Pr	Parity	0: None 1: Even 2: Odd	1		commur
SLP (STP)	Stop bit	1, 2	1		function
dL _(DLN)	Data length	7, 8: Fixed at 7, when the P.SL parameter is set to MODBUS (ASCII). Fixed at 8, when the P.SL parameter is set to MODBUS (RTU) or Ladder Communication.	8		
Adr	Address	1 to 99 However, the maximum number of stations connectable is 31.	1		
- P.Ł	Minimum response time	0 to 10 (× 10 ms)	0		
FSF		pears, press the SET/ENT key to return to the FUNC menu. e setpoint of the TEST parameter, otherwise the controller wi	ll he disabled		

Input-/Output-related Parameters

Parameter Symbol	Name of Parameter	Setting Range and Description	Initial Value	User Setting	Target Item in CD-ROM
l n	PV input type (PV INPUT terminals) 11 - 12 - 13terminals	OFF, 1 to 18, 30, 31, 35 to 37, 40, 41, 50, 51, 55, 56 See Instrument Input Range Codes in <i>Initial Settings</i> User's Manual.	OFF		_
UNIT) E	PV input unit	°C: degree Celsius °F: Fahrenheit (This parameter is not shown for voltage input.)	°C		_
rH _(RH)	Max. value of PV input range	Set the PV input range, however RL < RH -Temperature input Set the range of temperature that is actually controlled.	Max. value of instrument input range		_
r L	Min. value of PV input range	Voltage input Set the range of a voltage signal that is applied. The scale across which the voltage signal is actually controlled should be set using the parameters Maximum Value of PV Input Scale (SH) and Minimum Value of PV Input Scale (SL).	Min. value of instrument input range		_
5dP	PV input decimal point position (displayed at voltage input)	0 to 3 Set the position of the decimal point of voltage-mode PV input. 0: No decimal place 1: One decimal place 2, 3: Two, three decimal places	1		_
5 H _(SH)	Max. value of PV input scale (displayed at voltage input)	-1999 to 9999, however SL < SH Set the read-out scale of voltage-mode PV input.	100.0		_
5 <u>L</u>	Min. value of PV input scale (displayed at voltage input)		0.0		_
r <u>II</u>	Presence/absence of PV input reference junction compensation	OFF, ON	ON		_
65L	Selection of PV input burnout action	OFF 1: Up scale 2: Down scale	1		_
ot (OT)	Control output type	D Time proportional PID relay contact output (terminals ①-②-③) Time proportional PID voltage pulse output (terminals (6-⑦)) Current output (terminals (6-⑦)) ON/OFF control relay contact output (terminals (1-②-③))	0		_



O SP Selection when DIS = 3 is set

	DI1	DI2
1.SP	OFF	OFF
2.SP	ON	OFF
3.SP	OFF	ON
4.SP	ON	ON

[[[]	SELECT display-1	OFF, 201 to 1015	OFF		
L.J	registration	Select the desired parameter from among the operating and setup			
(C.S1)		parameters, then register the number (D register No.) accompanying that			
$\Gamma\Gamma$	SELECT display-2	parameter.			
i '\r'	registration	For example, registering "231" for C.S1 allows you to change alarm-1			
(C.S2)	Ŭ	setpoint in operating display.			
	SELECT display-3	Numbers for registering alarm SP parameter for operating display:			Ref.6.1(1)
	registration	Alarm-1 setpoint: 231 Alarm-2 setpoint: 232			
(C.S3)	registration	Alarm-3 setpoint: 233			
(0.55)		Above numbers are alarm setpoint parameters for target setpoint-1 (1.SP).			
rcu	SELECT display-4	See User's Manual (Reference) (CD-ROM).			
し.ファ	registration	Coo Cool o Mariaa (Noronoco) (CD Nom).			
(C.S4)					
1 _ T U	Key lock	OFF: No key lock	OFF		
LOLE		Change to any parameter prohibited			
(LOCK)		Prohibits any operating parameter or setup parameter from being changed.			
		The setpoint of the LOCK parameter itself can be changed, however.			
		Change to and display of operating parameters prohibited			Dof 7 1(2)
					Ref.7.1(2)
		Turns off the display for setting operating parameters, thus			
		prohibiting any change to the parameter settings.			
		(Hold down the SET/ENT key for more than 3 seconds to show the			
		password check display.)			
		3: Disables the A/M key on the instrument's front panel.			
	Password setting	0: Password not set	0		
1720		1 to 9999			Ref.7.1(1)
(PWD)				1	·

■ Useful Operating Displays (SELECT Display)

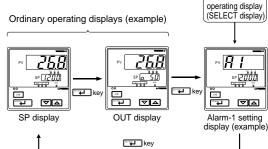
Registering frequently changed parameters in the SELECT display after ordinary operating displays will allow you to change settings easily. A maximum of four displays can be registered.

In heating/cooling control, the controller outputs the result of computation after splitting it into heating-purpose and cooling-purpose signals.

Set the parameter numbers (D register numbers) you wish to register
Ordinary operating displays (example) for setup parameters C.S1 to C.S4.

Alarm parameter for target setpoint-1	Registration number
Alarm-1 setpoint parameter	231
Alarm-2 setpoint parameter	232
Alarm-3 setpoint parameter	233

For any registration number other than those above, see User's Manual $\,$ (Reference) (CD-ROM version).



0% to 100%

Useful

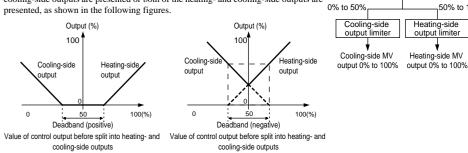
■ Heating/Cooling Control (for a Heating/Cooling Controller Only)

In addition, the controller can perform PID control or on-off control on the heating and cooling sides separately. When performing on-off control, set the proportional band to "0". The controller splits the result of computation (0 to 100%) into heating-side and cool-

ing-side signals, as described below. • 0% to 50% of the computation result is presented as a 0% to 100% cooling-side

• 50% to 100% of the computation result is presented as a 0% to 100% heating-side

Heating/cooling control provides two methods in which either none of the heating- and



cooling-side outputs Precautions in Heating/Cooling Control

• Keep the ratio of the heating-side proportional band (P) to the cooling-side proportional band (Pc) equal to or below 5. • If neither the heating side nor the cooling side is performing on-off control, setting the integral time (I or Ic) of one side to "0" results in

the Integral Time parameters of both sides being set to "OFF", irrespective of the integral time setting of the other side.

■ Cycle Time A cycle time can only be set if the type of control output is time propor-

A cycle time refers to one period consisting of on- and off-state time lengths. The ratio of the on-state time to the off-state time differs according to the value of the control output. The figure on the right shows on-to-off time ratios of the control output when the cycle time is set to 10 seconds. Setting a shorter cycle time allows the controller to perform elaborate control at short time intervals. This significantly reduces the

on- and off-state times, however it shortens the service life of a relay.

tional PID relay output or time proportional voltage pulse output.

Relay's Behavior when Cycle Time = 10 sec 10 sec 10 sec